Shepherds Bay Urban Renewal Development Stages 2 and 3

Traffic Impact Assessment Section 96 Application

Prepared for



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ABSTRACT

Road Delay Solutions Pty Ltd has been engaged by Holdmark Prperty Group to undertake investigation and provide supporting information into the traffic implications associated with the proposed Shepherds Bay Residential Development, Stages 2 and 3 and the Section 96 Application for the deletion of Community Facility and addition of apartments.

The Section 96 Application specifically proposes...

- Reduction of the largely unusable stepped terraces within the internal courtyards of each building. These have been replaced by a largely 'at grade' landscaping zone which reduces the amount of hard landscaping and increases the soft landscaping areas,
- → Amendments to the stepped terraces between Stage 2 and Stage 3 buildings. The current scheme proposed two separate lifts to enable people to traverse from Nancarrow Avenue to Rothesay Avenue. The second lift stopped approximately 4m above the landscaped paving toward Rothesay Avenue and then people traversed a series of ramps and/or stairs to access the lower part of the site. The proposal has one lift that takes people from Nancarrow Avenue to the Upper Basement level. The large curved stairs at Upper Basement and the series of steps between the multiple levels have been deleted. This improves accessibility throughout the site.
- → The proposed Café, which is currently at Lower Ground level or over 4m above Rothesay Avenue, has been relocated to the Upper Basement level, which allows far greater connectivity incorporating the adjusted landscape areas at this level.
- People now have the advantage of being able to access the internal courtyards of both buildings at the Upper Basement levels via generous links through both Stage 2 and Stage 3 buildings. This enables connectivity between the buildings that was not previously available.
- The current DA has three storeys of very large unusable space against the cliff. These spaces have been activated by adjusting the carparking areas and apartments as shown. This activates the unusable space by using it as car parking, a potential gym one storey below Nancarrow Avenue and Services spaces.
- → Removal of unnecessary walling needed to cope with the varying terrace levels both between the two buildings and within their respective internal courtyards.
- \rightarrow The number of water features have been reduced and refined.
- → 28 apartments have been added over and above the 17 included as part of the deed of agreement.

This assessment specifically focuses on the traffic impacts associated with the proposed urban renewal of the Meadowbank Precinct and the committed infrastructure projects associated with the Department of Planning & Infrastructure Concept Approval, MP09_0216.

Stages 2 and 3 of the development will provide for 498 residential apartments and is anticipated to generate some 144 vehicle trips per commuter peak travel period. The Section 96 Application is proposed to include...

- \rightarrow 498 residential apartments,
- \rightarrow 640 car parking spaces,
- \rightarrow 64 allocated bicycle spaces at 1 space per 10 car spaces,
- \rightarrow Pedestrian and bicycle pathways,
- \rightarrow Publically accessible open space,
- \rightarrow Provision for emergency and service vehicles, and
- → Infrastructure improvements to sustain the anticpated level of motor vehicle generation.

The internal vehicle machinations, parking and service provisions for the proposed Stages 2 and 3 is dealt with in a separate report prepared by Thompson Stanbury Associates.

LOCATION

Located within the precinct known as the Meadowbank Employment Area (MEA) the proposed Holdmark development, Shepherds Bay, is generally bounded by Bowden Street to the west, Constitution Road to the north and Belmore Street to the east, and the Parramatta River to the south.



Figure 1Shepherds Bay Development FootprintSourceRobertson + Marks Architects, Revision L, 2014

THE DEVELOPMENT

The full development involves the construction of 1,988, high end, residential apartment dwellings on the shore of the Parramatta River, Shepherds Bay, west of the Ryde Bridge.

Stage 1, involving the construction of 246 residential apartments, is located at the corner of Belmore Street and Rothesay Avenue, replacing the former industrial activities.

Stages 2 and 3 of the development, located to the immediate west of Stage 1, proposes the construction of a further 498 residential apartments, consisting of...

- \rightarrow 4 studio apartments,
- \rightarrow 253 single bedroom apartments,
- \rightarrow 12 loft apartmets,
- \rightarrow 212 two bedroom apartments, and
- \rightarrow 17 three bedroom apartments.

Vehicular access to the Stages 2 and 3 buildings is proposed to be facilitated via a single access driveway connecting with Rothesay Avenue in the south-eastern corner of the site. The driveway is proposed to provide a 6m wide ingress laneway, separated from a 6m wide egress lane by a 1m wide median. The driveway will permit access to 640, basement level, parking spaces.

EXISTING CONDITIONS

Road Network

Church Street is classified as a *State Road* under the auspices of the *RMS* and provides the key north-south transport corridor in the area. It typically comprises six (6) traffic lanes (ie. 3 lanes in each direction), with opposing traffic flows separated by a central concrete median island.

Victoria Road is also classified as a *State Road* under the auspices of the *RMS* providing a pivotal east-west transport link on the Sydney Metropolitan road network.

Typically comprising six (6) trafficable lanes, with opposing traffic flows separated by a central concrete median island.

Junction Street, Belmore Street and Constitution Road form part of a *collector road* system which permit traffic to enter and leave the Meadowbank Precinct.

Generally consisting of a single trafficable lane in each direction, and with kerbside parking permitted at select locations only, the collector road network affords both local and cross regional traffic the ability to by pass congestion on the arterial road network.





Existing Traffic Controls

The existing key traffic controls on the surrounding road network, in the vicinity of the Shepherds Bay development site, are...

- → A 70 km/h speed limit on Church Street
- \rightarrow A 60 km/h speed limit in Victoria Road,
- \rightarrow A 50 km/h speed limit on all other local roads in the area,
- → Traffic signals on Church Street at its intersection with both Junction Street and Morrison Road,
- → Traffic signals in Belmore Street at its intersection with both Constitution Road and Junction Street,
- → Central median islands in Church Street and in Victoria Road ptecluding right turn movements, with the exception of those permitted at key traffic signal controlled intersections,
- ightarrow A roundabout in Constitution Road at its intersection with Bowden Street, and
- Roundabouts in Porter Street at its intersection with both Parsonage Street and Well Street.

Traffic Counts

Road Delay Solutions has commissioned *ROAR Data* to annually count key intersections within the *MEA*, in particular the intersections of Constitution Road with both Bowden Sreet and Belmore Street. These counts have been collected in or around November of each year from 2011 to 2014, inclusive.

The 2014 counts, along with the projected traffic volumes for the respective stages of development, are presented in *Appendix* A.

From the counts, the annual growth rates on each road corridor have been calculated and utilised in the operational computer based modelling of the select infrastructure upgrades associated with the planning approval.

From the collated traffic data, the annual growth in traffic has been determined by Road corridors. Understandably a negative growth rate is currently reported through the precinct given...

- \rightarrow The transformation of local land uses,
- \rightarrow The vacation of local business prior to the development construction, and
- → The impedance of construction vehicles for the Shepherds Bay and surrounding developments.

A positive growth rate is anticipated with the occupancy of Stage 1, onwards.

While the Bureau of Transport Statistics (BTS) currently lists vehicle growth on the Metropolitan Arterial Road Network as some 1.2%, for the purpose of this assessment, an average 1% growth rate has been applied, annually, to the current traffic figures to assimilate any possible growth in cross regional traffic flow.

On top of the 1% growth rate applied, each annual stage of development has been added to the future traffic projections to enable assessment of a 'worst case' situation.

| | Vehicles | Vehicles per Hour (All vehicle types) | | | | | | |
|--------------------------------|----------|---------------------------------------|------|------|-------------------|--|--|--|
| Road Corridor | 2011 | 2012 | 2013 | 2014 | Average Growth | | | |
| AM Constitution Road Eastbound | 686 | 692 | 628 | 621 | -3.2% | | | |
| AM Constitution Road Westbound | 488 | 452 | 441 | 435 | -3.7% | | | |
| AM Bowden Road Northbound | 420 | 438 | 363 | 371 | -3.5% | | | |
| AM Bowden Street Southbound | 377 | 369 | 254 | 266 | -9.5% | | | |
| AM Belmore Street Northbound | 322 | 337 | 304 | 300 | -2.1% | | | |
| AM Belmore Street Southbound | 146 | 152 | 138 | 133 | -2.9% | | | |
| AM Railway Parade Northbound | 766 | 770 | 632 | 621 | -6.4% | | | |
| AM Railway Parade Southbound | 323 | 437 | 352 | 355 | 5.6% | | | |

| Average Annual Growth Rate | | | | | -29.0% |
|--------------------------------|-----|-----|-----|-----|--------|
| PM Railway Parade Southbound | 815 | 849 | 906 | 919 | 4.1% |
| PM Railway Parade Northbound | 302 | 344 | 375 | 372 | 7.4% |
| PM Belmore Street Southbound | 228 | 223 | 246 | 152 | -10.0% |
| PM Belmore Street Northbound | 322 | 346 | 331 | 284 | -3.7% |
| PM Bowden Street Southbound | 374 | 389 | 510 | 540 | 13.7% |
| PM Bowden Road Northbound | 413 | 384 | 255 | 189 | -22.2% |
| PM Constitution Road Westbound | 619 | 768 | 667 | 580 | -0.7% |
| PM Constitution Road Eastbound | 429 | 340 | 417 | 513 | 8.3% |

Current Road Network Growth Rates Table 1

Source

Road Delay Solutions, 2014

FUTURE CONDITIONS

Vehicle Generation

Based upon the *RMS Technical Direction TDT 2013/04a* high density residential apartment developments, the traffic generation for the Stages 2 and 3 has adopted a generation rate of 0.29 vehicles per hour (vph) per apartment, for both the morning and evening commuter peak periods, respectively. This generation rate is considered conservative and will aid in determining the appropriate triggers and warrants for infrastructure during construction of the development.

Travel patterns from the development have been drawn from the BTS data set published in 2011, and have been exported into *Road Delay Solutions'* Netanal strategic model for the purpose of utilising select link analysis to determine the projected movement of development generated traffic within the precinct.

| Vehicle Generation Period | R۸ | RMS Vehicle Generation Rate | | | | | | |
|--|-------------------|-----------------------------|---------------------|-------------------|--|--|--|--|
| | Sydney Average | Sydney Range | Regional Average | Regional Range | | | | |
| AM peak (1 hour) vehicle trips per unit | 0.19 | 0.07-0.32 | 0.53 | 0.39-0.67 | | | | |
| AM peak (1 hour) vehicle trips per car space | 0.15 | 0.09-0.29 | 0.35 | 0.32-0.37 | | | | |
| AM peak (1 hour) vehicle trips per bedroom | 0.09 | 0.03-0.13 | 0.21 | 0.20-0.22 | | | | |
| PM peak (1 hour) vehicle trips per unit | 0.15 | 0.06-0.41 | 0.32 | 0.22-0.42 | | | | |
| PM peak (1hour) vehicle trips per car space | 0.12 | 0.05-0.28 | 0.26 | 0.11-0.40 | | | | |
| PM peak (1 hour) vehicle trips per bedroom | 0.07 | 0.03-0.17 | 0.15 | 0.07-0.22 | | | | |
| Daily vehicle trips per unit | 1.52 | 0.77-3.14 | 4.58 | 4.37-4.78 | | | | |
| Daily vehicle trips per car space | 1.34 | 0.56-2.16 | 3.22 | 2.26-4.18 | | | | |
| Daily vehicle trips per bedroom | 0.72 | 0.35-1.29 | 1.93 | 1.59-2.26 | | | | |

Table 2Source

RMS Vehicle Generation Rates

Extract from RMS Technical Direction, 2013

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| | | Vehicle Generation | | | | | | | |
|-----------------------|---------------------|--------------------|-------------------------------|--------------------------------|------------------------|--|--|--|--|
| Construction Stage | No of Apartments | Adopted Rate | Vehicles per Hour (vph) | AM Outbound <i>(80%)</i> | AM Inbound (20%) | | | | |
| 1 | 246 | 0.29 | 71 | 57 | 14 | | | | |
| 2 and 3 | 498* | 0.29 | 144 | 116 | 29 | | | | |
| 4 and 5 | 511 | 0.29 | 148 | 119 | 30 | | | | |
| 6 and 7 | 311 | 0.29 | 90 | 72 | 18 | | | | |
| 8 and 9 | 422 | 0.29 | 122 | 98 | 24 | | | | |
| Totals | 1988 | | 577 | 461 | 115 | | | | |

* 28 apartments have been added over and above the 17 included as part of the deed of agreement.

| Table 3 | Development Vehicle Generation by Stage |
|---------|---|
| Source | Holdmark, 2015 |

Meadowbank Precinct JTW Mode Share



Figure 3 Meadowbank Precinct JTW Mode Choice

Source

ABS Census data – 'Suburban Community Profile'- Meadowbank, 2011



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The current predominant available transport mode choices for JTW have been catalogued from those available within, or adjacent to, the *MEA*, and as defined within the *BTS* 2006 transport zone number 2522.

The latest Household Travel Survey (HTS) data shows that average weekday trips grew by 1.0% between 2009/10 and 2010/11, which was slower than the 1.6% rate of population growth in the Sydney Statistical Division (SSD).

The private motor vehicle remains the dominant mode of transport embraced by the wider Sydney community. The ever increasing use of the private motor vehicle for both journey to work trips and recreational activities, places significant pressure on the road network infrastructure, the environment, health and local amenity, with road authorities compelled to sustain a perceived and expected satisfactory level of service.

In line with NSW 2021 targets, growth in public transport trips has been higher than growth in private vehicle passenger trips. Vehicle driver trips have increased by 1.5%, while train and bus trips increased by 2.6% and 2.3%, respectively. These inherent increases can be attributed to increased traffic congestion on the arterial road system, greater frequency of public transport services and improved intermodal/interchange provisions.



Figure 5Projected Sydney Metropolitan Peak Hour Travel DemandSourceRoad Delay Solutions, Netanal Model 2012

Infrastructure Requirements

During the planning and approval stage, the form and level of infrastructure required, to sustain the urban renewal development, was diligently assessed.

Holdmark has expressed it's commitment to constructing the following infrastructure during the staged construction of the development, in accordance with the Department of Planning and Infrastructure Approval MP09_0216.

The prescribed infrastructure upgrades include...

- → The extension of Nancarrow Avenue between Hamilton Crescent and Belmore Street,
- → The provision of left in/left out at the intersection of Belmore Street and Hamilton Crescent,
- → The provision of left in/left out at the intersection of Belmore Street and Yerong Street,
- \rightarrow Underdale Lane Local Area Traffic Management (LATM) measures,
- → Installation of a pedestrian refuge on Bowden Street near Nancarrow Avenue,
- → Installation of roundabout in Belmore Street at Rothesay Avenue,
- \rightarrow The provision of left in/left out at the intersection of Belmore Street and Yerong Street,
- $\rightarrow\,$ Installation of traffic signals at the intersection of Constitution Road and Bowden Street, and
- → Installation of traffic signal installation on Railway Road at the current pedestrian crossing near Meadowbank railway station.

Traffic Impacts

Investigations into the traffic impacts associated with the development vehicle generation has been undertaken using the computer based program, SIDRA.

In particular, the intersections of Constitution Road with Belmore Street and also Bowden Street, have been closely scrutinised.

Constitution Road and Bowden Street

It is understood that the intersection was itemised by Council, under the 2005 works program and again identified by Urban Horizon in July of 2010, to be reconstructed and operate under the control of traffic signals.

The single lane circulating roundabout controlled intersection was modelled extensively under both pre and post development conditions during the 'Concept Stage', at which time an operational Level of Service (LoS) 'A' was reported for both AM and PM peak commuter periods.



Figure 6 Source

Constitution Road and Bowden Street Operational Performance Road Delay Solutions, Netanal Model 2014

MOVEMENT SUMMARY

Site: Existing AM 2014 Constitution Rd & Bowden St Roundabout

| Mov CD IO Mov | | Demand Flow | | Deg | Average | Leveni ori- | 95% Black of | Queve | E Ping. III | Effective | Juncage. |
|------------------|-------------------|-----------------|-----|--------------------|-------------------------|-------------|------------------|---------|-------------|-----------------------|--------------------------|
| 0 | Mor | Tintel websh | 12 | Deg. Sata wt | Average Deley sec | Senika | Vehicles with | Catance | Queund | Stop Rate per with | Average Speed kent |
| SouthEns | Constitution Rd (| | | | 10.5 | ACC MUS | 2-22 | | a constant. | | |
| 21 | 1.2 | 33 | 7.8 | 0.399 | 5.4 | LOS A | 2.9 | 29.7 | 0.53 | 0.60 | 45.0 |
| 22 | Tt | 266 | 1.0 | 0.399 | 5.1 | LOS A | 2.9 | 20.7 | 0.53 | 0.60 | 45.8 |
| 23 | R2 | 136 | 0.6 | 0.399 | 8.1 | LOS A | 2.9 | 20.7 | 0.53 | 0.60 | 45.6 |
| Approach | | 435 | 1.4 | 0.399 | 6.1 | LOS A | 29 | 20.7 | 0.53 | 0.60 | 45.7 |
| NorthEast | Bowden St (NE) | | | | | | | | | | |
| 24 | L2 | 78 | 0.0 | 0.358 | 7.8 | LOS A | 2.4 | 17.0 | 0.76 | 0.82 | 43.9 |
| 25 | Tt | 69 | 4.3 | 0.358 | 7.8 | LOS A | 2.4 | 17.0 | D.76 | 0.62 | 44.5 |
| 26 | 82 | 119 | 3.5 | 0.358 | 10.8 | LOS B | 2.4 | 17.0 | 0.76 | 0.87 | 44.3 |
| Approach | | 266 | 2.7 | 0.358 | 9.2 | LOS A | 2.4 | 17.0 | 0.76 | 0.82 | 44.3 |
| NorthWest | Constitution Rd | NNS | | | | | | | | | |
| 27 | L2 | 142 | 2.5 | 0.615 | 7.7 | LOS A | 5.6 | 41.0 | 0.74 | 0.76 | 44.7 |
| 28 | Tt | 462 | 0.6 | 0.815 | 7.4 | LOS A | 5.8 | 41.0 | D.74 | 0.76 | 45.4 |
| 29 | R2 | 11 | 0.0 | 0.615 | 10.4 | LOS B | 5.8 | 41.0 | 0.74 | 0.76 | 45.2 |
| Approach | | 615 | 8.0 | 0.615 | 7.5 | LOS A | 5.8 | 41.0 | D.74 | 0.76 | 45.2 |
| SouthWee | t Bowden St (SW | | | | | | | | | | |
| 30 | L2 | 6 | 0.0 | 0.234 | 7.2 | LOS A | 1.4 | 10.0 | 0.66 | 0.75 | 44.2 |
| 31 | TT | 93 | 3.7 | 0.234 | 7.2 | LOS A | 1.4 | 10.0 | 0.66 | 0.75 | 44.8 |
| 32 | R2 | 87 | 3.6 | 0.234 | 10.2 | LOS B | 1.4 | 10.0 | 0.66 | 0.75 | 44.6 |
| Approach | | 196 | 3.5 | 0.234 | 5.6 | LOS A | 1.4 | 10.0 | 0.66 | 0.75 | 44.7 |
| All Vehicle | 5 | 1602 | 57 | 0.615 | 7.5 | LOS A | 5.0 | 41.0 | 0.67 | 0.72 | 45.1 |

MOVEMENT SUMMARY

V Site: Existing PM 2014

Constitution Rd & Bowden St Roundabout

| Moverne | ant Performance | Vehicles | | | | | | | | | |
|-------------|--|----------|----------------|--------------------|------------------|---|-------------------------|----------|------------------|------------------------|-------------------------|
| Mov 10 | OD Mav | Tussi | nd Flues HV | Deg Sats v/t | Avenuen Detay | Level of Service | 95% Back of Vehicles | Distance | Prop. Guarant | Effective Stop Role | Average Speed Mon |
| Could be an | Constitution Rd | unhiti | | - vit- | 100 | 100 A. M. | | 11 | | per web | 1924 |
| 21 | L2 | 27 | 0.0 | 0.689 | 8.2 | LOSA | 8.0 | 58.4 | 0.91 | 0.99 | 42.8 |
| 22 | T1 | 498 | 0.9 | 0.689 | 11.1 | LOS B | 80 | 56.4 | 0.91 | 0.99 | 43.4 |
| 23 | 82 | 55 | 1.4 | 0.689 | 14.1 | LOS B | 8.0 | 56.4 | 0.91 | 0.99 | 43.2 |
| Approach | 12,000 | 580 | 0.9 | 0.689 | 11.2 | LOS B | 6.0 | 56.4 | 0.91 | 0.99 | 43.4 |
| NorthEas | Bowden St (NE) | | | | | | | | | | |
| 24 | L2 | 76 | 0.0 | 0.583 | 8.1 | LOSA | 5.2 | 38.5 | 0.76 | 0.83 | 43.4 |
| 25 | T1 | 94 | 1.2 | 0.583 | 8.0 | LOS A | 5.2 | 36.5 | 0.76 | 0.83 | -#4.0 |
| 26 | R2 | 370 | 0.4 | 0.583 | 11.0 | LOS B | 5.2 | 36.5 | 0.76 | 0.63 | 43.9 |
| Approach | | 540 | 0.5 | 0.583 | 10.1 | LOS B | 5.2 | . 36.5 | 0.76 | 0.83 | 43.8 |
| NorthWei | at: Constitution Rd (| NW) | | | | | | | | | |
| 27 | 1.2 | 59 | 2.7 | 0.336 | 5.4 | LOS A | 2.3 | 16.1 | 0.52 | 0.57 | 45.5 |
| 28 | T1 | 297 | 0.4 | 0.536 | 5.1 | LOSA | 23 | 16.1 | 0.52 | 0.57 | 46.2 |
| 29 | R2 | 1 | 12.5 | 0.336 | 8.4 | LOSA | 2.3 | 16.1 | D.52 | 0.57 | 45.8 |
| Approach | 0 | 367 | 0.8 | 0.336 | 5.2 | LOSA | 2.3 | 16.1 | 5.52 | 0.57 | 48.1 |
| SouthWe | st Bowden St (SW) | ý - | | | | | | | | | |
| 30 | L2 | 24 | 0.0 | 0.365 | 12.1 | LOS B | 2.6 | 17.9 | 0.91 | 0.96 | 41.8 |
| 31 | Tt | 75 | 1.0 | 0.365 | 12.0 | LOS B | 2.6 | 17.9 | 0.91 | 0.96 | 42.4 |
| 32 | 82 | 86 | 0.0 | 0.365 | 14.9 | LOS B | 2.6 | 17.5 | 0.91 | 0.96 | 42.2 |
| Approach | 1. | 185 | 0.4 | 0.365 | 13,4 | LOS B | 2.6 | 17.9 | 0.91 | 0.96 | 42.2 |
| All Vehicl | ** | 1662 | 0.7 | 0.689 | 9.8 | LOSA | 6.0 | 56.4 | 0.75 | 0.84 | 43.9 |

