Proposed Residential Development

Avon and Beechworth Roads, Pymble

TRAFFIC AND PARKING ASSESSMENT REPORT

10 December 2012

Ref 12454



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1. INTRODUCTION

This report has been prepared to accompany an application for a residential development proposal located in Avon Road and Beechworth Road, Pymble (Figures 1 and 2).

The subject site is currently occupied by a number of dwelling houses which are to be demolished to facilitate the proposed residential development.

Vehicular access to the proposed residential development is to be provided via two driveways to be located in Avon Road and a single driveway which is to be located in Beechworth Road. The location of the proposed driveways generally coincides with the location of the existing driveways which already provide vehicular access to the site.

The purpose of this report is to assess the traffic and parking implications of the development proposal and to that end this report:

- describes the site and provides details of the development proposal
- reviews the road network in the vicinity of the site, and the traffic conditions on that road network
- estimates the traffic generation potential of the development proposal
- assesses the traffic implications of the development proposal in terms of road network capacity
- reviews the geometric design features of the proposed basement car parking facilities for compliance with the relevant codes and standards
- assesses the adequacy and suitability of the quantum of off-street car parking provided on the site.



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2. PROPOSED DEVELOPMENT

Site

The subject site is located immediately to the south of the North Shore railway line, and has street frontages to Avon Road and to Beechworth Road.

The site is readily accessible by public transport, being located approximately 600m walking distance from Pymble Railway Station. A pedestrian underpass beneath the Pacific Highway connects Avon Road to the railway station and also provides pedestrian access to the local shops and services such as the Commonwealth Bank and the Australia Post agency.

The subject site is currently occupied by three dwelling houses, each with a separate vehicular access driveway to either Avon Road or to Beechworth Road.

Proposed Development

The proposed development envisages the construction of 4 new residential apartment buildings with basement carparking facilities. A total of 297 residential apartments are proposed as set out in the table below:

Proposed Residential Development								
	Number of Units	Resident Parking	Visitor Parking	Total Parking				
Building 1	44 units	51 spaces	4 spaces	55 spaces				
Building 3	77 units	87 spaces	8 spaces	95 spaces				
Building 4	89 units	95 spaces	9 spaces	104 spaces				
Building 5	63 units	64 spaces	6 spaces	70 spaces				
TOTAL	273 units	297 spaces	27 spaces	324 spaces				

Vehicular access to Building 1 is to be provided via a new two-way driveway located in approximately the same position as the existing driveway which currently provides access to the dwelling house located at No. 5 Avon Road.

Vehicular access to Buildings 3 and 4 is to be provided via a new driveway located in approximately the same position as the existing vehicular access driveway currently serving No. 1 Avon Road.

Vehicular access to Building 5 is to be provided via a new driveway located in approximately the same position as the existing driveway which currently provides vehicular access to No. 4 Beechworth Road.

A number of pedestrian paths within the site will connect the various buildings with Avon Road and Beechworth Road, enabling direct pedestrian access through the site from Beechworth Road to Pymble Railway Station.

Plans of the proposed development have been prepared by *Marchese* + *Partners International Pty Ltd* and are to be reproduced in the following pages.



3. TRAFFIC ASSESSMENT

Road Hierarchy

The road hierarchy allocated to the road network in the vicinity of the site by the Roads and Maritime Services is illustrated on Figure 3.

The Pacific Highway is classified by the RMS as a *State Road* and provides the key northsouth road link in the area. It typically carries three traffic lanes in each direction, with opposite traffic flows separated by a central concrete median island.

Ryde Road/Mona Vale Road is also classified by the RMS as a *State Road* and provides a road link between Mona Vale in the north to Blakehurst in the south. It typically 3 traffic lanes in each direction, with additional lanes provided at key intersections to accommodate turning movements.

Bobbin Head Road is classified by the RMS as a *Regional Road* and provides a secondary north-south road link between Pymble and Ku-ring-gai Chase National Park. It typically carries 1 traffic lane in each direction.

Avon Road and Beechworth Road are local, unclassified roads which perform the function of *collector routes*, providing access from the surrounding residential area to the classified RMS arterial road network.

Existing Traffic Controls

The existing traffic controls which apply to the road network in the vicinity of the site are illustrated on Figure 4. Key features of those traffic controls are:

- a 60 km/h SPEED LIMIT in the Pacific Highway
- a 50 km/h SPEED LIMIT on all other local roads in the surrounding area



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- TRAFFIC SIGNALS in the Pacific Highway where it intersects with Beechworth Road and with Livingstone Road
- 40 km/h SCHOOL ZONES in Avon Road adjacent to the railway line, and to the south of Arilla Road.

Existing Traffic Conditions

An indication of the existing traffic conditions on the road network in the vicinity of the site is provided by detailed peak period traffic surveys undertaken as part of this traffic study. The traffic surveys were undertaken during the morning and afternoon commuter peak periods at the following locations:

Pacific Highway/Livingstone Road Pacific Highway/Beechworth Road Pacific Highway/Bobbin Head Road Avon Road/Access to Number 1 Avon Road Avon Road/Arilla Road

The results of the peak hour traffic surveys reveal that:

- two-way traffic flows on the Pacific Highway are typically in the order of 4500 vehicles per hour (vph) during commuter peak periods
- two-way traffic flows in Livingstone Road are typically in the order of 600-900 vph during peak periods
- two-way traffic flows in Bobbin Head Road are typically in the order of 700 vph during the morning and afternoon peak periods
- traffic flows in Beechworth Road are typically in the order of 350-550 vph in peak periods
- two-way traffic flows in Avon Road are typically in the order of 350-500 vph, and

• two-way traffic flows in Arilla Road are typically in the order of 400 vph during peak periods.

Projected Traffic Generation

An indication of the traffic generation potential of the proposed development is provided by reference to the RMS publication *Guide to Traffic Generating Developments, Section 3 - Landuse Traffic Generation (October 2002).*

The RMS *Guidelines* are based on extensive surveys of a wide range of land uses and nominate the following traffic generation rates which are applicable to the development proposal:

High Density Residential Flat Buildings in Sub-Regional Centres

0.29 peak hour vehicle trips per dwelling

The RMS Guidelines also make the following observation in respect of high density residential flat buildings:

Definition

A *high density residential flat building* refers to a building containing 20 or more dwellings. This does not include aged or disabled persons housing. *High density residential flat buildings* are usually more than 5 levels, have basement level carparking and are located in close proximity to public transport services. The building may contain a component of commercial use.

Factors

The above rates include visitors, staff, service/delivery and on-street movements such as taxis and pick-up/set-down activities.

The proposed development satisfies each of the above RMS criteria for a high density residential development, particularly in respect of the site's proximity to public transport services.

Application of the above traffic generation rate to the development proposal yields a traffic generation potential of 79 vph.

However, discussions with the Department of Planning and Infrastructure have indicated that consideration should also be given to using a higher traffic generation rate of 0.4 vph/unit. That higher traffic generation rate is usually applied to high density residential developments which may *NOT* be readily accessible by public transport eg; developments which are *NOT* located within easy walking distance of a suburban railway station.