Table 4Source

2014 Constitution Road/Bowden Street Movement Summaries

Road Delay Solutions, 2015

MOVEMENT SUMMARY

𝒜 Site: Stage 2 and 3 AM

Constitution Rd & Bowden St Roundabout

| movemen | it Performa | ance - Vehicles | | | | | | | | | |
|--------------|----------------|-------------------------|--------------------|---------------------|-------------------------|---------------------|--------------------------------|------------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Deman Total veh/h | d Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Vehicles veh | Queue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| SouthEast: | Constitution | | | | | | | | | | |
| 21 | L2 | 33 | 7.8 | 0.398 | 5.4 | LOS A | 2.9 | 20.8 | 0.53 | 0.60 | 45.0 |
| 22 | T1 | 269 | 1.0 | 0.398 | 5.1 | LOS A | 2.9 | 20.8 | 0.53 | 0.60 | 45.8 |
| 23 | R2 | 137 | 0.6 | 0.398 | 8.1 | LOS A | 2.9 | 20.8 | 0.53 | 0.60 | 45.6 |
| Approach | | 439 | 1.4 | 0.398 | 6.0 | LOS A | 2.9 | 20.8 | 0.53 | 0.60 | 45.7 |
| NorthEast: | Bowden St | (NE) | | | | | | | | | |
| 24 | L2 | 78 | 0.0 | 0.356 | 8.0 | LOS A | 2.4 | 17.0 | 0.77 | 0.83 | 43.8 |
| 25 | T1 | 69 | 4.3 | 0.356 | 8.0 | LOS A | 2.4 | 17.0 | 0.77 | 0.83 | 44.4 |
| 26 | R2 | 112 | 3.5 | 0.356 | 11.0 | LOS B | 2.4 | 17.0 | 0.77 | 0.83 | 44.2 |
| Approach | | 259 | 2.7 | 0.356 | 9.3 | LOS A | 2.4 | 17.0 | 0.77 | 0.83 | 44.2 |
| NorthWest: | : Constitution | n Rd (NW) | | | | | | | | | |
| 27 | L2 | 143 | 2.5 | 0.633 | 8.0 | LOS A | 6.2 | 44.1 | 0.76 | 0.78 | 44.5 |
| 28 | T1 | 478 | 0.6 | 0.633 | 7.7 | LOS A | 6.2 | 44.1 | 0.76 | 0.78 | 45.2 |
| 29 | R2 | 11 | 0.0 | 0.633 | 10.7 | LOS B | 6.2 | 44.1 | 0.76 | 0.78 | 45.0 |
| Approach | | 632 | 1.0 | 0.633 | 7.8 | LOS A | 6.2 | 44.1 | 0.76 | 0.78 | 45.1 |
| SouthWest | : Bowden St | t (SW) | | | | | | | | | |
| 30 | L2 | 6 | 0.0 | 0.236 | 7.2 | LOS A | 1.4 | 10.1 | 0.66 | 0.75 | 44.2 |
| 31 | T1 | 94 | 3.7 | 0.236 | 7.2 | LOS A | 1.4 | 10.1 | 0.66 | 0.75 | 44.8 |
| 32 | R2 | 88 | 3.6 | 0.236 | 10.2 | LOS B | 1.4 | 10.1 | 0.66 | 0.75 | 44.6 |
| Approach | | 188 | 3.5 | 0.236 | 8.6 | LOS A | 1.4 | 10.1 | 0.66 | 0.75 | 44.7 |
| All Vehicles | 5 | 1518 | 1.7 | 0.633 | 7.7 | LOS A | 6.2 | 44.1 | 0.68 | 0.73 | 45.0 |

MOVEMENT SUMMARY

Site: Stage 2 and 3 PM Constitution Rd & Bowden St Roundabout

| Mov | OD | | nd Flows | Deg. | Average | Level of | 95% Back of | | Prop. | Effective | Average |
|-------------|--------------------|----------------|----------|-------------|---------|----------|-----------------|----------|--------|-----------|---------|
| ID | Mov | Total veh/h | H∨ % | Satn v/c | Delay | Service | Vehicles veh | Distance | Queued | Stop Rate | Speed |
| SouthEas | st: Constitution f | | 70 | V/C | sec | | ven | m | | per veh | km/l |
| 21 | L2 | 27 | 0.0 | 0.706 | 8.7 | LOS A | 8.5 | 60.1 | 0.94 | 1.02 | 42.6 |
| 22 | Τ1 | 503 | 0.9 | 0.706 | 11.6 | LOS B | 8.5 | 60.1 | 0.94 | 1.02 | 43.2 |
| 23 | R2 | 56 | 1.4 | 0.706 | 14.6 | LOS B | 8.5 | 60.1 | 0.94 | 1.02 | 43.0 |
| Approach | ı | 586 | 0.9 | 0.706 | 11.7 | LOS B | 8.5 | 60.1 | 0.94 | 1.02 | 43.1 |
| NorthEast | t: Bowden St (N | IE) | | | | | | | | | |
| 24 | L2 | 93 | 0.0 | 0.635 | 9.6 | LOS A | 6.4 | 44.9 | 0.82 | 0.91 | 42.1 |
| 25 | T1 | 95 | 1.2 | 0.635 | 9.5 | LOS A | 6.4 | 44.9 | 0.82 | 0.91 | 43.3 |
| 26 | R2 | 374 | 0.4 | 0.635 | 12.5 | LOS B | 6.4 | 44.9 | 0.82 | 0.91 | 43.1 |
| Approach | 1 | 562 | 0.5 | 0.635 | 11.5 | LOS B | 6.4 | 44.9 | 0.82 | 0.91 | 43. |
| NorthWes | st: Constitution I | Rd (NW) | | | | | | | | | |
| 27 | L2 | 60 | 2.7 | 0.376 | 5.4 | LOS A | 2.7 | 18.8 | 0.54 | 0.58 | 45.4 |
| 28 | T1 | 341 | 0.4 | 0.376 | 5.2 | LOS A | 2.7 | 18.8 | 0.54 | 0.58 | 46. |
| 29 | R2 | 1 | 12.5 | 0.376 | 8.5 | LOS A | 2.7 | 18.8 | 0.54 | 0.58 | 45.1 |
| Approach | 1 | 402 | 0.8 | 0.376 | 5.3 | LOS A | 2.7 | 18.8 | 0.54 | 0.58 | 46.0 |
| SouthWe: | st: Bowden St (| SW) | | | | | | | | | |
| 30 | L2 | 24 | 0.0 | 0.376 | 12.5 | LOS B | 2.7 | 18.8 | 0.92 | 0.97 | 41.0 |
| 31 | T1 | 76 | 1.0 | 0.376 | 12.4 | LOS B | 2.7 | 18.8 | 0.92 | 0.97 | 42.3 |
| 32 | R2 | 87 | 0.0 | 0.376 | 15.3 | LOS B | 2.7 | 18.8 | 0.92 | 0.97 | 42. |
| Approach | 1 | 187 | 0.4 | 0.376 | 13.8 | LOS B | 2.7 | 18.8 | 0.92 | 0.97 | 42. |
| All Vehicle | es | 1737 | 0.7 | 0.706 | 10.4 | LOS B | 8.5 | 60.1 | 0.81 | 0.88 | 43. |

Table 5 Source Stages 2 and 3 Constitution Road/Bowden Street Movement Summaries Road Delay Solutions, 2015 The RMS warrant, which the authority is adhereing to stringently for signalisation of the site, requires Constitution Road to realise 900vph in each direction for four (4) one (1) hour periods of a single day.

With the addition of the Stages 1 through 3 vehicle generations, the intersection of Constitution Road and Bowden Street operates satisfactorily under roundabout control and fails to satisfy the warrant for the installation of traffic signals, prior to the release of an Occupancy Certificate for Stage 3.

Constitution Road and Belmore Street

The intersection of Constitution Road with Belmore Street currently operates at a satisfactory LoS during both the morning and evening peak commuter periods.

With the advent of Stages 2 and 3, no adverse impact on operation is reported by the SIDRA modelling. However, the intersection will require the introduction of a 'No Stopping' restriction, in the northbound aaproach of Belmore Street to increase the capacity and operation of the signals. The 'No Stopping' zone should extend from Rothesay Avenue to Constitution Road. This measure will also eliminate the potential conflict between left turn vehicles leaving Hamilton Crescent onto Belmore Street.

Modelling during the 'Concept Stage' also identified the Belmore Street and Constitution Road as a 'rat run' utilised by cross regional traffic. Two northbound lanes in Belmore Street between Rothesay Avenue and Constitution Road was identified as critical in ensuring sufficient mid block and queueing capacities for growth along the corridor. \$96 Traffic Impact Assessment



Source

Constitution Road and Belmore Street Operational Performance Road Delay Solutions, Netanal Model 2014

MOVEMENT SUMMARY

Site: Existing AM 2014

Belmore St & Constitution Rd

Signals - Fixed Time Isolated Cycle Time = 120 seconds (Optimum Cycle Time - Minimum Delay)

| Move | ment Perf | formance - V | /ehicles | | | | | | | | |
|-----------|-------------|--------------------------|------------------|---------------------|-------------------------|---------------------|-----------------------------|---------------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Demand Total veh/h | Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back Vehicles veh | of Queue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| NorthE | ast: Belmo | | | | | | | | | | |
| 25 | T1 | 27 | 0.0 | 0.042 | 28.6 | LOS C | 1.0 | 7.3 | 0.70 | 0.52 | 36.0 |
| 26 | R2 | 106 | 1.6 | 0.385 | 55.1 | LOS E | 5.7 | 40.6 | 0.95 | 0.78 | 28.3 |
| Approa | ach | 133 | 1.3 | 0.385 | 49.8 | LOS D | 5.7 | 40.6 | 0.90 | 0.73 | 29.6 |
| NorthV | Vest: Const | titution Rd (NV | V) | | | | | | | | |
| 27 | L2 | 216 | 1.5 | 0.154 | 8.5 | LOS A | 3.3 | 23.1 | 0.28 | 0.62 | 44.4 |
| 29 | R2 | 405 | 0.7 | 0.387 | 19.8 | LOS B | 12.9 | 91.1 | 0.60 | 0.74 | 39.0 |
| Approa | ach | 621 | 1.0 | 0.387 | 15.9 | LOS B | 12.9 | 91.1 | 0.49 | 0.70 | 40.7 |
| SouthV | Vest: Belm | ore St (SW) | | | | | | | | | |
| 30 | L2 | 388 | 0.1 | 0.287 | 9.6 | LOS A | 7.1 | 49.5 | 0.34 | 0.65 | 43.8 |
| 31 | T1 | 84 | 0.0 | 0.323 | 51.8 | LOS D | 4.5 | 31.8 | 0.95 | 0.74 | 29.3 |
| Approa | ich | 472 | 0.1 | 0.323 | 17.1 | LOS B | 7.1 | 49.5 | 0.45 | 0.67 | 40.3 |
| All Veh | icles | 1226 | 0.7 | 0.387 | 20.0 | LOS C | 12.9 | 91.1 | 0.52 | 0.69 | 39.0 |

MOVEMENT SUMMARY

Site: Existing PM 2014

Belmore St & Constitution Rd

Signals - Fixed Time Isolated Cycle Time = 120 seconds (Optimum Cycle Time - Minimum Delay)

| Move | ment Per | formance - V | ehicles | | | | | | | | |
|-----------|-------------|----------------------------|------------------|---------------------|-------------------------|---------------------|-----------------------------|---------------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Demand I Total veh/h | Flows H∨ % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back Vehicles veh | of Queue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| NorthE | East: Belmo | ore St (NE) | | | | | | | | | |
| 25 | T1 | 35 | 0.0 | 0.058 | 31.0 | LOS C | 1.4 | 9.9 | 0.73 | 0.55 | 35.1 |
| 26 | R2 | 117 | 2.4 | 0.513 | 59.1 | LOS E | 6.6 | 47.2 | 0.98 | 0.79 | 27.5 |
| Approa | ach | 152 | 1.8 | 0.513 | 52.6 | LOS D | 6.6 | 47.2 | 0.92 | 0.73 | 28.9 |
| NorthV | Vest: Cons | titution Rd (NV | V) | | | | | | | | |
| 27 | L2 | 232 | 0.5 | 0.164 | 8.5 | LOS A | 3.5 | 24.8 | 0.29 | 0.62 | 44.4 |
| 29 | R2 | 281 | 0.0 | 0.256 | 17.0 | LOS B | 7.8 | 54.3 | 0.51 | 0.70 | 40.2 |
| Approa | ach | 513 | 0.2 | 0.256 | 13.1 | LOS B | 7.8 | 54.3 | 0.41 | 0.67 | 42.0 |
| South\ | Nest: Belm | nore St (SW) | | | | | | | | | |
| 30 | L2 | 674 | 0.2 | 0.514 | 9.7 | LOS A | 13.9 | 97.4 | 0.39 | 0.68 | 43.8 |
| 31 | T1 | 52 | 0.0 | 0.200 | 50.7 | LOS D | 2.8 | 19.3 | 0.93 | 0.70 | 29.5 |
| Approa | ach | 726 | 0.2 | 0.514 | 12.6 | LOS B | 13.9 | 97.4 | 0.43 | 0.68 | 42.3 |
| All Veh | nicles | 1391 | 0.4 | 0.514 | 17.2 | LOS B | 13.9 | 97.4 | 0.48 | 0.68 | 40.2 |

Table 6 Source **2014 Constitution Road/Belmore Street Movement Summaries** Road Delay Solutions, 2015

INTERSECTION SUMMARY

Site: Stage 2 and 3 AM

Belmore St & Constitution Rd

Signals - Fixed Time Isolated Cycle Time = 120 seconds (Optimum Cycle Time - Minimum Delay)

| Performance Measure | Vehicles | Pedestrians | Persons |
|--|--|---|--|
| Travel Speed (Average) Travel Distance (Total) Travel Time (Total) | 38.0 km/h 1440 4 veh-km/h 37.9 veh-h/h | 2.2 km/h 0.2 ped-km/h 0.1 ped-h/h | 38.0 km/h 1728.6 pers-km/h 45.5 pers-h/h |
| Demand Flows (Total) Percent Heavy Vehicles (Demand) Degree of Saturation Practical Spare Capacity Effective Intersection Capacity | 1418 veh/h 1.0 % 0.437 105.9 % 3245 veh/h | 5 ped/h 0.001 | 1702 pers/h |
| Control Delay (Total) Control Delay (Average) Control Delay (Worst Lane) Control Delay (Worst Movement) Geometric Delay (Average) Stop-Line Delay (Average) Idling Time (Average) Intersection Level of Service (LOS) | 8.80 veh-h/h 22.3 sec 57.5 sec 57.5 sec 3.9 sec 18.5 sec 16.1 sec LOS C | 0.04 ped-h/h 30.3 sec 45.9 sec LOS D | 10.60 pers-h/h 22.4 sec 57.5 sec |
| 95% Back of Queue - Vehicles (Worst Lane) 95% Back of Queue - Distance (Worst Lane) Queue Storage Ratio (Worst Lane) Total Effective Stops Effective Stop Rate Proportion Queued Performance Index | 14.7 veh 103.7 m 0.37 996 veh/h 0.70 per veh 0.57 96.2 | 3 ped/h 0.70 per ped 0.70 0.1 | 1199 pers/h 0.70 per pers 0.57 96.3 |
| Cost (Total) Fuel Consumption (Total) Carbon Dioxide (Total) Hydrocarbons (Total) Carbon Monoxide (Total) NOx (Total) | 823.15 S/h 142.3 L/h 335.4 kg/h 0.027 kg/h 0.286 kg/h 0.255 kg/h | 1.53 \$/h | 824.67 \$/h |

Level of Service (LOS) Method: Delay (HCM 2000).

Intersection LOS value for Vehicles is based on average delay for all vehicle movements.

Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

| Performance Measure | Véhicles | Pedestrians | Persons |
|--|---|---|--|
| Demand Flows (Total) Delay Effective Stops Travel Distance Travel Time | 680,640 veh/y 4,224 veh-h/y 478,138 veh/y 691,376 veh-km/y 18,171 veh-h/y | 2,400 ped/y 20 ped-h/y 1,668 ped/y 84 ped-km/y 38 ped-h/y | 816,768 pers/y 5,089 pers-h/y 575,434 pers/y 829,735 pers-km/y 21,844 pers-h/y |
| Cost Fuel Consumption Carbon Dioxide Hydrocarbons Carbon Monoxide NOx | 395,110 \$/y 68,316 L/y 160,970 kg/y 13 kg/y 137 kg/y 122 kg/y | 734 \$/y | 395,844 \$/y |

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Table 7 Source

AM Stages 2 and 3 Constitution Road/Belmore Street Movement Summaries Road Delay Solutions, 2015

INTERSECTION SUMMARY

Site: Stage 2 and 3 PM

Belmore St & Constitution Rd

Signals - Fixed Time Isolated Cycle Time = 120 seconds (Optimum Cycle Time - Minimum Delay)

| Performance Measure | Vehicles | Pedestrians | Persons |
|---|---|---|--|
| Fravel Speed (Average) Fravel Distance (Total) Fravel Time (Total) | 39.8 km/h 1479.9 veh-km/h 37.2 veh-h/h | 2.2 km/h 0.2 ped-km/h 0.1 ped-h/h | 39.8 km/h 1776.1 pers-km/h 44.7 pers-h/h |
| Demand Flows (Total) Percent Heavy Vehicles (Demand) Degree of Saturation Practical Spare Capacity Iffective Intersection Capacity | 1457 veh/h 0.4 % 0.492 83.1 % 2964 veh/h | 5 ped/h 0.003 | 1748 pers/h |
| Control Delay (Total) Control Delay (Average) Control Delay (Worst Lane) | 7.30 veh-h/h 18.0 sec 57.9 sec | 0.04 ped-h/h 30.7 sec | 8.80 pers-h/h 18.1 sec |
| Control Delay (Worst Movement) Seometric Delay (Average) Stop-Line Delay (Average) dling Time (Average) ntersection Level of Service (LOS) | 57.9 sec 4.1 sec 13.9 sec 11.9 sec LOS B | 54.2 sec LOS D | 57.9 sec |
| 5% Back of Queue - Vehicles (Worst Lane) 15% Back of Queue - Distance (Worst Lane) Queue Storage Ratio (Worst Lane) total Effective Stops Effective Stop Rate Proportion Queued Performance Index | 14.6 veh 102.0 m 0.63 995 veh/h 0.68 per veh 0.50 84.0 | 3 ped/h 0.68 per ped 0.68 0.1 | 1197 pers/h 0.68 per pers 0.50 84.1 |
| Cost (Total) uel Consumption (Total) Carbon Dioxide (Total) Iydrocarbons (Total) Jarbon Monoxide (Total) IOx (Total) | 807.13 S/h 147.0 L/h 345.7 kg/h 0.029 kg/h 0.304 kg/h 0.172 kg/h | 1.54 S/h | 808.67 S/h |

Level of Service (LOS) Method: Delay (HCM 2000).

Intersection LOS value for Vehicles is based on average delay for all vehicle movements.

Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

| Performance Measure | Vehicles | Pedestrians | Persons |
|--|---|---|--|
| Demand Flows (Total) Delay Effective Stops Travel Distance Travel Time | 699,360 veh/y 3,505 veh-h/y 477,571 veh/y 710,372 veh-km/y 17,840 veh-h/y | 2,400 ped/y 20 ped-h/y 1,632 ped/y 84 ped-km/y 38 ped-h/y | 839,232 pers/y 4,226 pers-h/y 574,718 pers/y 852,531 pers-km/y 21,447 pers-h/y |
| Cost Fuel Consumption Carbon Dioxide Hydrocarbons Carbon Monoxide NOx | 387,425 \$/y 70,538 L/y 165,935 kg/y 14 kg/y 146 kg/y 82 kg/y | 739 S/y | 388.164 \$/y |

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Table 8 Source

PM Stages 2 and 3 Constitution Road/Belmore Street Movement Summaries Road Delay Solutions, 2015

Nancarrow Avenue Extension to Belmore Street

Concept approval conditioned the timing pertaining to the construction of the Nancarrow Avenue extension to Belmore Street prior to the issue of the Occupation Certificate for Stage 4.

No access will be possible to or from Belmore Street during or following completion of Stages 2 and 3. Therefore, construction of the extension should parallel with the construction of Stage 4.

Accordingly, no works are required under this stage of development.

Hamilton Crescent Left In/Left Out at Belmore Street

The Belmore Street access at Hamilton Crescent is dependant upon the construction of the Nancarrow Avenue extension and will be required prior to the issue of the Occupation Certificate for Stage 4.

Accordingly, no works are required under this stage of development.

Constitution Road and Hamilton Crescent

Access to the intersection will be facilitated with the occupancy of Stage 4 onwards and construction of the Nancarrow Road extension to Belmore Street.

It is proposed to install the necessary signposting to prevent right turns from Constitution Road into Hamilton Crescent and likewise from Hamilton Crescent into Constitution Road. In conjunction with the right turn ban from Constitution Road a central median, of sufficient length, should be installed to provide a physical barrier and enforce the restriction.

The works should be undertaken prior to the issue of the Occupancy Certificate for Stage 4.

Accordingly, no action is required under this stage of development.

Belmore Street and Rothesay Avenue Roundabout

Vehicular access for Stages 2 and 3 is proposed via Rothesay Avenue.

Given the projected vehicle generation of 144vph under this Section 96 Application with full occupation of these particular stages, it is considered the roundabout at the intersection of Belmore Street and Rothesay Avenue will need to be constructed prior to the issue of the Occupation Certificate for Stage 2.

Underdale Lane and Bowden Street

Once the Nancarrow Avenue upgrade and extension are complete, the Nancarrow Avenue and Underdale Lane corridor will become an essential link between the development and the Meadowbank Railway Station.

To reduce the conflict between motor vehicles and pedestrian/cyclist activities, measures are to be set in place to deter the lane's use by motor vehicles and highlight the high pedestrian activity. To this end it is proposed to...

- → Install three (3) raised thresholds in Underdale Lane immediately west of Bowden Street, immediately east of Angus Street and immediately east of Railway Road,
- → Install an alternate road surface coulouring and/or texture, in consultation with Council,
- \rightarrow Install signposting denoting high pedestrian and bicycle activity, and
- → Design and construction of a pedestrian refuge in Bowden Street, between Nancarrow Avenue and Underdale Lane, taking care to avoid driveways, utility services and roadside vegetation.

Until the Nancarrow Avenue upgrade is complete, access will be restricted to pedestrians by the construction activities associated with Stages 4 and 5.

It is considered the Underdale LATM upgrades and Belmore Street pedestrian refuge construction should be completed prior to the issue of the Occupation Certificate for Stage 4. Accordingly, no works are proposed during Stages 2 and 3.

Belmore Street and Yerong Street Left in/Left out

Conditioned in the concept approval is the design and installation of a triangular splitter island in Yerong Street at the intersection with Belmore Street.

With the occupancy of stages 1 through 3, the installation will be necessary to effectively manage traffic movements to and from Yerong Street.

It is proposed to construct a triangular, concrete, island in Yerong Street to facilitate priority controlled left in/left out.

The construction is to be completed prior to the issue of an Occupancy Certificate for Stage 2 of the development.

Railway Road Pedestrian Crossing

Based upon traffic counts undertaken by *R.O.A.R. Data*, and the projected vehicle generation with 100% occupation of Stages 1, 2 and 3 of the Shepherds Bay development the site fails to satisfy the current *RMS* warrant for traffic signal installation and no further action is considered necessary at this time.

The current volume of pedestrian demand reported during two, typical, consecutive one-hour periods, in the morning commuter peak is 555 with the corresponding vehicle flows in Railway Road of 1232 northbound and 685 southbound.

Extensive queuing was noted, extending to the south in Railway Road from the existing marked foot-crossing, to the railway overbridge roundabout at Bank Street.

The volume reported during two, one-hour periods, of the evening commuter peak totalled 337 with corresponding vehicle flows of 661 northbound and 1763 southbound with extensive queuing noted, extending back into Constitution Road, during the evening peak.

No recent accident history has been reported at the site.

The *RMS* warrant requires the pedestrian flows to exceed 250 persons/hour for each of four (4) one (1) hour periods with conflicting vehicle flows of no less than 600vph, in each direction.

With the addition of pedestrian and vehicle generation projected from Stages 1, 2 and 3, the mid block site does not satisfy the warrant for the installation of traffic signals, at this time.

PUBLIC TRANSPORT

The Metropolitan Strategy, under the auspices of 'Draft SEPP 66 – Integration of Land Use and Transport', prescribes guiding provisions that aim to ensure the urban structure, building forms, land use locations, development design, subdivision and street layouts to help achieve the following planning objectives...

- Improving accessibility to housing, employment and services by walking, bicycling and public transport,
- Improving the choice of transport and reducing the dependancy on private vehicle usage,
- Moderating growth in the demand for travel and the distances travelled, especially by car,
- → Support the efficient and viable operation of public transport services, and
- → Providing for the efficient movement of freight.

The provision seeks to influence mode choice made by both community and business.

The State Government's has invested in 300 new buses across the state, which has resulted in 400 new jobs for bus drivers and 150 jobs in bus construction.

Rail

Meadowbank Railway Station is located near the corner of Railway Road and Constitution Road, some 500-700m from the development. The railway station is approximately 6 to 8 minutes walk utilising the Underdale Lane pedestrian link from nancarrow Avenue.

The railway station is located on the Northern Line, approximately mid-way between Strathfield and Hornsby Railway Stations. The Northern Line operates on a loop comprising Hornsby, the City Circle and Strathfield, via the Epping-Chatswood rail link.

Weekday train services operate every 15 minutes during weekday commuter peak periods, and every 30 minutes outside peak periods. Weekend services also operate every 30 minutes.

Meadowbank Railway Station is located four stops south of Epping Station, a major bus rail interchange with connecting rail services to the City via Macquarie University, Chatswood and North Sydney, and connecting bus services to the Hills District.

To the south Meadowbank Railway Station is located four stops from Strathfield Station, a major bus rail interchange with connections to the North Shore and Western Line, the South Line (to Campbelltown), the Inner West Line between the City Circle and Liverpool, as well as most intercity rail services (ie. to Newcastle, Lithgow and Southern Highlands).

Buses

Bus services through the MEA are operated by Sydney Buses with weekday services operating every 30 minutes and additional services during the commuter peak periods.

Weekend services generally operate every 60 minutes. Bus stops are located at regular intervals along both sides of Bowden Street and Constitution Road, as well as along Church Street and Victoria Road.

Improved pedestrian access provisions under the development will afford residents greater incemntive to embrace the abundance of public transport oportunitites within the *MEA*.

| Route No. | Nearest Bus Stop | Service Route |
|-----------|-------------------|---|
| | | |
| 507 | Constitution Road | Meadowbank Station to Sydney CBD & Macquarie University |
| 513 | Bowden Street | Meadowbank Wharf to Carlingford Court |
| 533 | Church Street | Chatswood to Olympic Park |
| 458 | Church Street | Burwood Station to Top Ryde |
| 459 | Church Street | Strathfield Station to Macquarie University |
| 534 | Victoria Road | West Ryde Station to Chatswood Station |
| 520 | Victoria Road | Parramatta Station to Sydney CBD |

Pedestrians and Bicyclists

There are a number of cycleways and shared pedestrian paths providing convenient access to and from the Shepherds Bay development for those residents who do not wish to drive or use public transport.

Studies have shown that in Sydney, over 50% of trips are less than 5km; such trips are ideally suited to walking or cycling.

The nearby shared off-road pedestrian and cycleway path which is located along the foreshore continues towards the west to Parramatta and towards the east to the City, using a combination of on and off-road cycleways and pedestrian paths.

An on-road cycleway connects with the foreshore shared pedestrian and cycleway path and follows a generally north-south alignment along Bowden Street and Angus Street to connect with West Ryde Railway Station and other on-road cycleways which extend further to the north. A shared pedestrian and cycleway path also extends southward across Ryde Bridge to the Rhodes peninsula where it connects to other on and off-road cycleways that extend to the south to Concord and Olympic Park.

The proposed development will enhance the options available to residents for walking and cycling through the provision of 3 new east-west cycle links between Bowden Street and Belmore Road. The improved permeability for pedestrians and cyclists offered by these links will provide more direct links for residents when walking or cycling to nearby facilities such as the local primary school, TAFE College, local shops and railway station.

Improved pedestrian links will be provided along all east-west and north-south road links, with additional mid-block pedestrian links to be provided generally following a north-south alignment. The improved pedestrian links will significantly enhance the accessibility of public transport services for residents wishing to walk to the station or to bus stops located in Constitution Road, Bowden Street, Victoria Road, Belmore Street or Church Street.

CONCLUSION

This report, commissioned by *Holdmark* and undertaken by *Road Delay Solutions*, supports the Section 96 Application by Holdmark.

The Section 96 Applicastion proposes 28 additional apartments over and above the 17 included as part of the deed of agreement, bringing the total number of architecturally designed appartments for Stages 2 and 3 to 498.

The former DA Application sought approval to 431 apartnments.

The 498 apartments proposed under this Section 96 Application will generate some 144vph during the commuter peak travel periods.

The report assess the conditioned infrastructure necessary to sustain the level of development, in accordance with the Department of Planning & Infrastructure Concept Approval, MP09_0216 and proposes the relavent timing for each.

In support of the foregoing assessment, the following is considered relevant to the development Stages 2 and 3...

- → The site is ideally located in close proximity to a broad range of public transport alternatives, reducing dependence on use of private passenger vehicles.
- → The site is located within easy walking/cycling distance of a range of shops and services (such as the local post office, TAFE College and primary schools).
- → The site is located immediately adjacent to a shared pedestrian and bicycle path with links to Parramatta and the Sydney CBD.
- → The planned Nancarrow Road extension will improve mobility and accessibility for pedestrians and cyclists.
- → Construction of a roundabout at the intersection of Belmore Street and Rothesay Avenue should be designed, to Council specifications, prior to issue of the Occupation Certificate for Stage 2 of the development.
- Design and construction of a triangular, concrete, island in Yerong Street at Belmore Street to facilitate priority controlled left in/left out with construction to be completed prior to the issue of an Occupancy Certificate for Stage 2 of the development.

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- \rightarrow No warrant exists for the signalisation of the Constitution Road intersection with Bowden Street.
- \rightarrow No warrant exists for the signalisation of the marked foot crossing in Railway Road, at this time.

APPENDIX A – TRAFFIC COUNTS

Road Delay Solutions has commissioned ROAR Data to annually count key intersections within the MEA, in particular the intersections of Constitution Road with both Bowden Street and Belmore Street and the pedestrian mid block crossing in railway Road. These counts have been collected in or around November of each year from 2011 to 2014, inclusive.

The 2014 counts, along with the projected traffic volumes for the respective stages of development at key locations, are presented in this Appendix.

\$96 Traffic Impact Assessment



Shepherds Bay Stages 2 and 3

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Shepherds Bay Stages 2 and 3

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| Ø | Reliable, O | C. DATA Driginal & Au 7, Fax 881968 | | c Results 0.0418-239019 | | | | | Job No | ient o/Name /Date | : 5447 | Delay Soluti MEADOWB/ day / 9th Dec | ANK Traffic 8 | Ped Counts | |
|---|---|---|--|---|--------------------------------|--|------------------------------|--|---------------------------------|---|---|---|-------------------------------------|-------------------------------------|-------------------------|
| | | ay Rd lehicles | | AM | | ay Rd /ehicles | | | | ay Rd Vehicles | | <u>PM</u> | | vay Rd Vehicles | |
| Time Per | Northbound | Southbound | TOT | Time Per | Northbound | Southbound | TOT | Time Per | Northbound | Southbound | TOT | Time Per | Northbound | Southbound | TOT |
| 0700 - 0715 | 130 | 53 | 183 | 0700 - 0715 | 0 | 1 | 1 | 1600 - 1615 | 85 | 230 | 315 | 1600 - 1615 | 0 | 0 | 0 |
| 0715-0730 | 147 | 75 | 222 | 0715 - 0730 | 0 | 0 | 0 | 1615 - 1630 | 73 | 200 | 273 | 1615 - 1630 | 1 | 0 | 1 |
| 0730 - 0745 | 156 | 85 | 241 | 0730 - 0745 | 0 | 0 | 0 | 1630 - 1645 | 96 | 222 | 318 | 1630 - 1645 | 0 | 0 | 0 |
| 0745 - 0800 | 152 | 88 | 240 | 0745 - 0800 | 0 | 0 | 0 | 1645 - 1700 | 72 | 250 | 322 | 1645 - 1700 | 0 | 0 | 0 |
| 0800 - 0815 | 152 | 96 | 248 | 0800 - 0815 | 0 | 0 | 0 | 1700 - 1715 | 76 | 236 | 312 | 1700 - 1715 | 0 | 0 | 0 |
| 0815 - 0830 | 161 | 108 | 269 | 0815 - 0830 | 0 | 1 | 1 | 1715 - 1730 | 91 | 210 | 301 | 1715 - 1730 | 0 | 0 | 0 |
| 0830 - 0845 | 190 | 93 | 283 | 0830 - 0845 | 0 | 0 | 0 | 1730 - 1745 | 103 | 205 | 308 | 1730 - 1745 | 0 | 0 | 0 |
| 0845 - 0900 | 144 | 87 | 231 | 0845 - 0900 | 0 | 0 | 0 | 1745 - 1800 | 65 | 210 | 275 | 1745 - 1800 | 0 | 0 | 0 |
| eriod End | 1232 | 685 | 1917 | Period End | 0 | 2 | 2 | Period End | 661 | 1763 | 2424 | Period End | 1 | 0 | 1 |
| Peak Per 1700 - 0800 1715 - 0815 1730 - 0830 1745 - 0845 1800 - 0900 | Northbound 585 607 621 655 647 | Southbound 301 344 377 385 384 | TOT 886 951 998 1040 1031 | Peak Per 0700 - 0800 0715 - 0815 0730 - 0830 0745 - 0845 0800 - 0900 | Northbound 0 0 0 0 | Southbound 1 0 1 1 1 1 | TOT 1 0 1 1 1 | Peak Per 1600 - 1700 1615 - 1715 1630 - 1730 1645 - 1745 1700 - 1800 | 326 317 335 342 335 | Southbound 902 908 918 901 861 | TOT 1228 1225 1253 1243 1196 | Peak Per 1600 - 1700 1615 - 1715 1630 - 1730 1645 - 1745 1700 - 1800 | Northbound 1 0 0 0 0 | Southbound 0 0 0 0 0 | TOT 1 0 0 0 |
| PEAK HR | 655 | 385 | 1040 | PEAK HR | 0 | 1 | 1 | PEAK HR | 335 | 918 | 1253 | PEAK HR | 0 | 0 | 0 |
| Peak Hour | Railw | ay Rd | | TOTAL VOLUMES | Railw | ay Rd | | Peak Hour | Railw | ay Rd | | TOTAL VOLUMES | Raile | vay Rd | |
| 0745 - 0845 | ן מטוני מטוני |]]]]] | | | 0000 |]]]]] | | 1630 - 1730 | 0001 |] [[[[] 918 1 | | | 0001 |] [] [] [] 1763 I | |

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| | Railw Light V | ay Rd | | | Railw Heavy | ay Rd | | | | ray Rd /ehicles | | | | vay Rd Vehicles | 1 |
| Time Per | Northbound | and the second se | TOT | Time Per | Northbound | and the second state of th | TOT | Time Per | | Southbound | TOT | Time Per | | Southbound | TOT |
| 0700 - 0715 | 130 | 53 | 183 | 0790-0715 | 0 | Production of the | 1 | 1600 - 1615 | 85 | 230 | 315 | 1000- 3015 | D | 0 | 0 |
| 0715 - 0730 | 147 | 75 | 222 | 0715-0730 | 0 | 0 | 0 | 1615 - 1630 | 75 | 200 | 273 | 1615- 1630 | t | 0 | Ť |
| 0750 - 0745 | 156 | 85 | 241 | 0730 - 0745 | 0 | 0 | 0 | 1630 - 1645 | 96 | 222 | 318 | 1630 - 3545 | 0 | 0 | 0 |
| 0745-+ 0800 | 152 | 88 | 240 | 0745 - 0800 | 0 | 0 | 0 | 1645 - 1700 | 72 | 250 | 322 | 1645-1700 | 0 | 0 | 0 |
| 0800 - 0815 | 152 | 95 | 248 | 0600 - 0815 | 0 | 0 | 0 | 1700 - 1715 | 70 | 236 | 312 | 1700-1715 | 0 | 0 | 0 |
| 0815 - 0830 | 151 | tig | 269 | 0815 - 0838 | 0 | 1 | Ť | 1715 - 1730 | 90 | 210 | 301 | 1715- 1730 | 0 | 0 | 1 0 |
| 8630 - 0645 | 190 | 90e 93 | 283 | 0839+0845 | 0 | 0 | 0 | 1730 - 1745 | 103 | 205 | 308 | 1738-1745 | 0 | 0 | 0 |
| 0630 - 0605 | 140 | 67 | 231 | 0545 - 0900 | 0 | 0 | 0 | 1745 - 1800 | 65 | 210 | 275 | 1745+ 1800 | 0 | 0 | 0 |
| Period End | 1232 | 685 | 1917 | Period End | 0 | 2 | 2 | Period End | 661 | 1763 | 2424 | Period End | 1 | 0 | Ť |
| 0700 - 0800 0715 - 0815 | 585 667 | Southbound 301 304 | TOT 886 951 | Peak Per 0700 - 0908 0715 - 0815 | Northbound 0 0 | Southbound 1 0 | 1 1 0 | Peak Per 1600 - 1700 1615 - 1715 | 326 317 | 902 906 | TOT 1228 1225 | Peak Per 1600 - 1700 1615 - 1715 | Northbound t | 0 0 | 101 |
| 0730-0830 | 621 | 377 | 998 | .0730 - 0830 | 0 | 1 | 1 | 1830 - 1730 | 235 | 918 | 1253 | 1630 - 1750 | 0 | 0 | 0 |
| 0746 - 0845 | 655 | 385 | 1040 | 0745 - 0945 | 0 | 1 | 1 | 1645 - 1745 | 342 | 901 | 1243 | 1645-1745 | 0 | 0 | 0 |
| 8800 - 6900 | 647 | 364 | 1031 | 0600 - (0900 | 0 | 1 | 1 | 1700 - t800 | 335 | 166 | 1196 | 1700-3800 | 0 | 0 | U U |
| PEAK HR | 655 | 385 | 1040 | PEAK HR | 0 | 1 | 1 | PEAK HR | 335 | 918 | 1253 | PEAK HR | 0 | 0 | 0 |
| Peak Hour 0745 - 0845 | † | ^{™ Rd}]]]]]]]]]]]]]]]]]]]]]]]]]]]]]]]]]]]] | | TOTAL VOLUMES | 1232 | , ra] | | Peak Hour 1620 - 1730 | 1 335 | oy Rd | | TOTAL VOLUMES | 661 | ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | 0 |

| | | ay Rd | | | | ay Rd | 1 |
|----------------------------|--|--|-----|--------------|-----------|--------------------------------------|-----|
| | Peds C | rossing | L | | Peds C | rossing | |
| Time Per | Eastbound | Westbound | TOT | Time Per | Eastbound | Westbound | TOT |
|)700-0715 | 18 | 35 | 53 | 1600 - 1615 | 34 | 17 | 51 |
| 1715-0730 | 10 | 48 | 58 | 1615 - 1630 | 26 | 13 | 39 |
| 1730-0745 | 16 | 86 | 102 | 1630 - 1645 | 23 | - 24 | 47 |
| 0745 - C800- | 16 | 68 | 84 | 1645 - 1700 | 27 | 13 | 40 |
| 800 - 0815 | 10 | 88 | 98 | 1700 - 1715 | 30 | 19 | 49 |
| 3815 - 0830 | 18 | 40 | 66 | 1715 - 1738 | 30 | 12 | 42 |
| 830 - 0845 | 10 | 42 | 52 | 1730 - 1745 | 62 | -25 | 93 |
| 3845 - 0900 | 5 | 37 | 42 | 1745 - 1888 | 60 | 16 | 76 |
| eriod End | 103 | 452 | 555 | Period End | 292 | 145 | 437 |
| | | <u>K HOUR</u> - 0830 | | | | <u>K HOUR</u> - <mark>1800</mark> | |
| 8 | and the second strength of the second strengt | ay Rd | | 1 | | ay Rd | 1 |
| | | rossing | | | | rossing | |
| Peak Per | Eastbound | Address of the local division of the local d | TOT | Peak Per | Eastbound | Westbound | TOT |
| 1700 - 0800 | 60 | 237 | 297 | 1600 - 1700 | 110 | 67 | 177 |
| 1715 - 0815 | 52 | 290 | 342 | 1615 - 1715 | 105 | . 69 | 175 |
| 730 - 0830 | 60 54 | 290 | 300 | 1630 - 1730 | | 68 | 178 |
| 0745 - 0645 0900 - 0800 | 43 | 246 | 258 | 1700 - \$800 | 149 | 75 | 224 |
| 000 - 0000 | 40 | 219 | 230 | 1700 - 3800 | 194 | - 18 | 200 |
| PEAKHR | 60 | 290 | 350 | PEAK HR | 182 | 78 | 260 |
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Client : Road Delay Solutions Pty. Ltd Job No/Name : 5447 MEADOW/BANK Traffic & Ped Counts Day/Date : Tuesday / 9th December 2014

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APPENDIX B – PERFORMANCE INDICATORS

General

Intersection performance is best measured by the indicators of Level of Service (LoS), Average Vehicle Delay (AVD) and the Degree of Saturation (DS) during peak hours.

This is defined as the assessment of a qualitative effect of factors influencing vehicle movement through the intersection. Factors such as speed, traffic volume, geometric layout, delay and capacity are qualified and applied to the specific intersection control mode, as shown in Table 1.

The measure of average delay assessed for traffic signal operation is over all movements. For roundabouts and priority controlled intersections, the critical criterion for assessment is the movement with the highest delay per vehicle.

| Intersection Control | Performance Measure [Unit] |
|--------------------------|---|
| | → Delay of critical movement(s) [seconds/vehicle] |
| Sign or Priority Control | → Average Vehicle Delay [seconds/vehicle] |
| ° | → Queue length of critical movement(s) [metres] |
| | → Delay of critical movement(s) [seconds/vehicle] |
| | → Degree of Saturation [ratio of vehicles to capacity] |
| Traffic Signal Control | → Average Vehicle Delay [seconds/vehicle] |
| | → Cycle Length [seconds] |
| | → Queue length of critical movement(s) [metres] |
| | → Delay of critical movement(s) [seconds/vehicle] |
| | → Degree of Saturation[ratio of vehicles to capacity] |
| Roundabout Control | → Average Vehicle Delay [seconds/vehicle] |
| | \rightarrow Queue length of critical movement(s) [metres] |

Table A1: Performance Indicators by Control Method

Average Vehicle Delay (AVD)

The AVD is a measure of the operational performance of a road network or an intersection.

AVD is determined globally over a road network or within a cordon during an assignment model run. The AVD exhibited on comparable network models, for analogous peak periods, forms the basis of comparing the operational performance of the road network.

AVD is used in the determination of intersection Level of Service. Generally, the total delay incurred by vehicles through an intersection is averaged to give an indicative delay on any specific approach. Longer delays do occur but only the average over the peak hour period is reported.

Degree of Saturation (DS)

The DS of an intersection is usually taken as the highest ratio of traffic volume on an approach to the intersection compared with its theoretical capacity, and is a measure of the utilisation of available green time. The DS reported is generally of a critical movement through the intersection rather than the DS of the intersection unless equal saturation occurs on all approaches.

For intersections controlled by traffic signals, generally both queue length and delay increase rapidly as DS approaches 1.0. An intersection operates satisfactorily when its DS is kept below 0.875. When the DS exceeds 0.9, extensive queues can be expected.

| LOS | AVD secs | Traffic Signals and Roundabout | Give Way and Stop Sign Priority Control |
|-----|-------------|--|--|
| А | 1 to 14 | Good operation. | Good operation |
| В | 14 to 28 | Good operation with acceptable delays and spare capacity. | Good operation with acceptable delays and spare capacity. |
| с | 28 to 42 | Satisfactory. | Satisfactory but accident study and operational analysis required. |
| D | 42 to 56 | Operating near capacity. | Near capacity. Accident study and operational analysis required. |
| E | 56 to 70 | Unsatisfactory. Traffic signals incidence will cause excessive delays. Requires additional capacity. Roundabouts require alternative control mode. | At capacity. Requires alternative control mode. |
| F | >70 | Unsatisfactory. Over capacity and unstable operation. | Over capacity. Unstable and unsafe operation. |

Table A2: Qualified Level of Service by Control Method

APPENDIX C – ARTERIAL ROAD ASSESSMENT

Shepherds Bay, Meadowbank

Addendum Arterial Road Network Traffic Signal Operation Assessment

for...



Reference: 20100099 November 2012 © 2012 Road Delay Solutions Pty Ltd, Australia



DOCUMENT STATUS

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| Reviewed | Adam Fahim : Brian Mann: |
| Date | 2 November 2012 |

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Road Delay Solutions Pty Ltd assumes no responsibility or liability for the predictive nature of any traffic volumes, and resultant conclusions, detailed in this document. The modelling projections are subject to significant uncertainties and unanticipated change, without notice. While all source data, employed in the preparation of this document, has been diligently collated and checked, Road Delay Solutions Pty Ltd is unable to assume responsibility for any

errors resulting from such projections.

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1 INTRODUCTION

Road Delay Solutions has been engaged by Robertson + Marks Architects and Holdmark NSW Pty Ltd to undertake the preparation of a Strategic Transport Model in support of the Control for the Shepherds Bay Urban Renewal Development.

As part of this process an assessment has been undertaken into the impacts and operational performance of the arterial road network, under the control of traffic signals on Victoria Road and Church Street.

This assessment of the arterial road network, servicing the Meadowbank Employment Area (MEA) and the proposed Shepherds Bay Urban Renewal Development, has been prepared utilising the intersection turn movements, collected by R.O.A.R. in June 2010 to reflect the current base traffic conditions during the commuter peak periods.