In this instance, it is considered that the subject site is readily accessible by public transport, being located an easy 600m (or less) walking distance to Pymble Railway Station, along a relatively flat route.

However, a comparison of the two traffic generation rates reveals that the *difference* between the two traffic generation rates is relatively minor, resulting in a *difference* of less than 10 vph per building, or a cumulative difference of just 30 vph as set out in the table below:

Comparison of Projected Traffic Generation Rates							
	Number of Units	Traffic Gen	Natt Diffarance				
	Number of Clifts	0.29 vph/unit	0.40 vph/unit				
Building 1	44 units	12.8 vph	17.6 vph	4.8 vph			
Building 3	77 units	22.3 vph	30.8 vph	8.5 vph			
Building 4	89 units	25.8 vph	35.6 vph	9.8 vph			
Building 5	63 units	18.3 vph	25.2 vph	6.9 vph			
TOTAL	273 units	79.2 vph	109.2 vph	30.0 vph			

Accordingly, given the relatively minor difference in outcomes between the two traffic generation rates, the higher traffic generation rate of 0.4 vph/unit has been adopted to provide a more *rigorous* traffic assessment.

Traffic Assessment – Road Network Capacity

The traffic implications of development proposals primarily concern the effects that any *additional* traffic flows generated by the development may have on the operational performance of the nearby road network. Those effects can be assessed using the SIDRA capacity analysis program as is widely used by the RMS and many LGA's for this purpose. Criteria for evaluating the results of SIDRA capacity analysis are reproduced in the following pages.

The results of the SIDRA capacity analysis are summarised in the table below, revealing that:

- the Pacific Highway/Livingstone Road intersection will continue to operate at *Level of Service "B"* under the projected additional traffic flows, with increases in total average vehicle delays of less than 2 seconds per vehicle
- the intersection of Pacific Highway/Beechworth Road North will also continue to operate at *Level of Service "B"*, with increases in total average vehicle delays in the order of 3-4 seconds per vehicle
- the intersection of Avon Road/Arilla Road will continue to operate at *Level of Service* "*A*", with no appreciable change in total average vehicle delays.

The SIDRA capacity analysis program was also used to assess the operational performance of the site access driveways which are planned to serve the site. The results of that analysis reveal that each of the proposed vehicular access driveways will operate at *Level of Service* "A" and with absolutely minimal delays at all times.

RESULTS OF SIDRA CAPACITY ANALYSIS												
EXISTING									PROP	OSED		
	A	M PEA	K	PM PEAK		AM PEAK		PM PEAK		K		
	LOS D/S AV			LOS	D/S	AVD	LOS	D/S	AVD	LOS	D/S	AVD
Pacific Hwy/Livingstone Rd	В	0.794	24.7	В	0.854	19.4	В	0.835	26.3	В	0.878	21.0
Pacific Hwy/Beechworth Rd	В	0.716	14.8	В	0.903	15.0	В	0.758	18.7	В	0.924	17.3
Pacific Hwy/Bobbin Head Rd	В	0.746	19.5	В	0.88	16.0	В	0.746	19.5	В	0.819	16.0
Avon Rd/Arilla Rd	А	0.247	4.4	Α	0.265	4.8	А	0.250	4.5	А	0.175	4.9
Avon Rd/Bldgs 3 & 4 Site Access	Α	0.148	0.6	A	0.108	0.4	А	0.161	1.3	А	0.158	1.5
Avon Rd/ Bldg 1 Site Access	-	-	-	-	-	-	А	0.151	2.5	А	0.117	0.5
Beechworth Rd/Bldg 5 Site Access	-	-	-	-	-	-	А	0.176	1.2	А	0.134	0.8

LOS – Level of Service; D/S – Degree of Saturation; AVD – Total Average Vehicle Delays (sec/veh)

In summary, the results of the capacity analysis indicate that the proposed residential development will not have any unacceptable traffic implications in terms of road network capacity, and that there will not be any road improvements or intersection upgrades required to accommodate the projected additional traffic flows.

Evaluation of the Need of a Road Link between Arilla Road and Beechworth Road

It has been suggested that consideration be given to providing a road link across the site between Beechworth Road and Avon Road to augment the local road network. The suggested road link across the site would duplicate the existing link between Avon Road and Beechworth Road via Mayfield Avenue and Arilla Road.

The provision of a through-site road link could potentially provide increased flexibility for residents of the proposed development. It could also provide an alternate route for existing local traffic currently using Mayfield Avenue/Arilla Road.

However, an analysis of the traffic flows expected to be generated by the proposed residential development suggests that:

- traffic generated by Buildings 1, 3 and 4 would primarily use Livingstone Avenue to access the Pacific Highway, and
- traffic generated by Building 5 would primarily use Beechworth Road to access the Pacific Highway.

Thus the only traffic generated by the site which would benefit from a through-site road link would be traffic approaching Building 5 from the north, or traffic departing Buildings 1, 3 and 4 with a destination towards the north. However those particular approach/departure movements are expected to generate *less than 15 vph* combined, and can be satisfactorily accommodated using the existing Mayfield Avenue/Arilla Road route when proceeding from Avon Road to Beechworth Road. An internal through-site link is therefore *NOT* required to accommodate traffic flows generated by the site.

The capacity analysis of the Avon Road/Arilla Road route also indicates that the existing local traffic flows travelling between Avon Road and Beechworth Road are satisfactorily accommodated on the existing road network. In particular, the capacity analysis indicates that the Avon Road/Arilla Road intersection operates at *Level of Service "A"* and with minimal delays under both the existing and projected future traffic volumes. The results of that capacity analysis indicate that there would be little benefit to be gained in terms of local

traffic movements if *another* road link was constructed between Avon Road and Beechworth Road across the site, as the existing local traffic movements are satisfactorily accommodated using the existing road network.

Accordingly, it is clear that there is *NO* benefit to be gained by either local traffic or development traffic through the provision of another road link between Avon Road and Beechworth Road. The provision of a through-site road link between Avon Road and Beechworth Road is therefore considered to be unnecessary.

Through-Site Pedestrian Link

Whilst a through-site road link would be of no benefit to the operation of the surrounding road network, the provision of a through-site *pedestrian link* between Avon Road and Beechworth Road is considered to be essential because:

- a through-site *pedestrian link* would significantly enhance the public transport options available to occupants to Building 5 when walking to/from Pymble Railway Station, and
- the provision of a through-site *pedestrian link* would also improve the public transport accessibility of other local residents walking to/from Pymble Railway Station, particularly residents living in the Myoora Street/Jubilee Avenue precinct who would benefit from the shorter walking distance to the railway station (compared with using the existing walking route via Arilla Road).

Accordingly, it is considered that a through-site road link is unnecessary and would be of little benefit to road users, however the provision of a trough-site *pedestrian link* is considered essential as it would significantly enhance pedestrian accessibility to/from Pymble Railway Station and the nearby local shops and services.