The future year 2031 traffic projections have been taken from the preferred Bitzios Saturn models of the precinct for the respective peak commuter periods, with the turn movements interpolated, by percentage, from the base year intersections, by the corresponding vehicle movement.

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2 EXISTING CONDITIONS

The existing traffic volumes, as shown in Figure 1, were collected by R.O.A.R. DATA in June 2010 and encompass...

- → Victoria Road from Bowden Street to Devlin Street, and
- Church Street/Devlin Street from the Ryde Bridge to Victoria Road. \rightarrow

The Victoria Road intersectiuons modelled are...

- Victoria Road and Bowden Street TCS 491, and \rightarrow
- Victoria Road and Church Street TCS 110. \rightarrow

The Church Street intersections modelled are...

- → Church Street and Well Street mid block pedestrian site TCS 1956,
- Church Street and Junction Street TCS 448, and \rightarrow
- Church Street and Morrison Road TCS 11. \rightarrow

Figure 8: Existing Traffic



It should be noted that significant vehicle queuing has been observed, predominantly in the peak flow direction, during the commuter periods along Church Street. This resultant, 'platooned', vehicle demand exacerbates the operational route performance of Church Street, but is not directly attributable to the signal operations being assessed in this report.

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The Scates Model

The PC based Scates program calculates the optimum phasing design, phase splits, offsets and cycle lengths for network and/or linear traffic signal system operation.

This assessment will detail the operational characteristics of the traffic signal sites modeleld and present the maximum back of queue lengths reported.

A number of input parameters are required by Scates to reflect the current conditions at each traffic signal site. These user defined inputs are presented in Table 1.

Table 9: Scates Input Parameters

| Parameter | Parameter Value | Remarks | | | | |
|---|------------------------------------|--|--|--|--|--|
| Lane Saturation Thresholds | LT - 11750 Thru 1960 RT 1850 | The saturation threshold or capacity of each lane, by movement, is expressed in vehicles per hour. The maximum capacity of each lane type yielding a saturation of 1 is employed in the Scates model. The capacities are predetermined on a general acceptance of typical lane types for the specific conditions. The through movement lane types have been found to generally be capable of carrying some 1960 vph within the Sydney regional centres where congested traffic conditions prevail and motorists have become 'conditioned' to driving in closer formation at slow speeds. | | | | |
| % Heavy Vehicles | ² 2 | The percentage of heavy on Victoria Road and Church Street, commensurate with the field data collected by R.O.A.R., in June 2010. | | | | |
| Heavy Vehicle PCU Equivalence ³ 2 | | AUSTROADS prescribes a PCU equivalence of 2.4. Scates accepts whole numbers only with respect to the PCU equivalence. Each heavy vehicle is equivalent to the delay incurred by two (2) passenger vehicles. | | | | |
| Pedestrians | 50 peds/hr | An arbitrary 50 pedestrians per hour have been modelled at each site | | | | |
| Frequency of WALK Green Time | 25% / 33% | A pedestrian walk frequency of 30% has been adopted to reflect a call demand for the walk every 3rd cycle. | | | | |
| Pedestrian WALK 6 sec | | Commensurate with current RMS practice. | | | | |
| Pedestrian Clearance time | 1.2m/sec | Commensurate with current RMS practice. | | | | |
| Stop Penalty | 10 sec | Utilised in the calculation of the intersection Performance Index eg. <i>Rate of Delay + (Rate of Stops * Stop Penalty)</i> . A 10 second stop penalty optimises the traffic system to minimise vehicle and operating costs along the corridor. | | | | |
| Predominant Design Speed | 60 & 70 km/h | Regulated speeds - Victoria Road is 60 km/h and Church Street is 70 km/h. All residential side streets assume 50 km/h, unless signposted otherwise. | | | | |
| Effective Lost Time (ELT) | 4 sec | The total seconds accumulated during the inter-green periods minus the allowance for turn movements on amber, per cycle. 4 seconds is considered an average in s built up urban area. | | | | |
| LT / RT Delay | 0 sec | Employed in Scates to reflect the impact of a high ped demand and a LT and/or RT RA hold condition. Should the LT and/or RT movements be able to clear following clearance of the pedestrian demand and within the remaining green time, 0 sec delay should be modelled. | | | | |
| Min Cycle Length | 20 sec | Scates begins cycle iterations commencing at the | | | | |
| Max Cycle Length | 120 sec | Scates optimises the intersection operation to the upper limit specified but may increase the max cycle length, by up to 20 seconds, if it calculates a cost benefit to do so. | | | | |

¹ Expressed in vehicles per hour (vph)

² Scates converts traffic flow numbers to PCU's during a mode run to reflect the impact of heavy vehicle movements along the corridor

³ Each heavy vehicle is equivalent to the delay incurred by two (2) passenger vehicles

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Victoria Road

Victoria Road currently carries some 4,500 vph during the commuter peak periods. A major arterial corridor linking Parramatta to the Sydney CBD, intermittent bus lanes and a high number of signalised intersections, particularly through the West Ryde Precinct, has a platooning effect on traffic in the peak flow directions.

The intersection with Church Street has a bus only lane operating in the southbound, right turn approach to Victoria Road. To assimilate this feature the Scates model has adopted a late start for the right turn movement of 3 seconds, every 2nd cycle allowing the bus movement some 30 times during the combined morning and evening peak periods.

The modelling indicates that the Victoria Road traffic signals, at Bowden Street and Church Street, currently operate at an acceptable level of service, as shown in *Table* 2.

Queue lengths reported from the model are considered satisfactory and do not impede the operation of preceding intersections along the corridor while all turn movements are adequately contained within their respective bay lengths per cycle.

| | | VICTORIA ROAD OPERATION | | | |
|--------------------------------|-----|-------------------------|-------------------|--|--|
| Victoria Road Intersections | | AM (CL 139sec) | PM (CL 105sec) | | |
| | LOS | A | A | | |
| Bowden Street TCS 491 | DS | 0.90 | 0.81 | | |
| | AVD | 7 | 8 | | |
| | LOS | С | В | | |
| Church Street TCS 110 | DS | 0.67 | 0.75 | | |
| | AVD | 37 | 21 | | |

Table 10: Existing Operation – Victoria Road

Table 11: Existing Queue Lengths – Victoria Road

| | | VICTORIA RO | DAD QUEUES |
|--------------------------------|----|---------------------------------|---------------------------------|
| Victoria Road Intersections | | AM Max. Back of Queue (m) | PM Max. Back of Queue (m) |
| | NB | 60 | 30 |
| Bowden Street | SB | 24 | 18 |
| TCS 491 | EB | 85 | 42 |
| | WB | 45 | 36 |
| | NB | 42 | 42 |
| Church Street | SB | 48 | 54 |
| TCS 110 | EB | 66 | 48 |
| | WB | 54 | 54 |

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Church Street

Church Street carries in the order of 6,200 vph during the commuter peaks and is subject to the affects of 'platooned' traffic occurring in the peak flow directions from the intersections of Homebush Bay Drive and Concord Road, to the south, and the Devlin Street and Blaxland Road intersection, to the north.

The Scates analysis does not consider the impacts from residual queueing in Church Street from either the Concord Road intersection with Homebush Bay Drive or the Blaxland Road intersection with Devlin Street. While this is considered necessary to assess the route operation of Church Street, the Concord Road and Blaxland Road intersections are outside the scope of this study. It is further considered that no improvement to the capacity or operation of the modelled intersections in this report will result in a significant gain in route performance.

As a consequence, the modelling suggests that that the traffic signals, from Well Street to Morrison Road, operate at a satisfactory level of service. No significant queueing is generated by these sites and all turn movements are contained within the extents of the current bays.

Most importantly, the modelling indicates the signal operations adequately manage the volume of side street traffic currently accessing the corridor.

| | | CHURCH STR | EET EXISTING |
|--------------------------------|-----|-------------------|-------------------|
| Church Street Intersections | | AM (CL 105sec) | PM (CL 128sec) |
| | LOS | A | A |
| Well Street TCS 1956 | DS | 0.80 | 0.78 |
| | AVD | 5 | 6 |
| | LOS | A | A |
| Junction Street TCS 448 | DS | 0.69 | 0.72 |
| | AVD | 5 | 5 |
| | LOS | A | А |
| Morrison Road TCS 11 | DS | 0.76 | 0.80 |
| | AVD | 6 | 6 |

Table 12: Existing Operation - Church Street

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Table 13: Existing Queue Lengths – Church Street

| | | CHURCH STREET QUEUES - EXISTING | | |
|--------------------------------|----|---------------------------------|---------------------------------|--|
| Church Street Intersections | | AM Max. Back of Queue (m) | PM Max. Back of Queue (m) | |
| | NB | 54 | 60 | |
| Well Street | SB | 60 | 60 | |
| TCS 1956- | EB | - | - | |
| | WB | - | - | |
| | NB | 42 | 48 | |
| Junction Street | SB | 42 | 36 | |
| TCS 448 | EB | 18 | 18 | |
| | WB | - | - | |
| | NB | 48 | 42 | |
| Morrison Road | SB | 48 | 48 | |
| TCS 11 | EB | 36 | 30 | |
| | WB | 36 | 48 | |

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3 FUTURE CONDITIONS

Projected Volumes

The projected base 2031 link volumes, adopted in the Scaters modelling, have been interpolated from the Year 2031 preferred Saturn models, including Part 3A development, and application of the difference volumes, prepared by Bitzios Consulting, and presented in *Figure 2 – AM Peak* and *Figure 3 – PM Peak*.

The future 2031 preferred network traffic projections, prepared by Bitzios Consulting, are shown in Figure 4 – AM Peak and Figure 5 – PM Peak.

The turn movements employed in the Scates models were proportioned from the link volumes, based upon the current percentage movement volumes, shown in *Figure 1*.

The future traffic movements modelled at each intersection are presented in Figure 6.

Comparison modelling for year 2031, with and without the proposed 3A development, resulted in no significant difference in the operation levels reported at the modelled intersections.

Victoria Road

The future traffic projections suggest that traffic volumes on Victoria Road will be in the order of 5,100 vph and 4,900 vph during the morning and evening commuter peak periods, respectively. This constitutes an increases of some 10.9% in the morning peak and 16.7%% during the evening peak.

The modelling indicates that the Victoria Road traffic signals, subjected to the projected volumes as determined by Bitzios Consulting, should operate at an acceptable level of service, as shown in *Table* 6.

Queue lengths reported from the model are considered satisfactory and will not impede the operation of preceding intersections along the corridor, while all turn movements are adequately contained within their respective bay lengths per cycle.

As a result of the future year modelling it is deduced the future traffic generation associated with the proposed Shepherds Bay development does not necessitate any need for infrastructure improvements along the Victoria Road corridor.

| | | VICTORIA ROAD WITHOUT DEVELOPMENT | | VICTORIA ROAD WITH DEVELOPMENT | |
|--------------------------------|-----|-----------------------------------|-------------------|--------------------------------|-------------------|
| Victoria Road Intersections | | AM (CL 140sec) | PM (CL 105sec) | AM (CL 139sec) | PM (CL 105sec) |
| | LOS | В | В | В | В |
| Bowden Street TCS 491 | DS | 0.99 | 0.77 | 0.98 | 0.75 |
| | AVD | 26 | 18 | 24 | 18 |
| | LOS | С | В | С | В |
| | | | | | |

Table 14: Future Operation – Victoria Road

| TCS 110 | DS | 0.89 | 0.82 | 0.89 | 0.80 |
|---------|-----|------|------|------|------|
| | AVD | 35 | 23 | 36 | 23 |

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Addendum - Arterial Road Network

| | | VICTORIA ROAD QUEUES WITH DEVELOPMENT | | |
|--------------------------------|----|--|---------------------------------|--|
| Victoria Road Intersections | | AM Max. Back of Queue (m) | PM Max. Back of Queue (m) | |
| | NB | 54 | 54 | |
| Bowden Street | SB | 126 | 48 | |
| TCS 491 | EB | 36 | 42 | |
| | WB | 30 | 54 | |
| | NB | 42 | 24 | |
| Church Street TCS 110 | SB | 54 | 24 | |
| | EB | 60 | 54 | |
| | WB | 78 | 42 | |

Table 15: Future Queue Lengths with Development – Victoria Road

Church Street

With increases of 6.5% and 17.5% in the morning and evening peak commuter periods, respectively, Church Street is projected to carry some 6,600vph in the morning peak and 7,400vph in the evening peak.

Under theses increases Church Street has been found to should operate at an acceptable level of service, as shown in Table 8.

The reported queue lengths, generated by the three intersections modelled, do not impede the operation of preceding intersections and all turn movements are satisfactorily contained within the existing turn bays. However, in the broader regional context, residual queuing northbound, from the upstream intersection of Devlin Street and Blaxland Road has a dramatic impact on the Concord Road/Church Street route performance, which has been excluded from the operational modelling. It was found through sensitivity modelling that increasing the capacity on Church Street northbound, between Ryde Bridge and the Devlin Street underpass would have little to no significant impact on the residual queue length observed along the section as any isolated measure does not address the broader, downstream, impact of the Devlin Street intersection operation at Blaxland Road.

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Table 16: Future Operation - Church Street

| | | CHURCH STREET WITHOUT DEVELOPMENT | | CHURCH STREET WITH DEVELOPMENT | |
|--------------------------------|-----|-----------------------------------|-------------------|--------------------------------|-------------------|
| Church Street Intersections | | AM (CL 105sec) | PM (CL 128sec) | AM (CL 105sec) | PM (CL 128sec) |
| | LOS | A | A | A | A |
| Well Street TCS 1956 | DS | 0.87 | 0.88 | 0.88 | 0.86 |
| | AVD | 5 | 6 | 5 | 5 |
| | LOS | A | A | A | A |
| Junction Street TCS 448 | DS | 0.81 | 0.86 | 0.82 | 0.84 |
| | AVD | 6 | 5 | 6 | 5 |
| | LOS | A | A | A | A |
| Morrison Road TCS 11 | DS | 0.76 | 0.76 | 0.76 | 0.79 |
| | AVD | 6 | 6 | 6 | 6 |

Table 17: Future Queue Lengths with Development – Church Street

| | | CHURCH STREET QUEUES WITH DEVELOPMENT | |
|--------------------------------|----|--|---------------------------------|
| Church Street Intersections | | AM Max. Back of Queue (m) | PM Max. Back of Queue (m) |
| | NB | 60 | 72 |
| Well Street | SB | 66 | 72 |
| TCS 1956- | EB | - | - |
| | WB | - | - |
| | NB | 54 | 60 |
| Junction Street | SB | 54 | 36 |
| TCS 448 | EB | 30 | 24 |
| | WB | - | - |
| | NB | 48 | 42 |
| Morrison Road | SB | 48 | 48 |
| TCS 11 | EB | 36 | 30 |
| | WB | 36 | 36 |

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Figure 9: 2031 AM Peak Bitzios Traffic Volumes with Development



Link Volumes for the Preferred Network - 2031 AM Peak

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Figure 10: 2031 PM Peak Bitzios Traffic Volumes with Development



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4 CONCLUSION

Adopting the future year traffic projections provided by Bitzios Consulting, it can be concluded from the foregoing assessment that...

- → The residual queuing experienced, primarily on Church Street during the evening commuter peak periods as a result of the operations of intersections beyond the scope of this project, have not been factored into the operation of the modeled intersections,
- → The future operations of traffic signals on Church Street, between Well Street and Morrison Road, will be satisfactory,
- → The future operations of traffic signals on Victoria Road, between Bowden Street and Church Street, will be satisfactory,
- → The future traffic generation resulting from the proposed urban renewal of Shepherds Bay will have no detrimental impact on the operations of Victoria Road and Church Street, and
- → No warrant can be drawn for any improvements to road infrastructure on Victoria Road and/or Church Street as a result of the proposed Shepherds Bay development.

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APPENDIX A – Performance Indicators

General

Intersection performance is best measured by the indicators of Level of Service (LoS), Average Vehicle Delay (AVD) and the Degree of Saturation (DS) during peak hours.

This is defined as the assessment of a qualitative effect of factors influencing vehicle movement through the intersection. Factors such as speed, traffic volume, geometric layout, delay and capacity are qualified and applied to the specific intersection control mode, as shown in Table 1.

The measure of average delay assessed for traffic signal operation is over all movements. For roundabouts and priority controlled intersections, the critical criterion for assessment is the movement with the highest delay per vehicle.

| Intersection Control | Performance Measure [Unit] | | |
|--------------------------|--|--|--|
| Sign or Priority Control | Delay of critical movement(s) [seconds/vehicle] Average Vehicle Delay [seconds/vehicle] Queue length of critical movement(s) [metres] | | |
| Traffic Signal Control | Delay of critical movement(s) [seconds/vehicle] Degree of Saturation [ratio of vehicles to capacity] Average Vehicle Delay [seconds/vehicle] Cycle Length [seconds] Queue length of critical movement(s) [metres] | | |
| Roundabout Control | Delay of critical movement(s) [seconds/vehicle] Degree of Saturation[ratio of vehicles to capacity] Average Vehicle Delay [seconds/vehicle] Queue length of critical movement(s) [metres] | | |

Table A1: Performance Indicators by Control Method

Average Vehicle Delay (AVD)

The AVD is a measure of the operational performance of a road network or an intersection.

AVD is determined globally over a road network or within a cordon during an assignment model run. The AVD exhibited on comparable network models, for analogous peak periods, forms the basis of comparing the operational performance of the road network.

AVD is used in the determination of intersection Level of Service. Generally, the total delay incurred by vehicles through an intersection is averaged to give an indicative delay on any specific approach. Longer delays do occur but only the average over the peak hour period is reported.
Degree of Saturation (DS)

The DS of an intersection is usually taken as the highest ratio of traffic volume on an approach to the intersection compared with its theoretical capacity, and is a measure of the utilisation of available green time. The DS reported is generally of a critical movement through the intersection rather than the DS of the intersection unless equal saturation occurs on all approaches.

For intersections controlled by traffic signals, generally both queue length and delay increase rapidly as DS approaches 1.0. An intersection operates satisfactorily when its DS is kept below 0.875. When the DS exceeds 0.9, extensive queues can be expected.

| LOS | AVD secs | Traffic Signals and Roundabout | Give Way and Stop Sign Priority Control |
|-----|-------------|--|--|
| Α | 1 to 14 | Good operation. | Good operation |
| В | 14 to 28 | Good operation with acceptable delays and spare capacity. | Good operation with acceptable delays and spare capacity. |
| с | 28 to 42 | Satisfactory. | Satisfactory but accident study and operational analysis required. |
| D | 42 to 56 | Operating near capacity. | Near capacity. Accident study and operational analysis required. |
| E | 56 to 70 | Unsatisfactory. Traffic signals incidence will cause excessive delays. Requires additional capacity. Roundabouts require alternative control mode. | At capacity. Requires alternative control mode. |
| F | >70 | Unsatisfactory. Over capacity and unstable operation. | Over capacity. Unstable and unsafe operation. |

Table A2: Qualified Level of Service by Control Method

APPENDIX B - SCATES OUTPUT

Victoria Road Existing – VICX.DAT

SCATES Program Version: 2013 Date: 27-OCT-12 Time: Registered User Name. - Road Delay Solutions Pty Ltd Registered User No. - 0 Data File: VICX VICTORIA ROAD 2010 EXISTING VOLUMES

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| | | 1 | AM PEA | ٩K | | | F | PM PE | ٩K | | | E | BUSINE | ESS | |
|----|------|------|--------|------|------|------|------|-------|------|------|-----|------|--------|------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 494 | 1750 | S | 0 | 0.0 | 481 | 1750 | S | 0 | 0.0 | 102 | 1750 | S | 0 | 0.0 |
| 1T | 1838 | 5880 | Α | 0 | 0 | 1161 | 5880 | Α | 0 | 0 | 7 | 5880 | Α | 72 | 0 |
| 1R | 410 | 3700 | G | | | 322 | 3700 | G | | | 108 | 3700 | G | | |
| 2L | 70 | 1750 | S | | | 229 | 1750 | S | | | 102 | 1750 | S | | |
| 2T | 6 | 3920 | E | | | 6 | 3920 | E | | | 457 | 3920 | E | | |
| 2R | 552 | 3700 | D | | | 589 | 3700 | D | | | 108 | 3700 | D | | |
| ЗL | 468 | 1750 | S | 0 | 0.0 | 423 | 1750 | S | 0 | 0.0 | 102 | 1750 | S | 0 | 0.0 |
| ЗT | 1283 | 5880 | Α | | | 1299 | 5880 | Α | | | 7 | 5880 | Α | | |
| ЗR | 114 | 3700 | G | | | 148 | 3700 | G | | | 108 | 3700 | G | | |
| | | | | | | | | | | | | | | | |

ROAD DELAY SOLUTIONS

| 4L | 25 1750 | D GE | | 52 | 1750 | GE | | | 102 | 1750 | GE | |
|--------|----------|----------|-------|------|--------|-------|------|--------|------|------|------|--------|
| 4T | 6 3920 |) E | | 6 | 3920 | Е | | | 457 | 3920 | Е | |
| 4R | 646 3700 | D C | | 806 | 3700 | D | | | 108 | 3700 | D | |
| Type = | DOD0 | | | Α | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD |
| File = | = VICX | | | 1 | 32 | 4.0 | 0 | 0 | 0 | | 0 | |
| | | | | 2 | 30 | 4.0 | 0 | 0 | 0 | | 0 | |
| TCS = | 110 | | | 3 | 32 | 4.0 | 0 | 0 | 0 | | 0 | |
| | | | | 4 | 5 | 4.0 | 0 | 0 | 0 | | 0 | |
| | PEDES | STRIAN V | OLUME | WAL | <-CLEA | RANCE | Ξ 7 | FRAM D | DATA | PE | DEST | TRAM |
| Арр | P#AM | P#PM | P#B | Wall | K C | lear | | | | FA | СТ | FACT |
| 1 | 50 | 50 | 25 | 6 | 2 | 6 | (|)% | | 5 | 0 | 100 |
| 2 | 50 | 50 | 25 | 6 | 2 | 4 | (|)% | | 5 | 0 | 100 |
| 3 | 50 | 50 | 25 | 6 | 2 | 6 | (|)% | | 5 | 0 | 100 |
| 4 | 0 | 0 | 0 | 0 | 0 | 1 | (|)% | | 1 | 00 | 100 |
| | | | | | | | | | | | | |

APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 Tidal Down Lanes Grade Down Lanes Grade Down Lanes Grade Down Lanes Grade 0 3 0 0 2 0 0 3 0 0 2 0 N Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane LT 9999 1750 LT 9999 1750 LT 9999 1750 LT 9999 1750 T 9999 1960 R 9999 1850 T 9999 1960 TR 9999 1850 1 T 9999 1960 R 35 1850 T 9999 1960 T 9999 1960 2 3 4 5 6 7 8 No Parking No Parking No Parking No Parking
 AM
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 Apprch 0 0 0 0 Depart O File = VICX TCS = 491 Type = COCO _____ APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 DownLanesGradeDownLanesGradeDownLanesGrade06004060040 Tidal Ν Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane L 50 1750 L 9999 1750 L 110 1750 L 65 1750 T 9999 1960 T 9999 3920 T 9999 1960 T 9999 3920 1 2 T 9999 1960 R 9999 1850 T 9999 1960 R 120 1850 T 9999 1960 R 100 1850 3 R 100 1850 4 T 9999 1960 R 70 1850 R 120 1850 5 R 70 1850 6 R 120 1850 7 8 No ParkingNo ParkingNo ParkingNo ParkingAMPMBUSAMPMBUSAMPMBUS000000000000000000000000000 AM PM BUS Apprch 0 0 Depart File = VICX Type = DODO TCS = 110 AM PEAKPM PEAKBUSINESSGT%GT%CLCLGT%GT%CLCLCORDISOLCORDISOLCORDISOLCORDISOLCORDISOL78.978.913913979.779.710510526.826.856562121120.320.373.273.2 Ph G1%G1%G1%CORDISOLCORD78.978.971.121.121.120.3 А В С D dlay dlay Е dlay dlay dlay dlay 0.7 0.7 F G

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AB dlay 3 3 AB dlav 25 25 Sea Stps2.12.1Stps0.70.7DS0.810.811DS0.480.48 Mode 1

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ROAD DELAY SOLUTIONS

| File = VICX | | ay Bay Slip | • | Туре |
|---------------------|---------|-----------------------------------|-----------------------|--------------|
| TCS = 491 | | eq Act Req 5 35 21 11 21 | 0 0 | C0C0 |
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| В | | | | |
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| | | 1 | 33.6 33.6 | |
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| G 19.5 18.8 2.7 1.9 | 15.5 15 | | | |
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| Stps 3.9 4.1 | | Stps 3.8 | 3.8 8 | Stps 1.2 1.2 |
| Mode 1 DS 0.67 0.74 | | | | |
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| TCS = 110 | 1 4 | 5 70 12 | 50 | DODO |
| | 2 0 | 61 100 | | |
| | 3 | 8 120 24 | 110 | |
| | 4 | 16 | 65 | |
| | Bay | s if all into | ersections are o | optimised |
| | | | | |

| тсѕ | = | 491 I | solate | ed Opei | ration | Degree | e of Sa | turati | on for | PM Pe | eak VIO | Х | |
|-----|---|-------|--------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.39 | 80 | 0 | 5 | 0 | 6 | 0.39 | 80 | 0 | 5 | 0 | 6 |
| 1 | Т | 0.64 | 80 | 3 | 752 | 13 | 42 | 0.64 | 80 | 3 | 752 | 13 | 42 |
| 1 | R | 0.81 | 80 | 1 | 67 | 1 | 6 | 0.81 | 80 | 1 | 67 | 1 | 6 |
| 2 | L | 0.62 | 17 | 1 | 41 | 1 | 30 | 0.62 | 17 | 1 | 41 | 1 | 30 |
| 2 | Т | 0.62 | 17 | 1 | 109 | 3 | 30 | 0.62 | 17 | 1 | 109 | 3 | 30 |
| 2 | R | 0.81 | 17 | 3 | 167 | 5 | 30 | 0.81 | 17 | 3 | 167 | 5 | 30 |
| 3 | L | 0.53 | 80 | 0 | 59 | 1 | 36 | 0.53 | 80 | 0 | 59 | 1 | 36 |
| 3 | Т | 0.53 | 80 | 3 | 760 | 15 | 36 | 0.53 | 80 | 3 | 760 | 15 | 36 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.26 | 17 | 0 | 13 | 0 | 18 | 0.26 | 17 | 0 | 13 | 0 | 18 |
| 4 | Т | 0.26 | 17 | 1 | 93 | 3 | 18 | 0.26 | 17 | 1 | 93 | 3 | 18 |
| 4 | R | 0.31 | 17 | 0 | 12 | 0 | 18 | 0.31 | 17 | 0 | 12 | 0 | 18 |
| INT | | 0.81 | 105 | | | | | 0.81 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 491 Pedestrian - Vehicle Delay PM Peak File = VICX Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|-------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 17 | 0.0 | 4.3 | | | | 17 | 0.0 | 4.3 |
| 1 | Т | 40 | 0.5 | 46.7 | 1786 | 2.9 | 5.9 | 40 | 0.5 | 46.7 | 1786 | 2.9 | 5.9 |
| 1 | R | | | | 75 | 0.9 | 41.8 | | | | 75 | 0.9 | 41.8 |
| 2 | L | | | | 49 | 0.6 | 40.8 | | | | 49 | 0.6 | 40.8 |
| 2 | Т | 0 | 0.0 | | 130 | 1.5 | 40.8 | 0 | 0.0 | | 130 | 1.5 | 40.8 |
| 2 | R | | | | 161 | 2.7 | 60.7 | | | | 161 | 2.7 | 60.7 |
| 3 | L | | | | 163 | 0.2 | 5.1 | | | | 163 | 0.2 | 5.1 |
| 3 | Т | 0 | 0.0 | | 2105 | 3.0 | 5.1 | 0 | 0.0 | | 2105 | 3.0 | 5.1 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 17 | 0.2 | 38.3 | | | | 17 | 0.2 | 38.3 |
| 4 | Т | 0 | 0.0 | | 118 | 1.3 | 38.3 | 0 | 0.0 | | 118 | 1.3 | 38.3 |
| 4 | R | | | | 16 | 0.2 | 42.3 | | | | 16 | 0.2 | 42.3 |
| INT | | 40 | 1 | 46.7 | 4637 | 13 | 10.4 | 40 | 1 | 46.7 | 4637 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| TCS | = | 491 I | Pedestr | ian · | - Vehio | cle Del | .ay - 8 | Stops F | M Peak | File | = VICX | |
|-----|---|-------|---------|--------|---------|---------|---------|---------|---------|------|--------|----|
| | | | - Delay | s & S1 | tops at | fter Co | ordir | nated E | Evaluat | ion | | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 17 | 0.0 | 1.2 | 0 | 0.0 | Α | 0 | 6 |
| 1 | Т | 40 | 0.5 | 46.7 | 1786 | 0.6 | 1.2 | 0 | 0.0 | Α | 0 | 6 |
| 1 | R | | | | 75 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 2 | L | | | | 49 | 0.6 | 40.8 | 41 | 0.8 | С | 1 | 12 |
| 2 | Т | 0 | 0.0 | | 130 | 1.5 | 40.8 | 109 | 0.8 | С | 3 | 30 |
| 2 | R | | | | 161 | 2.7 | 60.7 | 167 | 1.0 | Е | 5 | 30 |
| 3 | L | | | | 163 | 0.4 | 8.0 | 57 | 0.4 | А | 1 | 6 |
| 3 | Т | 0 | 0.0 | | 2105 | 4.7 | 8.0 | 738 | 0.4 | А | 15 | 36 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 17 | 0.2 | 38.3 | 13 | 0.8 | С | 0 | 6 |
| 4 | Т | 0 | 0.0 | | 118 | 1.3 | 38.3 | 93 | 0.8 | С | 3 | 12 |
| 4 | R | | | | 16 | 0.2 | 42.3 | 12 | 0.8 | D | 0 | 6 |
| INT | | 40 | 1 | 46.7 | 4637 | 12 | 9.3 | 1230 | 0.3 | Α | | |

TCS = 491 Isolated Operation Degree of Saturation for Business Peak VICX --- Co-ordinated Cycle Length --- Isolated Cycle Length -----GT Delay Stops Queue Metre DS DS GT Delay Stops Queue Metre A M 6 0.30 0.30 1 L Т 0.02 6 0.02 R 0.13 6 0.13 L 0.48 24 0.48 Т 0.48 24 0.48 R 0.24 6 0.24 6 0.30 0.30 L 3 T 0.01 6 0.01 3 R 4 L 0.43 24 0.43 0 43 4 T 0.43 18 0.43 1 194 2 18 4 R 0.46 24 0.46 INT 0.48 0.48

| TCS | = | 491 | Pedestr | ian | | cle Dela solated | - | | Peak F | ile = | VICX | | |
|-----|---|------|---------|-------|------|---------------------|------|------|---------|--------|--------|---------|------|
| | | | Co-ordi | nated | | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 102 | 0.5 | 19.2 | | | | 102 | 0.5 | 19.2 |
| 1 | Т | 20 | 0.1 | 22.3 | 7 | 0.0 | 18.1 | 20 | 0.1 | 22.3 | 7 | 0.0 | 18.1 |
| 1 | R | | | | 36 | 0.2 | 18.1 | | | | 36 | 0.2 | 18.1 |
| 2 | L | | | | 102 | 0.1 | 4.7 | | | | 102 | 0.1 | 4.7 |
| 2 | Т | 0 | 0.0 | | 457 | 0.6 | 4.7 | 0 | 0.0 | | 457 | 0.6 | 4.7 |
| 2 | R | | | | 36 | 0.2 | 22.4 | | | | 36 | 0.2 | 22.4 |
| 3 | L | | | | 102 | 0.5 | 19.2 | | | | 102 | 0.5 | 19.2 |
| 3 | Т | 0 | 0.0 | | 7 | 0.0 | 18.1 | 0 | 0.0 | | 7 | 0.0 | 18.1 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 102 | 0.1 | 4.5 | | | | 102 | 0.1 | 4.5 |
| 4 | Т | 0 | 0.0 | | 457 | 0.6 | 4.5 | 0 | 0.0 | | 457 | 0.6 | 4.5 |
| 4 | R | | | | 36 | 0.2 | 22.9 | | | | 36 | 0.2 | 22.9 |
| INT | | 20 | 0 | 22.3 | 1444 | 3 | 8.0 | 20 | 0 | 22.3 | 1444 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 491 F | | | | | 2 | • | | | File = | |
|-----|---|-------|---------|---------|--------|---------|--------|---------|--------|-----|--------|----|
| | | | - Delay | 's & St | ops at | fter Co | -ordir | nated E | valuat | ion | | |
| Α | Μ | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 102 | 0.0 | 0.2 | 0 | 0.0 | Α | 0 | 6 |
| 1 | Т | 20 | 0.1 | 22.3 | 7 | 0.0 | 0.2 | 0 | 0.0 | Α | 0 | 6 |
| 1 | R | | | | 36 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 2 | L | | | | 102 | 0.1 | 4.7 | 46 | 0.4 | Α | 1 | 6 |
| 2 | Т | 0 | 0.0 | | 457 | 0.6 | 4.7 | 205 | 0.4 | Α | 2 | 24 |
| 2 | R | | | | 36 | 0.2 | 22.4 | 28 | 0.8 | В | 0 | 6 |
| 3 | L | | | | 102 | 0.0 | 0.4 | 2 | 0.0 | Α | 0 | 6 |
| 3 | Т | 0 | 0.0 | | 7 | 0.0 | 0.4 | 0 | 0.0 | Α | 0 | 6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 102 | 0.1 | 4.5 | 43 | 0.4 | Α | 1 | 6 |
| 4 | Т | 0 | 0.0 | | 457 | 0.6 | 4.5 | 194 | 0.4 | Α | 2 | 18 |
| 4 | R | | | | 36 | 0.2 | 22.9 | 29 | 0.8 | В | 0 | 6 |
| INT | | 20 | 0 | 22.3 | 1444 | 2 | 4.7 | 548 | 0.4 | Α | | |
| | | | | | | | | | | | | |

| тсѕ | = | 491 I | solate | ed Oper | ration | Degree | e of Sa | uturati | on fo | r AM Pe | eak VI | сх | |
|-----|---|-------|--------|---------|--------|--------|---------|---------|-------|---------|---------|---------|-------|
| | | C | o-ordi | inated | Cycle | Lengtl | h | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.34 | 106 | 0 | 4 | 0 | 6 | 0.34 | 106 | 0 | 4 | 0 | 6 |
| 1 | Т | 0.90 | 106 | 10 | 1756 | 25 | 84 | 0.90 | 106 | 10 | 1756 | 25 | 84 |
| 1 | R | 0.72 | 106 | 1 | 60 | 1 | 6 | 0.72 | 106 | 1 | 60 | 1 | 6 |
| 2 | L | 0.77 | 25 | 1 | 31 | 1 | 60 | 0.77 | 25 | 1 | 31 | 1 | 60 |
| 2 | Т | 0.77 | 25 | 4 | 192 | 7 | 60 | 0.77 | 25 | 4 | 192 | 7 | 60 |
| 2 | R | 0.82 | 25 | 4 | 167 | 6 | 42 | 0.82 | 25 | 4 | 167 | 6 | 42 |
| 3 | L | 0.47 | 106 | 0 | 43 | 1 | 42 | 0.47 | 106 | 0 | 43 | 1 | 42 |
| 3 | Т | 0.47 | 106 | 3 | 635 | 18 | 42 | 0.47 | 106 | 3 | 635 | 18 | 42 |

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Page | 80

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24

24

TCS = 491 Pedestrian - Vehicle Delay AM Peak File = VICX Isolated Operation --- Co-ordinated Cycle Length --- Isolated Cycle Length -----A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh Delay Aver 14 0.0 5.4 14 0.0 5.4 1 L 40 0.7 63.6 2525 10.1 14.4 74 1.0 46.8 1 T 40 0.7 63.6 2525 10.1 14.4 1 R 74 1.0 46.8 2 L 0.6 60.8 34 0.6 60.8 34 0 0.0 3.5 59.7 2 T 0.0 212 212 3.5 59.7 2 R 3.5 76.5 3.5 76.5 166 166 3 L 0.2 6.2 127 0.2 6.2 127 3 T 0 0.0 1896 3.3 6.2 0 0.0 1896 3.3 6.2 3 R 4 L 51 0.7 49.2 51 0.7 49.2 4 T 0.0 122 1.7 49.2 0 0.0 122 1.7 49.2 4 R 25 0.4 60.8 25 0.4 60.8 40 INT 1 63.6 5246 25 17.1 40 1 63.6 5246 0 0.0

| TCS | = | 491 I | Pedestr | ian - | • Vehi | cle Del | .ay - 9 | Stops A | M Peak | File = | = VICX | |
|-----|---|-------|---------|---------|--------|---------|---------|---------|--------|--------|--------|----|
| | | | - Delay | 's & St | tops a | fter Co | -ordi | nated E | valuat | ion | | |
| А | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 14 | 0.0 | 2.6 | 0 | 0.0 | Α | 0 | 6 |
| 1 | Т | 40 | 0.7 | 63.6 | 2525 | 1.8 | 2.6 | 0 | 0.0 | Α | 0 | 6 |
| 1 | R | | | | 74 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 2 | L | | | | 34 | 0.6 | 60.8 | 31 | 0.9 | Е | 1 | 12 |
| 2 | Т | 0 | 0.0 | | 212 | 3.5 | 59.7 | 192 | 0.9 | Е | 7 | 60 |
| 2 | R | | | | 166 | 3.5 | 76.5 | 167 | 1.0 | F | 6 | 42 |
| 3 | L | | | | 127 | 0.0 | 0.5 | 3 | 0.0 | Α | 0 | 6 |
| 3 | Т | 0 | 0.0 | | 1896 | 0.3 | 0.5 | 46 | 0.0 | А | 2 | 6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 51 | 0.7 | 49.2 | 40 | 0.8 | D | 2 | 6 |
| 4 | Т | 0 | 0.0 | | 122 | 1.7 | 49.2 | 95 | 0.8 | D | 4 | 24 |
| 4 | R | | | | 25 | 0.4 | 60.8 | 20 | 0.8 | Е | 1 | 6 |
| INT | | 40 | 1 | 63.6 | 5246 | 13 | 8.6 | 593 | 0.1 | А | | |
| | | | | | | | | | | | | |

| TCS | = | 110 I | solate | ed Oper | ration | Degree | e of Sa | iturati | on foi | r PM Pe | eak VIC | X | |
|-----|---|-------|--------|---------|--------|--------|---------|---------|--------|---------|---------|---------|-------|
| | | C | o-ordi | inated | Cycle | Lengtl | n | | Isola | ated Cy | /cle Le | ength - | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.30 | 97 | 0 | 43 | 1 | 12 | 0.30 | 97 | 0 | 43 | 1 | 12 |
| 1 | Т | 0.55 | 38 | 9 | 834 | 22 | 48 | 0.55 | 38 | 9 | 834 | 22 | 48 |
| 1 | R | 0.75 | 12 | 4 | 290 | 9 | 30 | 0.75 | 12 | 4 | 290 | 9 | 30 |
| 2 | L | 0.30 | 46 | 1 | 133 | 4 | 24 | 0.30 | 46 | 1 | 133 | 4 | 24 |
| 2 | Т | 0.02 | 15 | 0 | 5 | 0 | 6 | 0.02 | 15 | 0 | 5 | 0 | 6 |
| 2 | R | 0.75 | 22 | 6 | 503 | 14 | 42 | 0.75 | 22 | 6 | 503 | 14 | 42 |
| 3 | L | 0.29 | 89 | 0 | 78 | 2 | 12 | 0.29 | 89 | 0 | 78 | 2 | 12 |
| 3 | Т | 0.75 | 31 | 12 | 1056 | 27 | 54 | 0.75 | 31 | 12 | 1056 | 27 | 54 |
| 3 | R | 0.75 | 6 | 2 | 143 | 4 | 18 | 0.75 | 6 | 2 | 143 | 4 | 18 |
| 4 | L | 0.12 | 26 | 0 | 36 | 1 | 12 | 0.12 | 26 | 0 | 36 | 1 | 12 |
| 4 | Т | 0.02 | 21 | 0 | 4 | 0 | 6 | 0.02 | 21 | 0 | 4 | 0 | 6 |
| 4 | R | 0.75 | 31 | 8 | 661 | 17 | 54 | 0.75 | 31 | 8 | 661 | 17 | 54 |
| INT | | 0.75 | 105 | | | | | 0.75 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay PM Peak File = VICX Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 481 | 0.1 | 0.4 | | | | 481 | 0.1 | 0.4 |
| 1 | Т | 50 | 0.6 | 46.7 | 1161 | 8.7 | 26.9 | 50 | 0.6 | 46.7 | 1161 | 8.7 | 26.9 |
| 1 | R | | | | 322 | 4.3 | 47.6 | | | | 322 | 4.3 | 47.6 |
| 2 | L | | | | 229 | 1.2 | 18.9 | | | | 229 | 1.2 | 18.9 |
| 2 | Т | 50 | 0.6 | 46.7 | 6 | 0.1 | 38.7 | 50 | 0.6 | 46.7 | 6 | 0.1 | 38.7 |
| 2 | R | | | | 589 | 6.5 | 39.6 | | | | 589 | 6.5 | 39.6 |
| 3 | L | | | | 423 | 0.2 | 1.7 | | | | 423 | 0.2 | 1.7 |
| 3 | Т | 50 | 0.6 | 46.7 | 1299 | 12.0 | 33.4 | 50 | 0.6 | 46.7 | 1299 | 12.0 | 33.4 |
| 3 | R | | | | 148 | 2.3 | 56.0 | | | | 148 | 2.3 | 56.0 |
| 4 | L | | | | 52 | 0.4 | 30.3 | | | | 52 | 0.4 | 30.3 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 33.5 | 0 | 0.0 | | 6 | 0.1 | 33.5 |
| 4 | R | | | | 806 | 7.6 | 34.1 | | | | 806 | 7.6 | 34.1 |
| INT | | 150 | 2 | 46.7 | 5522 | 43 | 28.3 | 150 | 2 | 46.7 | 5522 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| TCS | = | 110 F | | | | | | | | File = ion | | | |
|-----|---|-------|-----|------|------|------|------|------|-----|---------------|----|----|--|
| А | М | Peds | - | | | | | | | | | | |
| 1 | L | | , | | 481 | 0.0 | 0.0 | ́о | 0.0 | А | 0 | 6 | |
| 1 | Т | 50 | 0.6 | 46.7 | 1161 | 13.4 | 41.7 | 778 | 0.7 | С | 22 | 48 | |
| 1 | R | | | | 322 | 0.4 | 5.0 | 9 | 0.0 | А | 0 | 6 | |
| 2 | L | | | | 229 | 1.2 | 18.9 | 133 | 0.6 | В | 4 | 24 | |
| 2 | Т | 50 | 0.6 | 46.7 | 6 | 0.1 | 38.7 | 5 | 0.8 | С | 0 | 6 | |
| 2 | R | | | | 589 | 6.5 | 39.6 | 503 | 0.9 | С | 14 | 42 | |
| 3 | L | | | | 423 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | Т | 50 | 0.6 | 46.7 | 1299 | 2.4 | 6.7 | 0 | 0.0 | А | 0 | 6 | |
| 3 | R | | | | 148 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 4 | L | | | | 52 | 0.4 | 30.3 | 36 | 0.7 | С | 1 | 12 | |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 33.5 | 4 | 0.7 | С | 0 | 6 | |
| 4 | R | | | | 806 | 7.6 | 34.1 | 661 | 0.8 | С | 17 | 54 | |
| INT | | 150 | 2 | 46.7 | 5522 | 32 | 21.0 | 2129 | 0.4 | В | | | |
| | | | | | | | | | | | | | |

| тсѕ | = | 110 I | solate | ed Opei | ration | Degree | e of S | Saturati | on fo | - Busir | ness Pe | eak VI(| x |
|-----|---|-------|--------|---------|--------|--------|--------|----------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | h | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | e DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.10 | 32 | 0 | 41 | 1 | 6 | 6 0.10 | 32 | 0 | 41 | 1 | 6 |
| 1 | Т | 0.00 | 15 | 0 | 5 | 0 | 6 | 0.00 | 15 | 0 | 5 | 0 | 6 |
| 1 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 2 | L | 0.07 | 47 | 0 | 16 | 0 | 6 | 0.07 | 47 | 0 | 16 | 0 | 6 |
| 2 | Т | 0.44 | 15 | 2 | 342 | 5 | 18 | 0.44 | 15 | 2 | 342 | 5 | 18 |
| 2 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 3 | L | 0.10 | 32 | 0 | 41 | 1 | 6 | 6 0.10 | 32 | 0 | 41 | 1 | 6 |
| 3 | Т | 0.00 | 15 | 0 | 5 | 0 | 6 | 0.00 | 15 | 0 | 5 | 0 | 6 |
| 3 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 4 | L | 0.15 | 22 | 0 | 60 | 1 | 6 | 0.15 | 22 | 0 | 60 | 1 | 6 |
| 4 | Т | 0.51 | 13 | 2 | 359 | 5 | 18 | 0.51 | 13 | 2 | 359 | 5 | 18 |
| 4 | R | 0.40 | 5 | 1 | 92 | 2 | 6 | 6 0.40 | 5 | 1 | 92 | 2 | 6 |
| INT | | 0.51 | 56 | | | | | 0.51 | 56 | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay Business Peak File = VICX Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 102 | 0.2 | 5.3 | | | | 102 | 0.2 | 5.3 |
| 1 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 |
| 1 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 2 | L | | | | 102 | 0.0 | 0.8 | | | | 102 | 0.0 | 0.8 |
| 2 | Т | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 |
| 2 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 3 | L | | | | 102 | 0.2 | 5.3 | | | | 102 | 0.2 | 5.3 |
| 3 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 |
| 3 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 4 | L | | | | 102 | 0.3 | 11.2 | | | | 102 | 0.3 | 11.2 |
| 4 | Т | 0 | 0.0 | | 457 | 2.4 | 18.8 | 0 | 0.0 | | 457 | 2.4 | 18.8 |
| 4 | R | | | | 108 | 0.7 | 24.2 | | | | 108 | 0.7 | 24.2 |
| INT | | 75 | 0 | 22.3 | 1768 | 8 | 16.6 | 75 | 0 | 22.3 | 1768 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay - Stops Business Peak File = VICX ----- Delays & Stops after Co-ordinated Evaluation-----A M Peds Delay Aver Vehs Delay Aver Stops Aver LOS 1 L 102 0.0 0.0 0 0.0 А 0 6 0.3 25 0.2 22.3 0.0 0.4 2 А 0 6 1 T 7 1 R 108 0.2 5.0 2 0.0 А 0 6 2 102 0 6 L 0.0 0.8 16 0.2 А 2 Т 25 0.2 22.3 457 2.2 17.1 342 0.7 В 5 18 2 R 108 0.7 24.1 91 0.8 В 1 6 3 L 0.0 0 6 102 0.0 0 0.0 А 3 T 0.2 22.3 25 0.0 0.0 0 0.0 А 0 6 7 0.0 3 R 108 0.0 0 6 0 0.0 А 4 L 102 0.3 11.2 60 0.6 А 1 6 4 T 0.0 457 18.8 359 0.8 18 0 2.4 В 5 4 R 108 0.7 24.2 92 0.9 В 1 6 INT 75 0 22.3 1768 963 0.5 7 13.2 А