4. PARKING IMPLICATIONS

Existing Kerbside Parking Restrictions

The existing kerbside parking restrictions which apply to the road network in the vicinity of the site are illustrated on Figure 5. Key features of those parking restrictions are:

- CLEARWAY restrictions along both sides of the Pacific Highway during peak periods
- BUS ZONES on both sides of the Pacific Highway at regular intervals
- PARKING restrictions in Beechworth Road on the approaches to the Pacific Highway intersection
- generally UNRESTRICTED kerbside parking elsewhere on the local road network.

Off-Street Parking Provisions

The off-street parking requirements applicable to the development proposal are specified in Council's *Development Control Plan No.43 – Car Parking (1998)* document in the following terms:

High Density Residential Flat Buildings	
1 bedroom apartments:	1.0 space per dwelling
2 bedroom apartments:	1.0 space per dwelling
3 bedroom apartments:	1.5 spaces per dwelling
Visitors:	1.0 space per 4 dwellings

Application of the above parking requirements to the retail and residential components of the development proposal yields an off-street parking requirement of 364 spaces as set out below:

Proposed Development - DCP No.43 Parking Requireme						
Residential (273 Apartments):	296.0 spaces					
Residential Visitors:	68.2 spaces					
TOTAL:	364.2 spaces					



The proposed development makes provision for a total of 324 off-street car parking spaces, comprising 297 residential spaces, 27 residential visitor spaces, thereby resulting in a "shortfall" of 40 spaces when assessed under Council's *DCP No.43*.

Reference is also made to the parking rates specified in Council's former *Development Control Plan (Town Centres) 2010, Section 3A.27 – Mixed-Use Development Car Parking Provision* document as follows:

Residential Component within Mixed-Use Development

Studio:	0.0 spaces per dwelling (min)	0.5 spaces per dwelling (max)
1-Bedroom Apartments:	0.6 spaces per dwelling (min)	1.0 spaces per dwelling (max)
2-Bedroom Apartments:	1.0 spaces per dwelling (min)	1.25 spaces per dwelling (max)
3-Bedroom Apartments:	1.0 spaces per dwelling (min)	1.5 spaces per dwelling (max)
Visitors:	1.0 spaces per 6 dwellings	1.0 spaces per 6 dwellings

Application of the above parking requirements to the retail and residential components of the development proposal yields an off-street parking requirement of between 288 spaces and 373 spaces as set out below:

Proposed Development – Former	Town Centres DCP 20	10 Parking Requirements
Residential (273 Apartments):	242.2 spaces (min)	327.8 spaces (max)
Residential Visitors:	45.5 spaces (min)	45.5 spaces (max)
TOTAL	287.7 spaces (min)	373.3 spaces (max)

The proposed development makes provision for a total of 324 off-street car parking spaces, thereby satisfying the former *Town Centre DCP* parking requirements.

By way of further comparison, reference is made to the parking rates nominated in the former Roads and Traffic Authority's (now RMS) publications *Guide to Traffic Generating Developments, Section 5 – Parking Requirements for Specific Land Uses (October 2002).*

The parking rates nominated in the RMS *Guidelines* are based on extensive surveys of a wide range of land uses and nominates the following off-street parking requirements which are relevant to the development proposal.

	Bo (inter openien oue in
1 bedroom apartments:	0.6 spaces per dwelling
2 bedroom apartments:	0.9 spaces per dwelling
3 bedroom apartments:	1.4 spaces per dwelling
Visitors:	1.0 space per 5 dwellings

High Density Residential Flat Buildings (Metropolitan Sub-Regional Centres)

Application of the above parking rates to the various components of the development proposal yields an off-street parking requirement of 284 parking spaces as set out below:

Proposed Development – RMS Parking Requirements						
Residential (273 Apartments):	234.1 spaces					
Residential Visitors:	54.6 spaces					
TOTAL:	288.7 spaces					

The proposed development makes provision for a total of 324 off-street carparking spaces, thereby satisfying the requirements specified in the RMS *Guidelines*.

In summary, the foregoing assessment has found that the proposed provision of 324 off-street carparking spaces as part of the development proposal:

- results in a shortfall of 40 carparking spaces when assessed in accordance with DCP No. 43
- falls within the range of the minimum and maximum parking requirements specified by the former *Town Centres DCP 2010*, and
- satisfies the requirements specified by the RMS *Guidelines*, resulting in a surplus of approximately 35 spaces.

Accordingly, the parking provisions incorporated in the development proposal are considered to be "constrained" when assessed in accordance with the more generous requirements specified by DCP 43, and are generally in keeping with the parking requirements specified by the former *Town Centre's DCP* and the RMS *Guidelines* which more specifically address the parking needs of high density residential developments with good access to public transport services, having regard for the proximity of the site to Pymble Railway Station.

APPENDIX A

SIDRA CAPACITY ANALYSIS MOVEMENT SUMMARIES

Pacific Hwy & Livingstone Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movement Performance - Vehicles											
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate	Average Speed km/b
South: Pacific Hwy (S)											
1	L	249	0.4	0.794	44.9	LOS D	11.9	83.9	0.77	0.85	25.3
2	Т	1479	4.3	0.740	29.1	LOS C	41.2	299.2	0.84	0.77	31.9
Approac	h	1728	3.8	0.794	31.4	LOS C	41.2	299.2	0.83	0.78	30.8
North: Pa	acific H	lwy (N)									
8	Т	2674	1.8	0.667	7.6	LOS A	32.4	230.0	0.50	0.46	47.7
9	R	318	0.3	0.780	69.1	LOS E	22.7	159.2	1.00	0.88	19.3
Approac	h	2992	1.6	0.780	14.2	LOS A	32.4	230.0	0.55	0.51	41.7
West: Liv	vingsto	ne Rd (W)									
10	L	111	0.0	0.757	74.6	LOS F	15.2	106.9	1.00	0.88	17.2
12	R	284	0.4	0.757	76.0	LOS F	15.2	106.9	1.00	0.88	17.0
Approac	h	395	0.3	0.757	75.6	LOS F	15.2	106.9	1.00	0.88	17.1
All Vehic	les	5115	2.2	0.794	24.7	LOS B	41.2	299.2	0.68	0.63	33.9

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians									
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped	
P7	Across W approach	53	20.3	LOS C	0.1	0.1	0.52	0.52	
All Ped	estrians	53	20.3	LOS C			0.52	0.52	

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Livingstone Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	Movement Performance - Vehicles										
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn	Average Delay	Level of Service	95% Back of Vehicles	of Queue Distance m	Prop. Queued	Effective Stop Rate	Average Speed km/b
South: P	acific H	Hwy (S)	/0				1011			por von	
1	L	119	0.0	0.266	15.3	LOS B	2.8	19.3	0.35	0.70	41.0
2	Т	2263	1.7	0.846	17.9	LOS B	60.0	426.2	0.81	0.77	38.2
Approac	h	2382	1.6	0.846	17.8	LOS B	60.0	426.2	0.79	0.76	38.3
North: Pa	acific H	lwy (N)									
8	Т	1815	0.8	0.505	3.9	LOS A	17.1	120.8	0.31	0.29	52.8
9	R	148	0.0	0.854	89.1	LOS F	11.8	82.5	1.00	0.93	16.7
Approac	h	1963	0.8	0.854	10.3	LOS A	17.1	120.8	0.36	0.34	45.7
West: Liv	vingsto	ne Rd (W)									
10	L	92	0.0	0.849	86.7	LOS F	13.5	94.7	1.00	0.94	16.9
12	R	226	0.0	0.849	87.7	LOS F	13.5	94.7	1.00	0.95	16.8
Approac	h	318	0.0	0.849	87.4	LOS F	13.5	94.7	1.00	0.95	16.8
All Vehic	les	4663	1.2	0.854	19.4	LOS B	60.0	426.2	0.62	0.60	37.6

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians											
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped			
P7	Across W approach	53	9.4	LOS A	0.1	0.1	0.35	0.35			
All Ped	estrians	53	9.4	LOS A			0.35	0.35			

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Livingstone Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	Movement Performance - Vehicles										
Mov ID	Turn	Demand Flow veb/b	HV %	Deg. Satn	Average Delay	Level of Service	95% Back of Vehicles	of Queue Distance	Prop. Queued	Effective Stop Rate	Average Speed km/b
South: P	acific H	Hwy (S)	70	V/C	300		VCII				KIII/II
1	L	262	0.4	0.835	47.9	LOS D	12.8	89.8	0.82	0.86	24.4
2	Т	1483	4.3	0.742	29.1	LOS C	41.4	300.5	0.84	0.77	31.9
Approac	h	1745	3.7	0.835	32.0	LOS C	41.4	300.5	0.84	0.79	30.6
North: Pa	acific H	lwy (N)									
8	Т	2691	1.8	0.678	8.2	LOS A	34.0	241.3	0.52	0.48	47.1
9	R	323	0.3	0.817	72.6	LOS F	23.9	167.6	1.00	0.90	18.7
Approac	h	3014	1.6	0.817	15.1	LOS B	34.0	241.3	0.57	0.53	40.9
West: Liv	vingsto	ne Rd (W)									
10	L	111	0.0	0.828	78.8	LOS F	17.9	125.2	1.00	0.93	16.6
12	R	337	0.3	0.828	79.5	LOS F	17.9	125.2	1.00	0.94	16.6
Approac	h	448	0.2	0.828	79.4	LOS F	17.9	125.2	1.00	0.94	16.6
All Vehic	les	5207	2.2	0.835	26.3	LOS B	41.4	300.5	0.70	0.65	33.0

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians											
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped			
P7	Across W approach	53	20.3	LOS C	0.1	0.1	0.52	0.52			
All Ped	estrians	53	20.3	LOS C			0.52	0.52			

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Livingstone Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	ent Pe	erformance - V	Vehicles								
Mov ID	Turn	Demand Flow	ΗV	Deg. Satn	Average Delay	Level of Service	95% Back o Vehicles	of Queue Distance	Prop. Queued	Effective Stop Rate	Average Speed
		veh/h	%	v/c	sec		veh	m		per veh	km/h
South: P	Pacific ⊢	łwy (S)									
1	L	172	0.0	0.404	16.6	LOS B	4.4	30.8	0.38	0.72	40.0
2	Т	2280	1.7	0.878	20.6	LOS B	65.1	462.6	0.87	0.83	36.3
Approac	h	2452	1.6	0.878	20.3	LOS B	65.1	462.6	0.84	0.82	36.6
North: Pa	acific H	lwy (N)									
8	Т	1819	0.8	0.511	4.2	LOS A	17.9	126.2	0.32	0.30	52.3
9	R	165	0.0	0.833	86.0	LOS F	12.9	90.3	1.00	0.91	17.1
Approac	h	1984	0.8	0.833	11.0	LOS A	17.9	126.2	0.38	0.35	45.0
West: Liv	vingsto	ne Rd (W)									
10	L	92	0.0	0.833	84.6	LOS F	13.8	96.4	1.00	0.93	17.1
12	R	239	0.0	0.833	85.6	LOS F	13.8	96.4	1.00	0.93	17.0
Approac	h	331	0.0	0.833	85.4	LOS F	13.8	96.4	1.00	0.93	17.1
All Vehic	les	4767	1.1	0.878	21.0	LOS B	65.1	462.6	0.66	0.63	36.5

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians											
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped			
P7	Across W approach	53	10.5	LOS B	0.1	0.1	0.37	0.37			
All Ped	estrians	53	10.5	LOS B			0.37	0.37			

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Beechworth Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	ent Pe	rformance - V	ehicles								
Mov ID	Turn	Demand	HV	Deg.	Average	Level of	95% Back	of Queue	Prop.	Effective	Average
	1 di li	riuw veh/h	0/2	Salli	Delay	Service	venicies	Distance	Queueu		Speeu km/h
South: P	acific H	wv (S)	/0	V/C	360	_	Ven		_	perven	KI11/11
1	L	242	0.0	0.679	19.1	LOS B	36.0	257.8	0.59	0.95	39.7
2	т	1772	3.8	0.679	12.1	LOS A	36.2	261.6	0.60	0.55	42.9
Approac	h	2014	3.4	0.679	13.0	LOS A	36.2	261.6	0.59	0.60	42.5
North: Pa	acific Hv	wy (N)									
8	Т	2963	1.6	0.704	12.0	LOS A	39.4	279.8	0.61	0.57	43.2
Approac	h	2963	1.6	0.704	12.0	LOS A	39.4	279.8	0.61	0.57	43.2
West: Be	eechwor	th Rd (W)									
10	L	180	0.0	0.389	37.6	LOS C	11.2	78.1	0.89	0.95	27.2
12	R	149	0.7	0.716	66.8	LOS E	9.9	69.8	0.93	0.83	19.9
Approac	h	329	0.3	0.716	50.8	LOS D	11.2	78.1	0.91	0.90	23.3
All Vehic	les	5306	2.2	0.716	14.8	LOS B	39.4	279.8	0.62	0.60	40.8

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Mover	nent Performance -	Pedestrian	S					
		Demand	Average	Level of	Average Back	of Queue	Prop.	Effective
Mov ID	Description	Flow	Delay	Service	Pedestrian	Distance	Queued	Stop Rate
		ped/h	sec		ped	m		per ped
P1	Across S approach	53	62.6	LOS F	0.2	0.2	0.91	0.91
P7	Across W approach	53	7.7	LOS A	0.1	0.1	0.32	0.32
All Ped	estrians	106	35.1	LOS D			0.62	0.62