TCS = 110 Isolated Operation Degree of Saturation for AM Peak VICX --- Co-ordinated Cycle Length --- Isolated Cycle Length -----GT Delay Stops Queue Metre DS DS GT Delay Stops Queue Metre A M 1 12 0.30 0.30 1 L 0 37 0.67 78 0.74 13 1392 Т R 0.67 42 0.74 L 0.08 0.08 Т 0.03 6 0.02 6 473 R 0.67 54 0.74 3 L 24 0.33 0 108 0.34 3 T 0.63 66 0.68 11 1005 3 R 0.67 18 0.65 2 101 4 L 0.09 6 0.07 5 4 T 0.02 6 0.02 4 R 0.67 8 520 60 0.74 7 544 INT 0.67 139 0.74 _____

| TCS | = | 110 | Pedestr | ian · | - Vehi | cle Dela | ay AM | Peak | File = | VICX | | | |
|-----|---|------|---------|--------|--------|----------|-------|-------|---------|--------|--------|---------|------|
| | | | | | Is | solated | Opera | ation | | | | | |
| | | | Co-ordi | inated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 494 | 0.0 | 0.3 | | | | 494 | 0.0 | 0.3 |
| 1 | Т | 50 | 0.9 | 63.6 | 1838 | 14.6 | 28.5 | 50 | 0.6 | 46.7 | 1838 | 13.0 | 25.5 |
| 1 | R | | | | 410 | 6.2 | 54.3 | | | | 410 | 5.1 | 44.4 |
| 2 | L | | | | 70 | 0.4 | 18.4 | | | | 70 | 0.3 | 13.0 |
| 2 | Т | 50 | 0.9 | 63.6 | 6 | 0.1 | 55.5 | 50 | 0.6 | 46.7 | 6 | 0.1 | 38.7 |
| 2 | R | | | | 552 | 7.5 | 49.2 | | | | 552 | 6.2 | 40.4 |
| 3 | L | | | | 468 | 0.5 | 3.6 | | | | 468 | 0.3 | 2.5 |
| 3 | Т | 50 | 0.9 | 63.6 | 1283 | 13.4 | 37.7 | 50 | 0.6 | 46.7 | 1283 | 11.1 | 31.1 |
| 3 | R | | | | 114 | 2.1 | 65.2 | | | | 114 | 1.6 | 49.1 |
| 4 | L | | | | 25 | 0.3 | 49.5 | | | | 25 | 0.2 | 33.9 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 52.6 | 0 | 0.0 | | 6 | 0.1 | 37.3 |
| 4 | R | | | | 646 | 8.2 | 45.9 | | | | 646 | 6.8 | 37.9 |
| INT | | 150 | 3 | 63.6 | 5912 | 53 | 32.5 | 150 | 2 | 46.7 | 5912 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| | | | - Delay | /s & S1 | tops at | fter Co | -ordir | nated E | valuat | ion | | |
|-----|---|------|---------|---------|---------|---------|--------|---------|--------|-----|----|----|
| А | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 494 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 1 | Т | 50 | 0.9 | 63.6 | 1838 | 40.9 | 80.0 | 1909 | 1.0 | F | 38 | 78 |
| 1 | R | | | | 410 | 0.6 | 5.0 | 16 | 0.0 | А | 1 | 6 |
| 2 | L | | | | 70 | 0.4 | 18.4 | 33 | 0.5 | В | 1 | 12 |
| 2 | Т | 50 | 0.9 | 63.6 | 6 | 0.1 | 55.5 | 5 | 0.8 | D | 0 | 6 |
| 2 | R | | | | 552 | 7.5 | 49.2 | 453 | 0.8 | D | 17 | 54 |
| 3 | L | | | | 468 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 3 | Т | 50 | 0.9 | 63.6 | 1283 | 2.7 | 7.5 | 0 | 0.0 | А | 0 | 6 |
| 3 | R | | | | 114 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 4 | L | | | | 25 | 0.3 | 49.5 | 19 | 0.8 | D | 1 | 6 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 52.6 | 5 | 0.8 | D | 0 | 6 |
| 4 | R | | | | 646 | 8.2 | 45.9 | 520 | 0.8 | D | 18 | 60 |
| INT | | 150 | 3 | 63.6 | 5912 | 61 | 37.0 | 2960 | 0.5 | С | | |

Victoria Road Future without Development - VICB.DAT

SCATES Program Version: 2013 Date: 02-NOV-12 Time: Registered User Name. - Road Delay Solutions Pty Ltd Registered User No. - 0 Data File: VICB VICTORIA ROAD 2031 BITZIOS BASE VOLUMES

| | | | AM PEA | ٩K | | | F | PM PEA | ٨K | | | E | BUSINE | ESS | |
|-------|-------|-------|--------|------|------|------|------|--------|------|--------|------|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 18 | 1750 | Α | 0 | 0.0 | 19 | 1750 | Α | 0 | 0.0 | 102 | 1750 | Α | 0 | 0.0 |
| 1T | 2917 | 3710 | Α | | | 1853 | 3710 | Α | | | 7 | 3710 | Α | | |
| 1R | 89 | 1850 | S | | | 80 | 1850 | S | | | 36 | 1850 | S | | |
| 2L | 28 | 1750 | В | | | 42 | 1750 | В | | | 102 | 1750 | В | | |
| 2T | 171 | 1750 | В | | | 112 | 1750 | В | | | 457 | 1750 | В | | |
| 2R | 132 | 1850 | S | | | 139 | 1850 | S | | | 36 | 1850 | S | | |
| ЗL | 123 | 1750 | Α | 0 | 0.0 | 145 | 1750 | Α | 0 | 0.0 | 102 | 1750 | Α | 0 | 0.0 |
| ЗT | 1848 | 5670 | Α | 0 | 982 | 1868 | 5670 | Α | 0 | 157 | 7 | 5670 | Α | 0 | 108 |
| ЗR | 0 | 0 | S | | | 0 | 0 | S | | | 0 | 0 | S | | |
| 4L | 59 | 1750 | В | | | 41 | 1750 | В | | | 102 | 1750 | В | | |
| 4T | 141 | 3600 | В | | | 287 | 3600 | В | | | 457 | 1850 | В | | |
| 4R | | 1850 | S | | | 42 | 1850 | S | | | 36 | 1850 | S | | |
| Туре | = COO | 0 | | | | А | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |
| File | = VIC | СВ | | | | 1 | 22 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| | | | | | | 2 | 5 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| TCS : | = 491 | 1 | | | | 3 | 5 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| | | | | | | 4 | 24 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| | F | PEDES | TRIAN | VOLU | ME | | | ARANCE | = - | TRAM [| DATA | PE | EDEST | TRA | M |
| Арр | P## | ١M | P#PM | Pi | #B | Walk | ((| Clear | | | | FÆ | ACT | FAC | т |
| 1 | 40 |) | 40 | : | 20 | 6 | - | 16 | (|)% | | Ę | 50 | 10 | 0 |
| 2 | 0 | | 0 | (| 0 | 0 | (| C | (|)% | | - | 100 | 10 | 0 |
| 3 | 0 | | 0 | (| 0 | 0 | (|) | (|)% | | | 100 | 10 | 0 |
| 4 | 0 | | 0 | (| 0 | 6 | | 18 | (|)% | | Ę | 50 | 10 | 0 |
| | | | | | | | | | | | | | | | - |

| | | | AM PEA | ٩K | | | F | PM PEA | ٩K | | | E | BUSINE | ESS | |
|------|-------|------|--------|------|------|------|------|--------|------|------|-----|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 337 | 1750 | S | 0 | 0.0 | 799 | 1750 | S | 0 | 0.0 | 102 | 1750 | S | 0 | 0.0 |
| 1T | 1585 | 5880 | Α | 0 | 484 | 599 | 5880 | Α | 0 | 89 | 7 | 5880 | Α | 72 | 0 |
| 1R | 702 | 3700 | G | | | 546 | 3700 | G | | | 108 | 3700 | G | | |
| 2L | 598 | 1750 | S | | | 235 | 1750 | S | | | 102 | 1750 | S | | |
| 2T | 6 | 3920 | Е | | | 6 | 3920 | E | | | 457 | 3920 | E | | |
| 2R | 236 | 3700 | D | | | 809 | 3700 | D | | | 108 | 3700 | D | | |
| 3L | 449 | 1750 | S | 0 | 0.0 | 489 | 1750 | S | 0 | 0.0 | 102 | 1750 | S | 0 | 0.0 |
| 3T | 1787 | 5880 | Α | | | 1239 | 5880 | Α | | | 7 | 5880 | Α | | |
| ЗR | 109 | 3700 | G | | | 176 | 3700 | G | | | 108 | 3700 | G | | |
| 4L | 22 | 1750 | GE | | | 61 | 1750 | GE | | | 102 | 1750 | GE | | |
| 4T | 6 | 3920 | Е | | | 6 | 3920 | Е | | | 457 | 3920 | E | | |
| 4R | 568 | 3700 | D | | | 696 | 3700 | D | | | 108 | 3700 | D | | |
| Туре | = D0[| 00 | | | | Α | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |

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ROAD DELAY SOLUTIONS

| File = | VICB | | | 1 | 32 4.0 | 0 | 0 | 0 | 0 | |
|--------|------|----------|-------|-------|-----------|------|--------|----|--------|------|
| | | | | 2 | 30 4.0 | 0 | 0 | 0 | 0 | |
| TCS = | 110 | | | 3 | 32 4.0 | 0 | 0 | 0 | 0 | |
| | | | | 4 | 5 4.0 | 0 | 0 | 0 | 0 | |
| | PEDE | STRIAN V | OLUME | WALK- | CLEARANCE | E TF | RAM DA | TA | PEDEST | TRAM |
| Арр | P#AM | P#PM | P#B | Walk | Clear | | | | FACT | FACT |
| 1 | 50 | 50 | 25 | 6 | 26 | 09 | б | | 50 | 100 |
| 2 | 50 | 50 | 25 | 6 | 24 | 09 | б | | 50 | 100 |
| 3 | 50 | 50 | 25 | 6 | 26 | 09 | б | | 50 | 100 |
| 4 | 0 | 0 | 0 | 0 | 0 | 09 | б | | 100 | 100 |
| | | | | | | | | | | |

APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 Tidal Down Lanes Grade Down Lanes Grade Down Lanes Grade Down Lanes Grade 0 3 0 0 2 0 0 3 0 0 2 0 N Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane LT 9999 1750 LT 9999 1750 LT 9999 1750 LT 9999 1750 T 9999 1960 R 9999 1850 T 9999 1960 TR 9999 1850 1 T 9999 1960 R 35 1850 T 9999 1960 TR 9999 1850 T 9999 1960 2 3 4 5 6 7 8 No Parking No Parking No Parking No Parking
 AM
 PM
 BUS
 AM
 AM
 AM
 AM
 Apprch 0 0 0 0 Depart O File = VICB TCS = 491 Type = COCO _____ APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 DownLanesGradeDownLanesGradeDownLanesGrade06004060040 Tidal N Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane L 50 1750 L 9999 1750 L 110 1750 L 65 1750 T 9999 1960 T 9999 3920 T 9999 1960 T 9999 3920 1 2 R 100 1850 T 9999 1960 R 9999 1850 R 100 1850 T 9999 1960 R 120 1850 T 9999 1960 3 4 T 9999 1960 R 70 1850 R 120 1850 5 R 70 1850 6 R 120 1850 7 8 NoParkingNoParkingNoParkingAMPMBUSAMPMBUSAMPMBUS00000000000000000000000000000 AM PM BUS 0 Apprch 0 Depart File = VICB Type = D0D0 TCS = 110 AM PEAK PM PEAK BUSINESS GT% GT% CL CL GT% GT% CL CL GT% GT% CL CL CL Ph CORD ISOL
 CORD ISOL
 CORD ISOL CORD ISOL
 CORD ISOL CORD ISOL
 CORD ISOL
 CORD ISOL

 A
 82.9
 82.9
 140
 140
 73.2
 73.2
 105
 105
 26.8
 26.8
 56
 56

 B
 17
 1
 17
 1
 73
 2
 73
 2
 B 17.1 17.1 26.8 26.8 73.2 73.2 С D Е dlay dlay 0.1 0.1 AB dlay 3 3 Stos 0 7 5 dlay dlay dlay dlay dlay 0.7 0.7 0.5 0.5 AB dlay 47 47 AB dlay 18 18 Stps 4.2 4.2 Stps 2.5 2.5 F G Seq

 Stps
 4.2
 4.2
 Stps
 2.5
 2.5

 DS
 0.99
 0.99
 1
 DS
 0.77
 0.77
 1

 A
 Bay
 Bay
 Slip
 Slip
 Slip

Mode 1 DS 0.48 0.48 File = VICB Type

ROAD DELAY SOLUTIONS

| TCS = 491 | 1 21 3 2 3 4 13 | t Req Act 5 27 O 11 O 27 O 0 18 O all intersections ar | COCO e optimised |
|----------------------------|--------------------------|---|---------------------|
| | | | |
| AM PEAK | PM F | EAK | BUSINESS |
| Ph GT% GT% CL CL | GT% GT% | CL CL GT% GT | % CL CL |
| CORD ISOL CORD ISOL | | | |
| A 36.8 37.6 140 113 | 29.5 29.5 | 105 105 34.8 34. | 8 56 56 |
| В | | | |
| C | ~ ~ ~ ~ ~ | | • |
| D 20.0 20.8 E 13.6 16.8 | 30.5 30.5 | 15.8 15. | 8 |
| E 13.6 16.8 | 18.1 18.1 | 33.6 33. | 6 |
| F dlay dlay | | dlay dlay | diay diay |
| G 29.6 24.8 2.7 2.1 | | | |
| Seq ADEG dlay 68 57 | | | |
| Stps 4.6 4.6 | Stp | s 3.8 3.8 | Stps 1.2 1.2 |
| Mode 1 DS 0.89 0.89 | | | |
| File = VICB | • | y Slip Slip | Туре |
| TCS = 110 | | t Req Act O 20 50 | DODO |
| 105 - 110 | | | DODO |
| | 2 102 10 | - | |
| | 3 29 12 4 | 0 46 110 20 65 | |
| | • | all intersections ar | o optimicod |
| | Dayo 11 | INCELSECTIONS al | e oprimised |
| | | | |

| TCS | = | 491 I | solat | ed Opei | ration | Degree | e of Sa | turati | on foi | ° PM P€ | eak VIC | СВ | |
|-----|---|-------|-------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord | inated | Cycle | Lengt | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.46 | 73 | 0 | 8 | 0 | 6 | 0.46 | 73 | 0 | 8 | 0 | 6 |
| 1 | Т | 0.73 | 73 | 5 | 1032 | 17 | 54 | 0.73 | 73 | 5 | 1032 | 17 | 54 |
| 1 | R | 0.77 | 73 | 1 | 70 | 1 | 6 | 0.77 | 73 | 1 | 70 | 1 | 6 |
| 2 | L | 0.38 | 24 | 0 | 32 | 1 | 24 | 0.38 | 24 | 0 | 32 | 1 | 24 |
| 2 | Т | 0.38 | 24 | 1 | 85 | 3 | 24 | 0.38 | 24 | 1 | 85 | 3 | 24 |
| 2 | R | 0.77 | 24 | 2 | 138 | 4 | 24 | 0.77 | 24 | 2 | 138 | 4 | 24 |
| 3 | L | 0.51 | 73 | 0 | 62 | 1 | 42 | 0.51 | 73 | 0 | 62 | 1 | 42 |
| 3 | Т | 0.51 | 73 | 4 | 799 | 17 | 42 | 0.51 | 73 | 4 | 799 | 17 | 42 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.45 | 24 | 0 | 32 | 1 | 36 | 0.45 | 24 | 0 | 32 | 1 | 36 |
| 4 | Т | 0.45 | 24 | 3 | 222 | 6 | 30 | 0.45 | 24 | 3 | 222 | 6 | 30 |
| 4 | R | 0.56 | 24 | 1 | 35 | 1 | 36 | 0.56 | 24 | 1 | 35 | 1 | 36 |
| INT | | 0.77 | 105 | | | | | 0.77 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 491 Pedestrian - Vehicle Delay PM Peak File = VICB Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|-------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 19 | 0.0 | 7.3 | | | | 19 | 0.0 | 7.3 |
| 1 | Т | 40 | 0.5 | 46.7 | 1853 | 5.1 | 10.0 | 40 | 0.5 | 46.7 | 1853 | 5.1 | 10.0 |
| 1 | R | | | | 80 | 0.9 | 41.6 | | | | 80 | 0.9 | 41.6 |
| 2 | L | | | | 42 | 0.4 | 34.1 | | | | 42 | 0.4 | 34.1 |
| 2 | Т | 0 | 0.0 | | 112 | 1.1 | 34.1 | 0 | 0.0 | | 112 | 1.1 | 34.1 |
| 2 | R | | | | 139 | 2.2 | 57.3 | | | | 139 | 2.2 | 57.3 |
| 3 | L | | | | 145 | 0.3 | 7.7 | | | | 145 | 0.3 | 7.7 |
| 3 | Т | 0 | 0.0 | | 1868 | 4.0 | 7.6 | 0 | 0.0 | | 1868 | 4.0 | 7.6 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 41 | 0.4 | 34.7 | | | | 41 | 0.4 | 34.7 |
| 4 | Т | 0 | 0.0 | | 287 | 2.8 | 34.7 | 0 | 0.0 | | 287 | 2.8 | 34.7 |
| 4 | R | | | | 42 | 0.5 | 44.8 | | | | 42 | 0.5 | 44.8 |
| INT | | 40 | 1 | 46.7 | 4628 | 18 | 13.8 | 40 | 1 | 46.7 | 4628 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 491 Pedestrian - Vehicle Delay - Stops PM Peak File = VICB ----- Delays & Stops after Co-ordinated Evaluation-----

| | | | Deruy | 5 4 0 | copo u | 1 2 2 1 0 0 | OTUTI | | vuruut | TOUL | | |
|-----|---|------|-------|-------|--------|-------------|-------|-------|--------|------|----|----|
| А | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 19 | 0.0 | 2.0 | 0 | 0.0 | Α | 0 | 6 |
| 1 | Т | 40 | 0.5 | 46.7 | 1853 | 1.0 | 2.0 | 0 | 0.0 | Α | 0 | 6 |
| 1 | R | | | | 80 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 2 | L | | | | 42 | 0.4 | 34.1 | 32 | 0.8 | С | 1 | 12 |
| 2 | Т | 0 | 0.0 | | 112 | 1.1 | 34.1 | 85 | 0.8 | С | 2 | 24 |
| 2 | R | | | | 139 | 2.2 | 57.3 | 138 | 1.0 | Е | 4 | 24 |
| 3 | L | | | | 145 | 1.2 | 30.0 | 87 | 0.6 | С | 1 | 6 |
| 3 | Т | 0 | 0.0 | | 1868 | 15.6 | 30.0 | 1118 | 0.6 | С | 17 | 42 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 41 | 0.4 | 34.7 | 32 | 0.8 | С | 1 | 6 |
| 4 | Т | 0 | 0.0 | | 287 | 2.8 | 34.7 | 222 | 0.8 | С | 6 | 30 |
| 4 | R | | | | 42 | 0.5 | 44.8 | 35 | 0.8 | D | 1 | 6 |
| INT | | 40 | 1 | 46.7 | 4628 | 25 | 19.6 | 1749 | 0.4 | В | | |

| TCS | = | 491 I | solate | ed Opei | ration | Degree | e of Sa | turati | on foi | - Busir | ness Pe | eak VI(| СВ |
|-----|---|-------|--------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.30 | 11 | 1 | 78 | 1 | 6 | 0.30 | 11 | 1 | 78 | 1 | 6 |
| 1 | Т | 0.02 | 11 | 0 | 5 | 0 | 6 | 0.02 | 11 | 0 | 5 | 0 | 6 |
| 1 | R | 0.13 | 11 | 0 | 26 | 0 | 6 | 0.13 | 11 | 0 | 26 | 0 | 6 |
| 2 | L | 0.48 | 37 | 0 | 46 | 1 | 24 | 0.48 | 37 | 0 | 46 | 1 | 24 |
| 2 | Т | 0.48 | 37 | 1 | 205 | 2 | 24 | 0.48 | 37 | 1 | 205 | 2 | 24 |
| 2 | R | 0.24 | 37 | 0 | 28 | 0 | 6 | 0.24 | 37 | 0 | 28 | 0 | 6 |
| 3 | L | 0.30 | 11 | 1 | 78 | 1 | 6 | 0.30 | 11 | 1 | 78 | 1 | 6 |
| 3 | Т | 0.01 | 11 | 0 | 5 | 0 | 6 | 0.01 | 11 | 0 | 5 | 0 | 6 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.43 | 37 | 0 | 43 | 1 | 24 | 0.43 | 37 | 0 | 43 | 1 | 24 |
| 4 | Т | 0.43 | 37 | 1 | 194 | 2 | 18 | 0.43 | 37 | 1 | 194 | 2 | 18 |
| 4 | R | 0.46 | 37 | 0 | 29 | 0 | 24 | 0.46 | 37 | 0 | 29 | 0 | 24 |
| INT | | 0.48 | 56 | | | | | 0.48 | 56 | | | | |
| | | | | | | | | | | | | | |