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Beechworth Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	ent Pe	rformance - V	ehicles								
MovuD	Turn	Demand	ш\/	Deg.	Average	Level of	95% Back	of Queue	Prop.	Effective	Average
	Turri	Flow	ΠV	Satn	Delay	Service	Vehicles	Distance	Queued	Stop Rate	Speed
		veh/h	%	v/c	sec		veh	m		per veh	km/h
South: P	acific H	wy (S)									
1	L	102	0.0	0.890	22.0	LOS B	68.9	488.0	0.82	0.98	38.7
2	Т	2691	1.4	0.890	15.0	LOS B	69.2	490.0	0.83	0.78	40.1
Approac	h	2793	1.4	0.890	15.2	LOS B	69.2	490.0	0.83	0.79	40.1
North: Pa	acific Hv	wy (N)									
8	Т	2001	0.7	0.571	7.9	LOS A	25.7	181.0	0.45	0.41	47.6
Approac	h	2001	0.7	0.571	7.9	LOS A	25.7	181.0	0.45	0.41	47.6
West: Be	eechwor	th Rd (W)									
10	L	154	0.0	0.417	60.9	LOS E	10.3	72.3	0.93	0.99	21.0
12	R	97	0.0	0.903	78.7	LOS F	7.0	49.0	0.92	0.90	18.0
Approac	h	251	0.0	0.903	67.8	LOS E	10.3	72.3	0.93	0.96	19.7
All Vehic	les	5045	1.0	0.903	15.0	LOS B	69.2	490.0	0.68	0.65	40.5

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Mover	nent Performance -	Pedestrian	S					
		Demand	Average	Level of	Average Back	of Queue	Prop.	Effective
Mov ID	Description	Flow	Delay	Service	Pedestrian	Distance	Queued	Stop Rate
		ped/h	sec		ped	m		per ped
P1	Across S approach	53	66.3	LOS F	0.2	0.2	0.94	0.94
P7	Across W approach	53	6.5	LOS A	0.1	0.1	0.29	0.29
All Ped	estrians	106	36.4	LOS D			0.62	0.62

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Beechworth Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	ent Pe	rformance - V	ehicles								
MoviD	Turn	Demand	Ц\/	Deg.	Average	Level of	95% Back	of Queue	Prop.	Effective	Average
	Turri	Flow	ΠV	Satn	Delay	Service	Vehicles	Distance	Queued	Stop Rate	Speed
		veh/h	%	v/c	sec		veh	m		per veh	km/h
South: P	acific H	wy (S)									
1	L	246	0.0	0.724	22.8	LOS B	41.8	299.8	0.68	0.94	37.2
2	Т	1772	3.8	0.724	16.3	LOS B	42.1	304.2	0.68	0.64	39.4
Approac	h	2018	3.4	0.724	17.1	LOS B	42.1	304.2	0.68	0.67	39.1
North: Pa	acific Hv	wy (N)									
8	Т	2968	1.6	0.746	15.9	LOS B	45.4	322.3	0.70	0.66	39.9
Approac	h	2968	1.6	0.746	15.9	LOS B	45.4	322.3	0.70	0.66	39.9
West: Be	eechwor	th Rd (W)									
10	L	197	0.0	0.373	40.8	LOS C	11.7	81.6	0.86	0.96	26.1
12	R	166	0.6	0.758	63.8	LOS E	10.9	76.3	0.89	0.85	20.5
Approac	h	363	0.3	0.758	51.3	LOS D	11.7	81.6	0.87	0.91	23.2
All Vehic	les	5349	2.2	0.758	18.7	LOS B	45.4	322.3	0.71	0.68	37.8

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Mover	nent Performance -	Pedestrian	S					
		Demand	Average	Level of	Average Back	of Queue	Prop.	Effective
Mov ID	Description	Flow	Delay	Service	Pedestrian	Distance	Queued	Stop Rate
		ped/h	sec		ped	m		per ped
P1	Across S approach	53	57.2	LOS E	0.2	0.2	0.87	0.87
P7	Across W approach	53	9.7	LOS A	0.1	0.1	0.36	0.36
All Ped	estrians	106	33.5	LOS D			0.62	0.62

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Beechworth Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	ent Per	formance - V	/ehicles								
May ID	Turn	Demand		Deg.	Average	Level of	95% Back	of Queue	Prop.	Effective	Average
	Turri	Flow	ΠV	Satn	Delay	Service	Vehicles	Distance	Queued	Stop Rate	Speed
		veh/h	%	v/c	sec		veh	m		per veh	km/h
South: P	acific H	wy (S)									
1	L	119	0.0	0.914	25.8	LOS B	76.8	543.5	0.88	0.98	36.3
2	Т	2691	1.4	0.914	18.5	LOS B	76.9	544.8	0.88	0.84	37.5
Approac	h	2810	1.4	0.914	18.8	LOS B	76.9	544.8	0.88	0.85	37.5
North: Pa	acific Hv	vy (N)									
8	Т	2018	0.7	0.586	8.9	LOS A	27.5	193.7	0.47	0.44	46.5
Approac	h	2018	0.7	0.586	8.9	LOS A	27.5	193.7	0.47	0.44	46.5
West: Be	eechwor	th Rd (W)									
10	L	159	0.0	0.411	63.3	LOS E	10.6	74.3	0.92	0.99	20.6
12	R	101	0.0	0.924	74.1	LOS F	7.0	49.0	0.91	0.85	18.7
Approac	h	260	0.0	0.924	67.5	LOS E	10.6	74.3	0.92	0.94	19.8
All Vehic	les	5088	1.0	0.924	17.3	LOS B	76.9	544.8	0.72	0.69	38.7

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians												
		Demand	Average	Level of	Average Back	of Queue	Prop.	Effective				
Mov ID	Description	Flow	Delay	Service	Pedestrian	Distance	Queued	Stop Rate				
		ped/h	sec		ped	m		per ped				
P1	Across S approach	53	64.4	LOS F	0.2	0.2	0.93	0.93				
P7	Across W approach	53	7.1	LOS A	0.1	0.1	0.31	0.31				
All Ped	estrians	106	35.7	LOS D			0.62	0.62				

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Bobbin Head Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movement Performance - Vehicles											
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay se <u>c</u>	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/ <u>h</u>
South: P	acific H	lwy (S)									
2	Т	1805	3.7	0.578	4.8	LOS A	22.0	158.7	0.37	0.35	51.3
3	R	147	0.7	0.746	81.0	LOS F	11.0	77.5	1.00	0.86	17.4
Approac	h	1952	3.5	0.746	10.6	LOS A	22.0	158.7	0.42	0.39	45.2
East: Bo	bbin He	ead Rd (E)									
4	L	211	1.4	0.465	57.4	LOS E	13.1	92.9	0.90	0.81	19.9
6	R	268	0.4	0.723	80.0	LOS F	10.0	70.2	1.00	0.86	16.5
Approac	h	479	0.8	0.723	70.1	LOS E	13.1	92.9	0.96	0.84	17.8
North: Pa	acific H	wy (N)									
7	L	111	3.6	0.736	24.6	LOS B	43.6	310.3	0.70	0.99	36.1
8	Т	2752	1.6	0.736	16.9	LOS B	44.2	313.7	0.71	0.66	39.1
Approac	h	2863	1.7	0.736	17.2	LOS B	44.2	313.7	0.71	0.68	39.0
All Vehic	les	5294	2.3	0.746	19.5	LOS B	44.2	313.7	0.62	0.58	36.9

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians											
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped			
P3	Across E approach	53	11.6	LOS B	0.1	0.1	0.39	0.39			
All Pede	estrians	53	11.6	LOS B			0.39	0.39			

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Bobbin Head Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movement Performance - Vehicles											
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back of Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h
South: P	acific H	lwy (S)									
2	Т	2676	1.4	0.818	6.0	LOS A	47.5	336.1	0.55	0.52	49.2
3	R	169	0.6	0.806	83.2	LOS F	13.0	91.2	1.00	0.89	17.6
Approac	h	2845	1.3	0.818	10.6	LOS A	47.5	336.1	0.57	0.55	44.7
East: Bo	bbin He	ead Rd (E)									
4	L	168	0.0	0.399	60.2	LOS E	10.4	73.1	0.90	0.81	21.2
6	R	204	0.0	0.749	85.9	LOS F	7.8	54.8	1.00	0.86	17.0
Approac	h	372	0.0	0.749	74.3	LOS F	10.4	73.1	0.95	0.84	18.6
North: Pa	acific H	wy (N)									
7	L	177	0.0	0.631	13.5	LOS A	5.7	40.1	0.39	0.83	43.2
8	Т	1833	0.8	0.633	12.7	LOS A	33.2	233.9	0.58	0.54	42.6
Approac	h	2010	0.7	0.633	12.8	LOS A	33.2	233.9	0.56	0.56	42.7
All Vehic	les	5227	1.0	0.818	16.0	LOS B	47.5	336.1	0.60	0.57	40.0

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians												
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped				
P3	Across E approach	53	10.5	LOS B	0.1	0.1	0.37	0.37				
All Pede	estrians	53	10.5	LOS B			0.37	0.37				

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Bobbin Head Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movement Performance - Vehicles											
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back of Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h
South: P	acific H	lwy (S)									
2	Т	1822	3.7	0.583	4.9	LOS A	22.4	161.5	0.38	0.35	51.3
3	R	147	0.7	0.746	81.0	LOS F	11.0	77.5	1.00	0.86	17.4
Approac	h	1969	3.5	0.746	10.6	LOS A	22.4	161.5	0.42	0.39	45.2
East: Bo	bbin He	ead Rd (E)									
4	L	211	1.4	0.465	57.4	LOS E	13.1	92.9	0.90	0.81	19.9
6	R	268	0.4	0.723	80.0	LOS F	10.0	70.2	1.00	0.86	16.5
Approac	h	479	0.8	0.723	70.1	LOS E	13.1	92.9	0.96	0.84	17.8
North: Pa	acific H	wy (N)									
7	L	111	3.6	0.737	24.6	LOS B	43.8	311.4	0.71	0.99	36.0
8	Т	2757	1.6	0.737	16.9	LOS B	44.4	314.8	0.71	0.66	39.0
Approac	h	2868	1.7	0.737	17.2	LOS B	44.4	314.8	0.71	0.68	38.9
All Vehic	les	5316	2.3	0.746	19.5	LOS B	44.4	314.8	0.62	0.58	36.9

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians												
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped				
P3	Across E approach	53	11.6	LOS B	0.1	0.1	0.39	0.39				
All Pede	estrians	53	11.6	LOS B			0.39	0.39				

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Pacific Hwy & Bobbin Head Rd, Pymble

Signals - Fixed Time Cycle Time = 150 seconds (User-Given Cycle Time)

Movem	Movement Performance - Vehicles											
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h	
South: P	acific H	lwy (S)										
2	Т	2681	1.4	0.819	6.0	LOS A	47.7	338.2	0.55	0.53	49.2	
3	R	169	0.6	0.806	83.2	LOS F	13.0	91.2	1.00	0.89	17.6	
Approac	h	2850	1.3	0.819	10.6	LOS A	47.7	338.2	0.58	0.55	44.6	
East: Bo	bbin He	ead Rd (E)										
4	L	168	0.0	0.399	60.2	LOS E	10.4	73.1	0.90	0.81	21.2	
6	R	204	0.0	0.749	85.9	LOS F	7.8	54.8	1.00	0.86	17.0	
Approac	h	372	0.0	0.749	74.3	LOS F	10.4	73.1	0.95	0.84	18.6	
North: Pa	acific H	wy (N)										
7	L	177	0.0	0.637	13.6	LOS A	5.8	40.9	0.39	0.84	43.1	
8	Т	1850	0.8	0.638	12.8	LOS A	33.7	237.5	0.58	0.54	42.6	
Approac	h	2027	0.7	0.638	12.8	LOS A	33.7	237.5	0.57	0.57	42.6	
All Vehic	les	5249	1.0	0.819	16.0	LOS B	47.7	338.2	0.60	0.58	40.0	

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Movement Performance - Pedestrians												
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped				
P3	Across E approach	53	10.5	LOS B	0.1	0.1	0.37	0.37				
All Pede	estrians	53	10.5	LOS B			0.37	0.37				

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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Avon Rd & Arilla Rd, Pymble Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles											
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back (Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h	
East: Av	on Rd ((E)										
5	Т	87	0.0	0.190	0.5	LOS A	1.0	6.9	0.24	0.00	38.0	
6	R	190	0.5	0.190	5.4	LOS A	1.0	6.9	0.24	0.60	35.9	
Approac	h	277	0.4	0.190	3.9	NA	1.0	6.9	0.24	0.41	36.6	
North: A	rilla Rd	(N)										
7	L	152	0.0	0.247	6.2	LOS A	1.1	7.4	0.24	0.51	35.6	
9	R	57	0.0	0.247	6.6	LOS A	1.1	7.4	0.24	0.69	35.3	
Approac	h	209	0.0	0.247	6.3	LOS A	1.1	7.4	0.24	0.56	35.5	
West: Av	von Rd	(W)										
10	L	48	0.0	0.054	4.5	LOS A	0.0	0.0	0.00	0.60	36.7	
11	Т	55	0.0	0.054	0.0	LOS A	0.0	0.0	0.00	0.00	40.0	
Approac	h	103	0.0	0.054	2.1	NA	0.0	0.0	0.00	0.28	38.4	
All Vehic	les	589	0.2	0.247	4.4	NA	1.1	7.4	0.20	0.44	36.5	

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Arilla Rd, Pymble Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles												
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h		
East: Av	on Rd ((E)											
5	Т	72	0.0	0.169	0.7	LOS A	0.8	5.9	0.30	0.00	45.6		
6	R	163	0.0	0.169	7.5	LOS A	0.8	5.9	0.30	0.69	42.3		
Approac	h	235	0.0	0.169	5.4	NA	0.8	5.9	0.30	0.48	43.3		
North: A	rilla Rd	(N)											
7	L	46	0.0	0.079	8.1	LOS A	0.3	2.0	0.29	0.58	41.8		
9	R	18	0.0	0.079	8.4	LOS A	0.3	2.0	0.29	0.73	41.6		
Approac	h	64	0.0	0.079	8.2	LOS A	0.3	2.0	0.29	0.62	41.8		
West: Av	von Rd	(W)											
10	L	64	0.0	0.084	6.4	LOS A	0.0	0.0	0.00	0.76	43.3		
11	Т	96	0.0	0.084	0.0	LOS A	0.0	0.0	0.00	0.00	50.0		
Approac	h	160	0.0	0.084	2.6	NA	0.0	0.0	0.00	0.31	47.1		
All Vehic	cles	459	0.0	0.169	4.8	NA	0.8	5.9	0.19	0.44	44.3		