| тсѕ | = | 491 | Pedestr | rian | | cle Del solated | | | Peak F | ile = | VICB | | |
|-----|---|------|---------|----------|---------|--------------------|--------|--------------|---------|----------|------|-------|------|
| | | | Co ond | inatod | | Length | | | Teolo | tod Cu | | nath | |
| • | | | | | | | | | | | | - | |
| A | М | Peas | ретау | Aver | | Delay | | Peas | ретау | Aver | | Delay | |
| 1 | L | | | | 102 | | 19.2 | | | | 102 | 0.5 | 19.2 |
| 1 | Т | 20 | 0.1 | 22.3 | 7 | 0.0 | 18.1 | 20 | 0.1 | 22.3 | 7 | 0.0 | 18.1 |
| 1 | R | | | | 36 | 0.2 | 18.1 | | | | 36 | 0.2 | 18.1 |
| 2 | L | | | | 102 | 0.1 | 4.7 | | | | 102 | 0.1 | 4.7 |
| 2 | Т | C | 0.0 | | 457 | | 4.7 | 0 | 0.0 | | 457 | 0.6 | 4.7 |
| 2 | R | , c | , 0.0 | | 36 | | 22.4 | 0 | 0.0 | | 36 | 0.2 | |
| | | | | | | | | | | | | | |
| 3 | L | | | | 102 | | 19.2 | | | | 102 | 0.5 | 19.2 |
| 3 | Т | C | 0.0 | | 7 | 0.0 | 18.1 | 0 | 0.0 | | 7 | 0.0 | 18.1 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 102 | 0.1 | 4.5 | | | | 102 | 0.1 | 4.5 |
| 4 | Т | C | 0.0 | | 457 | | 4.5 | 0 | 0.0 | | 457 | 0.6 | 4.5 |
| | R | , c | 0.0 | | 36 | | | | 0.0 | | 36 | 0.2 | |
| | | | | <u> </u> | | | | | 0 | <u> </u> | | | |
| INT | | 20 |) () | 22.3 | | 3 | | | 0 | 22.3 | | 0 | 0.0 |
| | | | - Delay | /s & S† | tops at | cle Del fter Co | -ordir | nated E | Evaluat | ion | | | |
| A | | Peus | ретау | Aver | | Delay | | - | | LOS | | | |
| 1 | L | | | | 102 | | 0.2 | 0 | | A | 0 | 6 | |
| 1 | Т | 20 | 0.1 | 22.3 | 7 | 0.0 | 0.2 | 0 | 0.0 | Α | 0 | 6 | |
| 1 | R | | | | 36 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 | |
| 2 | L | | | | 102 | 0.1 | 4.7 | 46 | 0.4 | Α | 1 | 6 | |
| 2 | Т | C | 0.0 | | 457 | | 4.7 | 205 | | A | 2 | 24 | |
| 2 | R | , c | 0.0 | | 36 | | 22.4 | 28 | 0.8 | В | 0 | 6 | |
| | | | | | | | | | | | | | |
| 3 | L | | | | 102 | | 0.4 | 2 | | Α | 0 | 6 | |
| 3 | Т | C | 0.0 | | 7 | 0.0 | 0.4 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 102 | 0.1 | 4.5 | 43 | 0.4 | Α | 1 | 6 | |
| 4 | Т | C | 0.0 | | 457 | 0.6 | 4.5 | 194 | 0.4 | А | 2 | 18 | |
| 4 | R | | | | 36 | | 22.9 | | 0.8 | В | 0 | 6 | |
| INT | | 20 | 0 | 22.3 | | | | | 0.4 | Ā | Ŭ | 0 | |
| | | | | | | | | | | | | | |
| | | | | | | Degree Length | | | | | | | |
| А | М | DS | | | | Queue | | | | | | | |
| 1 | L | 0.39 | | - | 5 | | | 0.39 | | 0 | 5 | 0 | 6 |
| 1 | Т | 0.99 | | 30 | 2947 | | 138 | 0.99 | | 30 | 2947 | 41 | 138 |
| | | | | | | | | | | | | | |
| 1 | R | 0.74 | | 1 | 71 | 1 | 6 | | 112 | 1 | 71 | 1 | 6 |
| 2 | L | 0.80 | | 1 | 27 | 1 | 54 | | 20 | 1 | 27 | 1 | 54 |
| 2 | Т | 0.80 | | 3 | | 6 | 54 | | 20 | 3 | 164 | 6 | 54 |
| 2 | R | 0.97 | ' 20 | 6 | 214 | 8 | 54 | 0.97 | 20 | 6 | 214 | 8 | 54 |
| 3 | L | 0.43 | | 0 | 34 | 1 | 36 | 0.43 | | 0 | 34 | 1 | 36 |
| 3 | Т | 0.43 | | 2 | 508 | 14 | 36 | 0.43 | 112 | 2 | 508 | 14 | 36 |
| | | 0.70 | , 112 | 2 | 500 | | 00 | 0.70 | 114 | 2 | 000 | 17 | 50 |
| 3 | R | • • | | | | - | | a : - | | | | - | • - |
| 4 | L | 0.45 | | 1 | 49 | 2 | 30 | | 20 | 1 | 49 | 2 | 30 |
| 4 | Т | 0.45 | 5 20 | 2 | 116 | 5 | 30 | | | 2 | 116 | 5 | 30 |
| 4 | R | 0.75 | 5 20 | 1 | 29 | 1 | 30 | 0.75 | 20 | 1 | 29 | 1 | 30 |
| INT | | 0.99 | 140 | | | | | 0.99 | 140 | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 491 | Pedestr | ian | | cle Del solated | | | File = | VICB | | | |
|-----|---|------|---------|-------|-------|--------------------|-------|------|---------|--------|--------|---------|-------|
| | | | Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 18 | 0.0 | 4.0 | | | | 18 | 0.0 | 4.0 |
| 1 | Т | 40 | 0.7 | 64.1 | 2917 | 29.6 | 36.6 | 40 | 0.7 | 64.1 | 2917 | 29.6 | 36.6 |
| 1 | R | | | | 89 | 1.1 | 42.6 | | | | 89 | 1.1 | 42.6 |
| 2 | L | | | | 28 | 0.5 | 69.5 | | | | 28 | 0.5 | 69.5 |
| 2 | Т | C | 0.0 | | 171 | 3.3 | 68.9 | 0 | 0.0 | | 171 | 3.3 | 68.9 |
| 2 | R | | | | 132 | 6.4 | 174.5 | | | | 132 | 6.4 | 174.5 |
| 3 | L | | | | 123 | 0.1 | 4.3 | | | | 123 | 0.1 | 4.3 |
| 3 | Т | C | 0.0 | | 1848 | 2.2 | 4.3 | 0 | 0.0 | | 1848 | 2.2 | 4.3 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 59 | 0.9 | 55.0 | | | | 59 | 0.9 | 55.0 |
| 4 | Т | C | 0.0 | | 141 | 2.2 | 55.0 | 0 | 0.0 | | 141 | 2.2 | 55.0 |
| 4 | R | | | | 29 | 0.7 | 83.9 | | | | 29 | 0.7 | 83.9 |
| INT | | 40 |) 1 | 64.1 | 5555 | 47 | 30.4 | 40 | 1 | 64.1 | 5555 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| TCS | = | 491 | Pedestr | ian · | - Vehio | cle Dei | Lay - S | Stops A | M Peak | File | = VICB | |
|-----|---|------|---------|---------|---------|---------|---------|---------|--------|------|--------|----|
| | | | - Delay | 's & St | tops at | fter Co | o-ordir | nated E | valuat | ion | | |
| А | Μ | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 18 | 0.2 | 36.3 | 0 | 0.0 | С | 0 | 6 |
| 1 | Т | 40 | 0.7 | 64.1 | 2917 | 29.4 | 36.3 | 0 | 0.0 | С | 0 | 6 |
| 1 | R | | | | 89 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 2 | L | | | | 28 | 0.5 | 69.5 | 27 | 1.0 | Е | 1 | 12 |
| 2 | Т | 0 | 0.0 | | 171 | 3.3 | 68.9 | 164 | 1.0 | Е | 6 | 54 |
| 2 | R | | | | 132 | 6.4 | 174.5 | 214 | 1.6 | F | 8 | 54 |
| 3 | L | | | | 123 | 0.2 | 5.6 | 27 | 0.2 | А | 1 | 6 |
| 3 | Т | 0 | 0.0 | | 1848 | 2.9 | 5.6 | 406 | 0.2 | А | 14 | 36 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 59 | 0.9 | 55.0 | 49 | 0.8 | D | 2 | 12 |
| 4 | Т | 0 | 0.0 | | 141 | 2.2 | 55.0 | 116 | 0.8 | D | 5 | 24 |
| 4 | R | | | | 29 | 0.7 | 83.9 | 29 | 1.0 | F | 1 | 6 |
| INT | | 40 | 1 | 64.1 | 5555 | 47 | 30.2 | 1032 | 0.2 | С | | |
| | | | | | | | | | | | | |

| TCS | = | 110 I | solate | ed Oper | ration | Degree | e of Sa | iturati | on foi | r PM Pe | eak VIC | В | |
|-----|---|-------|--------|---------|--------|--------|---------|---------|--------|---------|---------|---------|-------|
| | | C | o-ordi | inated | Cycle | Length | า | | Isola | ated Cy | /cle Le | ength - | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.49 | 97 | 0 | 95 | 2 | 12 | 0.49 | 97 | 0 | 95 | 2 | 12 |
| 1 | Т | 0.27 | 40 | 4 | 372 | 11 | 24 | 0.27 | 40 | 4 | 372 | 11 | 24 |
| 1 | R | 0.82 | 19 | 7 | 502 | 14 | 42 | 0.82 | 19 | 7 | 502 | 14 | 42 |
| 2 | L | 0.21 | 66 | 1 | 92 | 3 | 18 | 0.21 | 66 | 1 | 92 | 3 | 18 |
| 2 | Т | 0.02 | 19 | 0 | 4 | 0 | 6 | 0.02 | 19 | 0 | 4 | 0 | 6 |
| 2 | R | 0.82 | 28 | 9 | 708 | 18 | 54 | 0.82 | 28 | 9 | 708 | 18 | 54 |
| 3 | L | 0.36 | 82 | 0 | 134 | 3 | 24 | 0.36 | 82 | 0 | 134 | 3 | 24 |
| 3 | Т | 0.82 | 27 | 13 | 1068 | 27 | 60 | 0.82 | 27 | 13 | 1068 | 27 | 60 |
| 3 | R | 0.82 | 6 | 3 | 190 | 6 | 18 | 0.82 | 6 | 3 | 190 | 6 | 18 |
| 4 | L | 0.16 | 23 | 1 | 45 | 1 | 12 | 0.16 | 23 | 1 | 45 | 1 | 12 |
| 4 | Т | 0.02 | 13 | 0 | 5 | 0 | 6 | 0.02 | 13 | 0 | 5 | 0 | 6 |
| 4 | R | 0.82 | 24 | 8 | 621 | 16 | 54 | 0.82 | 24 | 8 | 621 | 16 | 54 |
| INT | | 0.82 | 105 | | | | | 0.82 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay PM Peak File = VICB Isolated Operation

| | | | | | | oo ra coa | 00010 | | | | | | |
|-----|---|------|---------|-------|-------|-----------|-------|------|---------|--------|--------|--------|------|
| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ngth - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 799 | 0.1 | 0.5 | | | | 799 | 0.1 | 0.5 |
| 1 | Т | 50 | 0.6 | 46.7 | 599 | 3.7 | 22.5 | 50 | 0.6 | 46.7 | 599 | 3.7 | 22.5 |
| 1 | R | | | | 546 | 7.1 | 46.5 | | | | 546 | 7.1 | 46.5 |
| 2 | L | | | | 235 | 0.6 | 8.5 | | | | 235 | 0.6 | 8.5 |
| 2 | Т | 50 | 0.6 | 46.7 | 6 | 0.1 | 35.4 | 50 | 0.6 | 46.7 | 6 | 0.1 | 35.4 |
| 2 | R | | | | 809 | 8.8 | 39.1 | | | | 809 | 8.8 | 39.1 |
| 3 | L | | | | 489 | 0.5 | 3.5 | | | | 489 | 0.5 | 3.5 |
| 3 | Т | 50 | 0.6 | 46.7 | 1239 | 13.1 | 38.1 | 50 | 0.6 | 46.7 | 1239 | 13.1 | 38.1 |
| 3 | R | | | | 176 | 3.3 | 67.0 | | | | 176 | 3.3 | 67.0 |
| 4 | L | | | | 61 | 0.6 | 33.5 | | | | 61 | 0.6 | 33.5 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 40.4 | 0 | 0.0 | | 6 | 0.1 | 40.4 |
| 4 | R | | | | 696 | 8.1 | 42.1 | | | | 696 | 8.1 | 42.1 |
| INT | | 150 | 2 | 46.7 | 5661 | 46 | 29.2 | 150 | 2 | 46.7 | 5661 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| TCS | = | 110 F | | | | | 5 | | | | | |
|-----|---|-------|---------|---------|---------|---------|--------|---------|--------|-----|----|----|
| | | | • Delay | 's & St | cops at | fter Co | -ordir | nated E | valuat | ion | | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 799 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 1 | Т | 50 | 0.6 | 46.7 | 599 | 13.2 | 79.2 | 789 | 1.3 | F | 11 | 24 |
| 1 | R | | | | 546 | 0.8 | 5.0 | 16 | 0.0 | Α | 0 | 6 |
| 2 | L | | | | 235 | 0.6 | 8.5 | 92 | 0.4 | Α | 3 | 18 |
| 2 | Т | 50 | 0.6 | 46.7 | 6 | 0.1 | 35.4 | 4 | 0.7 | С | 0 | 6 |
| 2 | R | | | | 809 | 8.8 | 39.1 | 708 | 0.9 | С | 18 | 54 |
| 3 | L | | | | 489 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 3 | Т | 50 | 0.6 | 46.7 | 1239 | 2.6 | 7.7 | 0 | 0.0 | Α | 0 | 6 |
| 3 | R | | | | 176 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 4 | L | | | | 61 | 0.6 | 33.5 | 45 | 0.7 | С | 1 | 12 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 40.4 | 5 | 0.8 | С | 0 | 6 |
| 4 | R | | | | 696 | 8.1 | 42.1 | 621 | 0.9 | D | 16 | 54 |
| INT | | 150 | 2 | 46.7 | 5661 | 35 | 22.1 | 2281 | 0.4 | В | | |
| | | | | | | | | | | | | |

| TCS | = | 110 I | solate | ed Oper | ration | Degree | e of Sa | aturati | on fo | r Busir | ness Pe | eak VIC | ЭВ |
|-----|---|-------|--------|---------|--------|--------|---------|---------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Lengtl | n | | Isola | ated Cy | ycle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.10 | 32 | 0 | 41 | 1 | 6 | 0.10 | 32 | 0 | 41 | 1 | 6 |
| 1 | Т | 0.00 | 15 | 0 | 5 | 0 | 6 | 0.00 | 15 | 0 | 5 | 0 | 6 |
| 1 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 2 | L | 0.07 | 47 | 0 | 16 | 0 | 6 | 0.07 | 47 | 0 | 16 | 0 | 6 |
| 2 | Т | 0.44 | 15 | 2 | 342 | 5 | 18 | 0.44 | 15 | 2 | 342 | 5 | 18 |
| 2 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 3 | L | 0.10 | 32 | 0 | 41 | 1 | 6 | 0.10 | 32 | 0 | 41 | 1 | 6 |
| 3 | Т | 0.00 | 15 | 0 | 5 | 0 | 6 | 0.00 | 15 | 0 | 5 | 0 | 6 |
| 3 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 4 | L | 0.15 | 22 | 0 | 60 | 1 | 6 | 0.15 | 22 | 0 | 60 | 1 | 6 |
| 4 | Т | 0.51 | 13 | 2 | 359 | 5 | 18 | 0.51 | 13 | 2 | 359 | 5 | 18 |
| 4 | R | 0.40 | 5 | 1 | 92 | 2 | 6 | 0.40 | 5 | 1 | 92 | 2 | 6 |
| INT | | 0.51 | 56 | | | | | 0.51 | 56 | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay Business Peak File = VICB Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 102 | 0.2 | 5.3 | | | | 102 | 0.2 | 5.3 |
| 1 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 |
| 1 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 2 | L | | | | 102 | 0.0 | 0.8 | | | | 102 | 0.0 | 0.8 |
| 2 | Т | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 |
| 2 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 3 | L | | | | 102 | 0.2 | 5.3 | | | | 102 | 0.2 | 5.3 |
| 3 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 |
| 3 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 4 | L | | | | 102 | 0.3 | 11.2 | | | | 102 | 0.3 | 11.2 |
| 4 | Т | 0 | 0.0 | | 457 | 2.4 | 18.8 | 0 | 0.0 | | 457 | 2.4 | 18.8 |
| 4 | R | | | | 108 | 0.7 | 24.2 | | | | 108 | 0.7 | 24.2 |
| INT | | 75 | 0 | 22.3 | 1768 | 8 | 16.6 | 75 | 0 | 22.3 | 1768 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay - Stops Business Peak File = VICB ----- Delays & Stops after Co-ordinated Evaluation-----

| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | | |
|-----|---|------|-------|------|------|-------|------|-------|------|-----|---|----|--|
| 1 | L | | | | 102 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 | |
| 1 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 0.4 | 2 | 0.3 | Α | 0 | 6 | |
| 1 | R | | | | 108 | 0.2 | 5.0 | 2 | 0.0 | Α | 0 | 6 | |
| 2 | L | | | | 102 | 0.0 | 0.8 | 16 | 0.2 | Α | 0 | 6 | |
| 2 | Т | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 | 342 | 0.7 | В | 5 | 18 | |
| 2 | R | | | | 108 | 0.7 | 24.1 | 91 | 0.8 | В | 1 | 6 | |
| 3 | L | | | | 102 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | 108 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 | |
| 4 | L | | | | 102 | 0.3 | 11.2 | 60 | 0.6 | Α | 1 | 6 | |
| 4 | Т | 0 | 0.0 | | 457 | 2.4 | 18.8 | 359 | 0.8 | В | 5 | 18 | |
| 4 | R | | | | 108 | 0.7 | 24.2 | 92 | 0.9 | В | 1 | 6 | |
| INT | | 75 | 0 | 22.3 | 1768 | 7 | 13.2 | 963 | 0.5 | Α | | | |
| | | | | | | | | | | | | | |

| TCS | = | 110 I | solate | ed Oper | ration | Degree | e of Sa | turati | on foi | ∽ AM P€ | eak VIC | В | |
|-----|---|-------|--------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | ו ר | | Isola | ated Cy | /cle Le | ength · | |
| Α | Μ | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.20 | 134 | 0 | 15 | 1 | 6 | 0.20 | 107 | 0 | 20 | 1 | 6 |
| 1 | Т | 0.68 | 80 | 9 | 1001 | 26 | 78 | 0.53 | 58 | 8 | 958 | 24 | 54 |
| 1 | R | 0.89 | 37 | 11 | 651 | 22 | 84 | 0.89 | 24 | 11 | 682 | 19 | 60 |
| 2 | L | 0.52 | 93 | 2 | 277 | 8 | 48 | 0.54 | 71 | 2 | 303 | 7 | 42 |
| 2 | Т | 0.03 | 15 | 0 | 5 | 0 | 6 | 0.02 | 15 | 0 | 5 | 0 | 6 |
| 2 | R | 0.89 | 10 | 6 | 268 | 11 | 36 | 0.89 | 8 | 6 | 281 | 9 | 30 |
| 3 | L | 0.37 | 99 | 1 | 161 | 5 | 36 | 0.34 | 85 | 1 | 135 | 3 | 24 |
| 3 | Т | 0.89 | 48 | 23 | 1556 | 47 | 96 | 0.89 | 39 | 19 | 1569 | 38 | 78 |
| 3 | R | 0.82 | 5 | 3 | 124 | 5 | 18 | 0.67 | 5 | 2 | 97 | 3 | 12 |
| 4 | L | 0.05 | 36 | 0 | 15 | 1 | 6 | 0.05 | 28 | 0 | 15 | 1 | 6 |
| 4 | Т | 0.02 | 27 | 0 | 4 | 0 | 6 | 0.01 | 24 | 0 | 4 | 0 | 6 |
| 4 | R | 0.89 | 24 | 11 | 556 | 20 | 66 | 0.89 | 19 | 9 | 570 | 17 | 54 |
| INT | | 0.89 | 140 | | | | | 0.89 | 113 | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 110 | Pedestr | ian | - Vehi | cle Dela | ay AM | Peak | File = | VICB | | | |
|-----|---|------|---------|-------|--------|----------|-------|-------|---------|--------|--------|---------|------|
| | | | | | Is | solated | Opera | ation | | | | | |
| | | | Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 337 | 0.0 | 0.1 | | | | 337 | 0.0 | 0.2 |
| 1 | Т | 50 | 0.9 | 64.1 | 1585 | 9.3 | 21.1 | 50 | 0.7 | 50.7 | 1585 | 8.2 | 18.6 |
| 1 | R | | | | 702 | 11.3 | 57.9 | | | | 702 | 10.5 | 54.1 |
| 2 | L | | | | 598 | 2.0 | 12.2 | | | | 598 | 2.0 | 11.8 |
| 2 | Т | 50 | 0.9 | 64.1 | 6 | 0.1 | 56.0 | 50 | 0.7 | 50.7 | 6 | 0.1 | 42.6 |
| 2 | R | | | | 236 | 6.5 | 98.5 | | | | 236 | 5.6 | 85.5 |
| 3 | L | | | | 449 | 1.0 | 8.3 | | | | 449 | 0.6 | 4.7 |
| 3 | Т | 50 | 0.9 | 64.1 | 1787 | 22.9 | 46.2 | 50 | 0.7 | 50.7 | 1787 | 18.9 | 38.1 |
| 3 | R | | | | 109 | 3.0 | 98.1 | | | | 109 | 1.6 | 53.2 |
| 4 | L | | | | 22 | 0.2 | 38.9 | | | | 22 | 0.2 | 32.1 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 45.7 | 0 | 0.0 | | 6 | 0.1 | 34.9 |
| 4 | R | | | | 568 | 11.1 | 70.5 | | | | 568 | 9.4 | 59.5 |
| INT | | 150 | 3 | 64.1 | 6405 | 68 | 38.0 | 150 | 2 | 50.7 | 6405 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| | | | • Delay | S & S1 | tops at | fter Co | -ordir | nated E | valuat | ion | | |
|-----|---|------|---------|--------|---------|---------|--------|---------|--------|-----|----|----|
| А | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 337 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 1 | Т | 50 | 0.9 | 64.1 | 1585 | 33.1 | 75.1 | 1943 | 1.2 | F | 26 | 78 |
| 1 | R | | | | 702 | 0.9 | 4.6 | 25 | 0.0 | А | 1 | 6 |
| 2 | L | | | | 598 | 2.0 | 12.2 | 277 | 0.5 | Α | 8 | 48 |
| 2 | Т | 50 | 0.9 | 64.1 | 6 | 0.1 | 56.0 | 5 | 0.8 | D | 0 | 6 |
| 2 | R | | | | 236 | 6.5 | 98.5 | 268 | 1.1 | F | 10 | 36 |
| 3 | L | | | | 449 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 3 | Т | 50 | 0.9 | 64.1 | 1787 | 4.6 | 9.2 | 0 | 0.0 | А | 0 | 6 |
| 3 | R | | | | 109 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 4 | L | | | | 22 | 0.2 | 38.9 | 15 | 0.7 | С | 1 | 6 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 45.7 | 4 | 0.7 | D | 0 | 6 |
| 4 | R | | | | 568 | 11.1 | 70.5 | 556 | 1.0 | F | 20 | 66 |
| INT | | 150 | 3 | 64.1 | 6405 | 59 | 32.9 | 3094 | 0.5 | С | | |