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Arilla Rd, Pymble Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h			
East: Av	on Rd ((E)												
5	Т	87	0.0	0.201	0.5	LOS A	1.0	7.3	0.24	0.00	38.0			
6	R	204	0.5	0.201	5.4	LOS A	1.0	7.3	0.24	0.60	35.9			
Approac	:h	291	0.3	0.201	3.9	NA	1.0	7.3	0.24	0.42	36.5			
North: A	rilla Rd	(N)												
7	L	152	0.0	0.250	6.3	LOS A	1.1	7.4	0.24	0.51	35.5			
9	R	57	0.0	0.250	6.7	LOS A	1.1	7.4	0.24	0.69	35.3			
Approac	h	209	0.0	0.250	6.4	LOS A	1.1	7.4	0.24	0.56	35.4			
West: Av	von Rd	(W)												
10	L	48	0.0	0.054	4.5	LOS A	0.0	0.0	0.00	0.60	36.7			
11	Т	55	0.0	0.054	0.0	LOS A	0.0	0.0	0.00	0.00	40.0			
Approac	h	103	0.0	0.054	2.1	NA	0.0	0.0	0.00	0.28	38.4			
All Vehic	cles	603	0.2	0.250	4.5	NA	1.1	7.4	0.20	0.44	36.4			

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Arilla Rd, Pymble Giveway / Yield (Two-Way)

Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back of Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h		
East: Av	on Rd ((E)											
5	Т	72	0.0	0.175	0.7	LOS A	0.9	6.2	0.30	0.00	45.6		
6	R	171	0.0	0.175	7.5	LOS A	0.9	6.2	0.30	0.68	42.3		
Approac	h	243	0.0	0.175	5.5	NA	0.9	6.2	0.30	0.48	43.2		
North: A	rilla Rd	(N)											
7	L	46	0.0	0.079	8.1	LOS A	0.3	2.1	0.29	0.58	41.8		
9	R	18	0.0	0.079	8.4	LOS A	0.3	2.1	0.29	0.73	41.6		
Approac	h	64	0.0	0.079	8.2	LOS A	0.3	2.1	0.29	0.62	41.7		
West: Av	von Rd	(W)											
10	L	64	0.0	0.084	6.4	LOS A	0.0	0.0	0.00	0.76	43.3		
11	Т	96	0.0	0.084	0.0	LOS A	0.0	0.0	0.00	0.00	50.0		
Approac	h	160	0.0	0.084	2.6	NA	0.0	0.0	0.00	0.31	47.1		
All Vehic	cles	467	0.0	0.175	4.9	NA	0.9	6.2	0.20	0.44	44.2		

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

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Avon Rd & Proposed Northern Access Driveway Giveway / Yield (Two-Way)

Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h		
East: Ave	on Rd	(E)											
5	Т	285	0.7	0.148	0.9	LOS A	1.0	7.4	0.38	0.00	37.4		
6	R	1	0.0	0.148	5.9	LOS A	1.0	7.4	0.38	0.76	36.1		
Approac	h	286	0.7	0.148	1.0	NA	1.0	7.4	0.38	0.00	37.4		
North: Ad	ccess I	Rd (N)											
7	L	1	0.0	0.003	7.9	LOS A	0.0	0.1	0.43	0.49	34.5		
9	R	1	0.0	0.003	8.3	LOS A	0.0	0.1	0.43	0.64	34.3		
Approac	h	2	0.0	0.003	8.1	LOS A	0.0	0.1	0.43	0.56	34.4		
West: Av	on Rd	(W)											
10	L	1	0.0	0.105	4.5	LOS A	0.0	0.0	0.00	0.70	36.7		
11	Т	204	0.0	0.105	0.0	LOS A	0.0	0.0	0.00	0.00	40.0		
Approac	h	205	0.0	0.105	0.0	NA	0.0	0.0	0.00	0.00	40.0		
All Vehic	les	493	0.4	0.148	0.6	NA	1.0	7.4	0.22	0.01	38.4		

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Proposed Northern Access Driveway Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h			
East: Ave	on Rd	(E)												
5	Т	209	0.0	0.108	0.6	LOS A	0.7	4.9	0.30	0.00	46.4			
6	R	1	0.0	0.108	7.4	LOS A	0.7	4.9	0.30	0.89	43.0			
Approac	h	210	0.0	0.108	0.7	NA	0.7	4.9	0.30	0.00	46.3			
North: Ad	ccess	Rd (N)												
7	L	1	0.0	0.003	8.6	LOS A	0.0	0.1	0.34	0.53	41.4			
9	R	1	0.0	0.003	8.9	LOS A	0.0	0.1	0.34	0.65	41.2			
Approac	h	2	0.0	0.003	8.7	LOS A	0.0	0.1	0.34	0.59	41.3			
West: Av	/on Rd	(W)												
10	L	1	0.0	0.076	6.4	LOS A	0.0	0.0	0.00	0.92	43.3			
11	Т	147	0.0	0.076	0.0	LOS A	0.0	0.0	0.00	0.00	50.0			
Approac	h	148	0.0	0.076	0.0	NA	0.0	0.0	0.00	0.01	49.9			
All Vehic	les	360	0.0	0.108	0.4	NA	0.7	4.9	0.18	0.01	47.7			

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

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Avon Rd & Proposed Northern Access Driveway Giveway / Yield (Two-Way)

Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h		
East: Av	on Rd	(E)											
5	Т	290	0.7	0.161	1.0	LOS A	1.1	8.0	0.39	0.00	37.3		
6	R	13	0.0	0.161	6.0	LOS A	1.1	8.0	0.39	0.75	36.1		
Approac	h	303	0.7	0.161	1.2	NA	1.1	8.0	0.39	0.03	37.2		
North: A	ccess I	Rd (N)											
7	L	42	0.0	0.070	6.7	LOS A	0.3	1.8	0.37	0.56	35.2		
9	R	10	0.0	0.070	7.2	LOS A	0.3	1.8	0.37	0.74	35.0		
Approac	h	52	0.0	0.070	6.8	LOS A	0.3	1.8	0.37	0.59	35.2		
West: Av	on Rd	(W)											
10	L	1	0.0	0.111	4.5	LOS A	0.0	0.0	0.00	0.70	36.7		
11	Т	215	0.0	0.111	0.0	LOS A	0.0	0.0	0.00	0.00	40.0		
Approac	h	216	0.0	0.111	0.0	NA	0.0	0.0	0.00	0.00	40.0		
All Vehic	les	571	0.4	0.161	1.3	NA	1.1	8.0	0.24	0.07	38.0		

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Proposed Northern Access Driveway Giveway / Yield (Two-Way)

Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h		
East: Av	on Rd	(E)											
5	Т	226	0.0	0.158	0.7	LOS A	1.0	6.9	0.31	0.00	46.1		
6	R	52	0.0	0.158	7.4	LOS A	1.0	6.9	0.31	0.82	42.8		
Approac	h	278	0.0	0.158	1.9	NA	1.0	6.9	0.31	0.15	45.4		
North: A	ccess I	Rd (N)											
7	L	10	0.0	0.016	8.1	LOS A	0.1	0.4	0.30	0.57	41.8		
9	R	3	0.0	0.016	8.4	LOS A	0.1	0.4	0.30	0.71	41.6		
Approac	h	13	0.0	0.016	8.2	LOS A	0.1	0.4	0.30	0.60	41.8		
West: Av	on Rd	(W)											
10	L	1	0.0	0.077	6.4	LOS A	0.0	0.0	0.00	0.92	43.3		
11	Т	150	0.0	0.077	0.0	LOS A	0.0	0.0	0.00	0.00	50.0		
Approac	h	151	0.0	0.077	0.0	NA	0.0	0.0	0.00	0.01	49.9		
All Vehic	les	442	0.0	0.158	1.5	NA	1.0	6.9	0.20	0.12	46.8		

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Proposed Southen Access Driveway Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h			
East: Av	on Rd	(E)												
5	Т	291	0.0	0.151	4.1	LOS A	2.5	17.8	0.71	0.00	35.4			
6	R	1	100.0	0.151	11.0	LOS A	2.5	17.8	0.71	0.84	34.7			
Approac	h	292	0.3	0.151	4.1	NA	2.5	17.8	0.71	0.00	35.4			
North: A	ccess	Rd (N)												
7	L	11	0.0	0.019	6.6	LOS A	0.1	0.5	0.36	0.53	35.3			
9	R	3	0.0	0.019	7.0	LOS A	0.1	0.5	0.36	0.69	35.1			
Approac	h	14	0.0	0.019	6.7	LOS A	0.1	0.5	0.36	0.56	35.3			
West: Av	/on Rd	(W)												
10	L	1	0.0	0.106	4.5	LOS A	0.0	0.0	0.00	0.70	36.7			
11	Т	205	0.0	0.106	0.0	LOS A	0.0	0.0	0.00	0.00	40.0			
Approac	h	206	0.0	0.106	0.0	NA	0.0	0.0	0.00	0.00	40.0			
All Vehic	les	512	0.2	0.151	2.5	NA	2.5	17.8	0.41	0.02	37.1			

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Avon Rd & Proposed Southen Access Driveway Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h			
East: Av	on Rd	(E)												
5	Т	227	0.0	0.117	0.6	LOS A	0.8	5.4	0.30	0.00	46.4			
6	R	1	0.0	0.117	7.4	LOS A	0.8	5.4	0.30	0.89	43.0			
Approac	h	228	0.0	0.117	0.6	NA	0.8	5.4	0.30	0.00	46.3			
North: A	ccess l	Rd (N)												
7	L	3	0.0	0.005	7.9	LOS A	0.0	0.1	0.29	0.55	42.0			
9	R	1	0.0	0.005	8.2	LOS A	0.0	0.1	0.29	0.67	41.8			
Approac	h	4	0.0	0.005	8.0	LOS A	0.0	0.1	0.29	0.58	41.9			
West: Av	/on Rd	(W)												
10	L	1	0.0	0.075	6.4	LOS A	0.0	0.0	0.00	0.92	43.3			
11	Т	145	0.0	0.075	0.0	LOS A	0.0	0.0	0.00	0.00	50.0			
Approac	h	146	0.0	0.075	0.0	NA	0.0	0.0	0.00	0.01	49.9			
All Vehic	les	378	0.0	0.117	0.5	NA	0.8	5.4	0.19	0.01	47.6			

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Beechworth Rd & Proposed Site Access Giveway / Yield (Two-Way)

Movem	Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h			
South: B	leechwo	orth Rd (S)												
2	Т	342	0.0	0.176	1.2	LOS A	1.3	9.4	0.43	0.00	37.0			
3	R	1	0.0	0.176	6.1	LOS A	1.3	9.4	0.43	0.77	36.1			
Approac	h	343	0.0	0.176	1.2	NA	1.3	9.4	0.43	0.00	37.0			
East: Pro	oposed	Site Access Dr	iveway (E))										
4	L	1	0.0	0.063	12.6	LOS A	0.2	1.5	0.62	0.59	31.8			
6	R	21	0.0	0.063	13.0	LOS A	0.2	1.5	0.62	0.83	31.7			
Approac	h	22	0.0	0.063	13.0	LOS A	0.2	1.5	0.62	0.82	31.7			
North: B	eechwo	orth Rd (N)												
7	L	4	0.0	0.126	4.5	LOS A	0.0	0.0	0.00	0.70	36.7			
8	Т	242	0.0	0.126	0.0	LOS A	0.0	0.0	0.00	0.00	40.0			
Approac	h	246	0.0	0.126	0.1	NA	0.0	0.0	0.00	0.01	39.9			
All Vehic	les	611	0.0	0.176	1.2	NA	1.3	9.4	0.27	0.04	37.9			

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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Beechworth Rd & Proposed Site Access Giveway / Yield (Two-Way)

Movement Performance - Vehicles													
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h		
South: B	seechwo	orth Rd (S)											
2	Т	255	0.0	0.134	0.5	LOS A	0.9	6.1	0.27	0.00	46.7		
3	R	4	0.0	0.134	6.6	LOS A	0.9	6.1	0.27	0.96	43.0		
Approac	h	259	0.0	0.134	0.6	NA	0.9	6.1	0.27	0.01	46.6		
East: Pro	oposed	Site Access Dr	iveway (E))									
4	L	1	0.0	0.011	8.7	LOS A	0.0	0.3	0.41	0.48	34.8		
6	R	5	0.0	0.011	9.1	LOS A	0.0	0.3	0.41	0.65	34.7		
Approac	h	6	0.0	0.011	9.0	LOS A	0.0	0.3	0.41	0.62	34.7		
North: B	eechwo	orth Rd (N)											
7	L	17	0.0	0.061	5.6	LOS A	0.0	0.0	0.00	0.88	43.2		
8	Т	102	0.0	0.061	0.0	LOS A	0.0	0.0	0.00	0.00	50.0		
Approac	h	119	0.0	0.061	0.8	NA	0.0	0.0	0.00	0.13	48.9		
All Vehic	les	384	0.0	0.134	0.8	NA	0.9	6.1	0.19	0.06	47.1		

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Minor Road Approach LOS values are based on average delay for all vehicle movements.

NA: Intersection LOS and Major Road Approach LOS values are Not Applicable for two-way sign control since the average delay is not a good LOS measure due to zero delays associated with major road movements.

SIDRA Standard Delay Model used.

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