Victoria Road Future with Development - VICF.DAT

SCATES Program Version: 2013 Date: 27-OCT-12 Time: Registered User Name. - Road Delay Solutions Pty Ltd Registered User No. - 0 Data File: VICF VICTORIA ROAD 2031 BITZIOS VOLUMES

| | | | AM PEA | ٩K | | | F | PM PEA | ٩K | | | E | BUSINE | ESS | |
|-------|-------|-------|--------|------|------|------|--------|--------|------|-----------|------|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 15 | 1750 | Α | 0 | 0.0 | 18 | 1750 | Α | 0 | 0.0 | 102 | 1750 | Α | 0 | 0.0 |
| 1T | 2907 | 3710 | Α | | | 1850 | 3710 | Α | | | 7 | 3710 | Α | | |
| 1R | 84 | 1850 | S | | | 78 | 1850 | S | | | 36 | 1850 | S | | |
| 2L | 28 | 1750 | В | | | 42 | 1750 | В | | | 102 | 1750 | В | | |
| 2T | 171 | 1750 | В | | | 112 | 1750 | В | | | 457 | 1750 | В | | |
| 2R | 132 | 1850 | S | | | 139 | 1850 | S | | | 36 | 1850 | S | | |
| 3L | 125 | 1750 | Α | 0 | 0.0 | 142 | 1750 | Α | 0 | 0.0 | 102 | 1750 | Α | 0 | 0.0 |
| ЗT | 1856 | 5670 | Α | 0 | 958 | 1831 | 5670 | Α | 0 | 140 | 7 | 5670 | Α | 0 | 108 |
| ЗR | 0 | 0 | S | | | 0 | 0 | S | | | 0 | 0 | S | | |
| 4L | 59 | 1750 | В | | | 41 | 1750 | В | | | 102 | 1750 | В | | |
| 4T | 141 | 3600 | В | | | 284 | 3600 | В | | | 457 | 1850 | В | | |
| 4R | 29 | 1850 | S | | | 39 | 1850 | S | | | 36 | 1850 | S | | |
| Туре | = CO(| 00 | | | | А | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |
| File | = VIC | CF | | | | 1 | 22 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| | | | | | | 2 | 5 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| TCS : | = 49 | 1 | | | | 3 | 5 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| | | | | | | 4 | 24 | 4.0 | 0 | 0 | 0 | 0 ' | 0 | 0 | |
| | F | PEDES | TRIAN | VOLU | ME | WAL | <-CLE/ | ARANCE | = - | TRAM [| DATA | PI | EDEST | TRA | M |
| Арр | P#/ | ۹M | P#PM | Pi | #B | Wall | ((| Clear | | | | F | ACT | FAC | т |
| 1 | 40 |) | 40 | : | 20 | 6 | | 16 | (|)% | | Ę | 50 | 10 | 0 |
| 2 | 0 | | 0 | (| 0 | 0 | (| C | (|)% | | | 100 | 10 | 0 |
| 3 | 0 | | 0 | (| 0 | 0 | (| C | (|)% | | | 100 | 10 | 0 |
| 4 | 0 | | 0 | (| 0 | 6 | - | 18 | (|)% | | Ę | 50 | 10 | 0 |
| | | | | | | | | | | | | | | | - |

| | | ļ | AM PEA | ٩K | | | F | M PEA | ٩K | | | E | BUSINE | ESS | |
|------|-------|------|--------|------|------|------|------|-------|------|------|-----|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 347 | 1750 | S | 0 | 0.0 | 816 | 1750 | S | 0 | 0.0 | 102 | 1750 | S | 0 | 0.0 |
| 1T | 1600 | 5880 | Α | 0 | 449 | 609 | 5880 | Α | 0 | 59 | 7 | 5880 | Α | 72 | 0 |
| 1R | 702 | 3700 | G | | | 546 | 3700 | G | | | 108 | 3700 | G | | |
| 2L | 588 | 1750 | S | | | 218 | 1750 | S | | | 102 | 1750 | S | | |
| 2T | 6 | 3920 | E | | | 6 | 3920 | E | | | 457 | 3920 | E | | |
| 2R | 228 | 3700 | D | | | 779 | 3700 | D | | | 108 | 3700 | D | | |
| ЗL | 449 | 1750 | S | 0 | 0.0 | 476 | 1750 | S | 0 | 0.0 | 102 | 1750 | S | 0 | 0.0 |
| ЗT | 1787 | 5880 | Α | | | 1229 | 5880 | Α | | | 7 | 5880 | Α | | |
| ЗR | 109 | 3700 | G | | | 166 | 3700 | G | | | 108 | 3700 | G | | |
| 4L | 22 | 1750 | GE | | | 43 | 1750 | GE | | | 102 | 1750 | GE | | |
| 4T | 6 | 3920 | Е | | | 6 | 3920 | E | | | 457 | 3920 | E | | |
| 4R | 564 | 3700 | D | | | 666 | 3700 | D | | | 108 | 3700 | D | | |
| Туре | = D0[| 00 | | | | А | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |

ROAD DELAY SOLUTIONS

| File = | VICF | | | 1 | 32 | 4.0 | 0 | 0 | 0 | 0 | |
|--------|------|----------|--------|-------|-------|-------|----|-------|----|--------|------|
| | | | | 2 | 30 | 4.0 | 0 | 0 | 0 | 0 | |
| TCS = | 110 | | | 3 | 32 | 4.0 | 0 | 0 | 0 | 0 | |
| | | | | 4 | 5 | 4.0 | 0 | 0 | 0 | 0 | |
| | PEDE | STRIAN V | /OLUME | WALK- | CLEAF | RANCE | TR | AM DA | TA | PEDEST | TRAM |
| Арр | P#AM | P#PM | P#B | Walk | C1 | Lear | | | | FACT | FACT |
| 1 | 50 | 50 | 25 | 6 | 26 | 5 | 0% | | | 50 | 100 |
| 2 | 50 | 50 | 25 | 6 | 24 | 1 | 0% | | | 50 | 100 |
| 3 | 50 | 50 | 25 | 6 | 26 | 5 | 0% | | | 50 | 100 |
| 4 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 100 | 100 |
| | | | | | | | | | | | |

APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 Tidal Down Lanes Grade Down Lanes Grade Down Lanes Grade Down Lanes Grade 0 3 0 0 2 0 0 3 0 0 2 0 N Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane LT 9999 1750 LT 9999 1750 LT 9999 1750 LT 9999 1750 T 9999 1960 R 9999 1850 T 9999 1960 TR 9999 1850 1 T 9999 1960 R 35 1850 T 9999 1960 T 9999 1960 2 3 4 5 6 7 8 No Parking No Parking No Parking No Parking
 AM
 PM
 BUS
 AM
 AM
 AM
 AM
 Apprch 0 0 0 0 Depart O File = VICF TCS = 491 Type = COCO _____ APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 DownLanesGradeDownLanesGradeDownLanesGrade06004060040 Tidal Ν Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane L 50 1750 L 9999 1750 L 110 1750 L 65 1750 T 9999 1960 T 9999 3920 T 9999 1960 T 9999 3920 1 2 T 9999 1960 R 9999 1850 T 9999 1960 R 120 1850 T 9999 1960 R 100 1850 3 R 100 1850 4 T 9999 1960 R 70 1850 R 120 1850 5 R 70 1850 6 R 120 1850 7 8 NoParkingNoParkingNoParkingAMPMBUSAMPMBUSAMPMBUS00000000000000000000000000000 AM PM BUS Apprch 0 0 Depart File = VICF Type = D0D0 TCS = 110 AM PEAKPM PEAKBUSINESSGT%GT%CLCLGT%GT%CLCLCORDISOLCORDISOLCORDISOLCORDISOLCORDISOL82.982.914014072.872.810510526.826.8565617117127.273.273.273.2 Ph А В С D Е dlay dlay dlay dlay dlay dlay 0.7 0.7 F G
 dlay
 44
 44
 AB
 dlay
 17
 17

 Stps
 4.0
 4.0
 Stps
 2.5
 2.5

 DS
 0.98
 0.98
 1
 DS
 0.75
 0.75
 AB dlay 44 44 AB dlay 3 3 Sea Stps2.52.5Stps0.70.7DS0.750.751DS0.480.48 Mode 1

ROAD DELAY SOLUTIONS

| File = VICF | - | Bay Slip | | Туре |
|---|-----------|------------------------------|-----------------------|-----------|
| TCS = 491 | | Act Req 35 27 11 27 | 0 0 | 0000 |
| | 4 12 | 2 0 18 | 0 ersections are (| optimised |
| | | | | |
| AM PEAK | | PM PEAK | BI | USINESS |
| Ph GT% GT% CL CL | GT% GT% | 5 CL | CL GT% GT% | CL CL |
| CORD ISOL CORD ISOL A 36.9 37.6 140 112 B | | | | |
| C D 19.9 20.6 | 30.0 30.0 | I | 15.8 15.8 | |
| E 13.6 17.0 F dlav dlav | | dlav | | dlav dlav |
| F dlay dlay G 29.6 24.8 2.7 2.1 | | | dlay 1 9 15 8 15 8 | dlay dlay |
| Seq ADEG dlay 67 57 | | | | |
| | | - | 3.7 | - |
| Mode 1 DS 0.89 0.89 | | | | |
| File = VICF | A Bay | ' Bay Slip | Slip | Туре |
| | Rec | Act Req | Act | |
| TCS = 110 | 1 90 | 70 20 | 50 | DODO |
| | 2 99 | | | |
| | 3 27 | | | |
| | 4 | 20 | 65 | |
| | Bays | if all inte | ersections are (| optimised |
| | | | | |

| TCS | = | 491 I | solate | ed Opei | ration | Degree | e of Sa | turati | on foi | ° PM P€ | eak VIC | CF | |
|-----|---|-------|--------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord | inated | Cycle | Lengt | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.45 | 72 | 0 | 7 | 0 | 6 | 0.45 | 72 | 0 | 7 | 0 | 6 |
| 1 | Т | 0.73 | 72 | 5 | 1040 | 17 | 54 | 0.73 | 72 | 5 | 1040 | 17 | 54 |
| 1 | R | 0.75 | 72 | 1 | 67 | 1 | 6 | 0.75 | 72 | 1 | 67 | 1 | 6 |
| 2 | L | 0.38 | 25 | 0 | 32 | 1 | 24 | 0.38 | 25 | 0 | 32 | 1 | 24 |
| 2 | Т | 0.38 | 25 | 1 | 85 | 3 | 24 | 0.38 | 25 | 1 | 85 | 3 | 24 |
| 2 | R | 0.75 | 25 | 2 | 133 | 3 | 24 | 0.75 | 25 | 2 | 133 | 3 | 24 |
| 3 | L | 0.50 | 72 | 0 | 61 | 1 | 42 | 0.50 | 72 | 0 | 61 | 1 | 42 |
| 3 | Т | 0.50 | 72 | 4 | 784 | 17 | 42 | 0.50 | 72 | 4 | 784 | 17 | 42 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.43 | 25 | 0 | 31 | 1 | 36 | 0.43 | 25 | 0 | 31 | 1 | 36 |
| 4 | Т | 0.43 | 25 | 3 | 218 | 6 | 30 | 0.43 | 25 | 3 | 218 | 6 | 30 |
| 4 | R | 0.54 | 25 | 0 | 32 | 1 | 36 | 0.54 | 25 | 0 | 32 | 1 | 36 |
| INT | | 0.75 | 105 | | | | | 0.75 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 491 Pedestrian - Vehicle Delay PM Peak File = VICF Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 18 | 0.0 | 7.3 | | | | 18 | 0.0 | 7.3 |
| 1 | Т | 40 | 0.5 | 46.7 | 1850 | 5.2 | 10.2 | 40 | 0.5 | 46.7 | 1850 | 5.2 | 10.2 |
| 1 | R | | | | 78 | 0.9 | 40.6 | | | | 78 | 0.9 | 40.6 |
| 2 | L | | | | 42 | 0.4 | 33.8 | | | | 42 | 0.4 | 33.8 |
| 2 | Т | 0 | 0.0 | | 112 | 1.1 | 33.8 | 0 | 0.0 | | 112 | 1.1 | 33.8 |
| 2 | R | | | | 139 | 2.1 | 53.8 | | | | 139 | 2.1 | 53.8 |
| 3 | L | | | | 142 | 0.3 | 7.7 | | | | 142 | 0.3 | 7.7 |
| 3 | Т | 0 | 0.0 | | 1831 | 3.9 | 7.7 | 0 | 0.0 | | 1831 | 3.9 | 7.7 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 41 | 0.4 | 34.3 | | | | 41 | 0.4 | 34.3 |
| 4 | Т | 0 | 0.0 | | 284 | 2.7 | 34.3 | 0 | 0.0 | | 284 | 2.7 | 34.3 |
| 4 | R | | | | 39 | 0.5 | 44.7 | | | | 39 | 0.5 | 44.7 |
| INT | | 40 | 1 | 46.7 | 4576 | 17 | 13.8 | 40 | 1 | 46.7 | 4576 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 491 Pedestrian - Vehicle Delay - Stops PM Peak File = VICF ----- Delays & Stops after Co-ordinated Evaluation------A M Peds Delay Aver Vehs Delay Aver Stops Aver LOS 0 1 L 18 0.0 2.0 0.0 Α 0 6 2.0 40 0.5 46.7 1850 0 0.0 0 1 T 1.0 Α 6 1 R 78 0.0 0.0 0 0.0 А 0 6 2 42 0.4 33.8 0.8 12 L 32 С 1 2 Т 0 0.0 112 1.1 33.8 85 0.8 С 2 24 2 R 139 2.1 53.8 133 1.0 D 3 24 3 L 30.7 С 1 6 142 1.2 84 0.6 3 T 0 0.0 1831 15.6 30.7 1088 0.6 С 17 42 3 R 0.4 34.3 4 L 41 31 0.8 С 1 6 4 T 284 2.7 34.3 218 0.8 С 30 0 0.0 6 4 R 39 0.5 44.7 32 0.8 D 1 6 INT 40 1 46.7 4576 25 19.6 1704 0.4 В

TCS = 491 Isolated Operation Degree of Saturation for Business Peak VICF ---- Co-ordinated Cycle Length ---- Isolated Cycle Length -----GT Delay Stops Queue Metre DS DS GT Delay Stops Queue Metre A M 6 0.30 0.30 1 L Т 0.02 6 0.02 R 0.13 6 0.13 L 0.48 24 0.48 Т 0.48 24 0.48 R 0.24 6 0.24 0.30 6 0.30 L 3 T 0.01 6 0.01 3 R 4 L 0.43 24 0.43 0 43 4 T 0.43 18 0.43 1 194 2 18 4 R 0.46 24 0.46 INT 0.48 0.48

| TCS | = | 491 | Pedestr | ian | | cle Dela solated | - | | Peak F | ile = | VICF | | |
|-----|---|------|---------|-------|-------|---------------------|------|------|---------|--------|--------|---------|------|
| | | | Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | Μ | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 102 | 0.5 | 19.2 | | | | 102 | 0.5 | 19.2 |
| 1 | Т | 20 | 0.1 | 22.3 | 7 | 0.0 | 18.1 | 20 | 0.1 | 22.3 | 7 | 0.0 | 18.1 |
| 1 | R | | | | 36 | 0.2 | 18.1 | | | | 36 | 0.2 | 18.1 |
| 2 | L | | | | 102 | 0.1 | 4.7 | | | | 102 | 0.1 | 4.7 |
| 2 | Т | C | 0.0 | | 457 | 0.6 | 4.7 | 0 | 0.0 | | 457 | 0.6 | 4.7 |
| 2 | R | | | | 36 | 0.2 | 22.4 | | | | 36 | 0.2 | 22.4 |
| 3 | L | | | | 102 | 0.5 | 19.2 | | | | 102 | 0.5 | 19.2 |
| 3 | Т | C | 0.0 | | 7 | 0.0 | 18.1 | 0 | 0.0 | | 7 | 0.0 | 18.1 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 102 | 0.1 | 4.5 | | | | 102 | 0.1 | 4.5 |
| 4 | Т | C | 0.0 | | 457 | 0.6 | 4.5 | 0 | 0.0 | | 457 | 0.6 | 4.5 |
| 4 | R | | | | 36 | 0.2 | 22.9 | | | | 36 | 0.2 | 22.9 |
| INT | | 20 |) 0 | 22.3 | 1444 | 3 | 8.0 | 20 | 0 | 22.3 | 1444 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 491 Pedestrian - Vehicle Delay - Stops Business Peak File = VICF ----- Delays & Stops after Co-ordinated Evaluation------A M Peds Delay Aver Vehs Delay Aver Stops Aver LOS 1 L 102 0.0 0.2 0 0.0 Α 0 6 1 T 20 0.1 22.3 0.2 0.0 7 0.0 0 А 0 6 1 R 36 0.0 0.0 0 0.0 0 6 А 1 2 L 102 0.1 4.7 46 0.4 Α 6 2 T 0.0 457 0.6 4.7 205 0.4 2 24 0 Α 2 R 36 0.2 22.4 28 0.8 В 0 6 3 L 102 0.0 0.4 2 0.0 A 0 6 3 T 0 0.0 0 0.0 A 0 7 0.0 0.4 6 3 R 4 L 102 0.1 4.5 43 0.4 А 1 6 4 T 194 0 0.0 457 0.6 4.5 0.4 А 2 18 4 R 36 0.2 22.9 29 0.8 В 0 6 20 INT 0 22.3 1444 2 4.7 548 0.4 Α

TCS = 491 Isolated Operation Degree of Saturation for AM Peak VICF

| | | C | o-ord: | inated | Cycle | Lengtl | 1 | | Isola | ated Cy | /cle Le | ength · | |
|-----|---|------|--------|--------|-------|--------|-------|------|-------|---------|---------|---------|-------|
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.34 | 112 | 0 | 4 | 0 | 6 | 0.34 | 112 | 0 | 4 | 0 | 6 |
| 1 | Т | 0.98 | 112 | 27 | 2836 | 38 | 126 | 0.98 | 112 | 27 | 2836 | 38 | 126 |
| 1 | R | 0.72 | 112 | 1 | 66 | 1 | 6 | 0.72 | 112 | 1 | 66 | 1 | 6 |
| 2 | L | 0.80 | 20 | 1 | 27 | 1 | 54 | 0.80 | 20 | 1 | 27 | 1 | 54 |
| 2 | Т | 0.80 | 20 | 3 | 163 | 6 | 54 | 0.80 | 20 | 3 | 163 | 6 | 54 |
| 2 | R | 0.96 | 20 | 6 | 211 | 8 | 54 | 0.96 | 20 | 6 | 211 | 8 | 54 |
| 3 | L | 0.44 | 112 | 0 | 35 | 1 | 36 | 0.44 | 112 | 0 | 35 | 1 | 36 |
| 3 | Т | 0.44 | 112 | 2 | 513 | 14 | 36 | 0.44 | 112 | 2 | 513 | 14 | 36 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.45 | 20 | 1 | 49 | 2 | 30 | 0.45 | 20 | 1 | 49 | 2 | 30 |
| 4 | Т | 0.45 | 20 | 2 | 116 | 5 | 30 | 0.45 | 20 | 2 | 116 | 5 | 30 |
| 4 | R | 0.75 | 20 | 1 | 29 | 1 | 30 | 0.75 | 20 | 1 | 29 | 1 | 30 |
| INT | | 0.98 | 140 | | | | | 0.98 | 140 | | | | |

TCS = 491 Pedestrian - Vehicle Delay AM Peak File = VICF Isolated Operation --- Co-ordinated Cycle Length --- Isolated Cycle Length -----A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh Delay Aver 0.0 3.8 0.0 3.8 1 L 15 15 40 0.7 64.1 2907 26.5 32.9 1 T 40 0.7 64.1 2907 26.5 32.9 1 R 84 1.0 42.8 84 1.0 42.8 0.5 69.1 2 L 0.5 69.1 28 28 0 0.0 2 T 0.0 3.2 68.4 3.2 68.4 171 171 2 R 6.3 170.9 6.3 170.9 132 132 3 L 4.3 0.1 4.3 125 0.1 125 3 T 0 0.0 1856 2.2 4.3 0 0.0 1856 2.2 4.3 3 R 4 L 59 0.9 54.9 59 0.9 54.9 4 T 0.0 141 2.2 54.9 0 0.0 141 2.2 54.9 4 R 29 0.7 83.9 29 0.7 83.9 40 INT 1 64.1 5547 44 28.4 40 1 64.1 5547 0 0.0

| TCS | = | 491 I | Pedestr | ian · | • Vehi | cle Del | Lay - S | Stops A | M Peak | File : | = VICF | |
|-----|---|-------|---------|---------|---------|---------|---------|---------|--------|--------|--------|----|
| | | | - Delay | 's & St | tops at | fter Co | o-ordir | nated E | valuat | ion | | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | |
| 1 | L | | | | 15 | 0.1 | 32.7 | 0 | 0.0 | С | 0 | 6 |
| 1 | Т | 40 | 0.7 | 64.1 | 2907 | 26.4 | 32.7 | 0 | 0.0 | С | 0 | 6 |
| 1 | R | | | | 84 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 2 | L | | | | 28 | 0.5 | 69.1 | 27 | 1.0 | Е | 1 | 12 |
| 2 | Т | 0 | 0.0 | | 171 | 3.2 | 68.4 | 163 | 1.0 | Е | 6 | 54 |
| 2 | R | | | | 132 | 6.3 | 170.9 | 211 | 1.6 | F | 8 | 54 |
| 3 | L | | | | 125 | 0.2 | 5.3 | 26 | 0.2 | А | 1 | 6 |
| 3 | Т | 0 | 0.0 | | 1856 | 2.7 | 5.3 | 383 | 0.2 | А | 14 | 36 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 59 | 0.9 | 54.9 | 49 | 0.8 | D | 2 | 12 |
| 4 | Т | 0 | 0.0 | | 141 | 2.2 | 54.9 | 116 | 0.8 | D | 5 | 24 |
| 4 | R | | | | 29 | 0.7 | 83.9 | 29 | 1.0 | F | 1 | 6 |
| INT | | 40 | 1 | 64.1 | 5547 | 43 | 28.0 | 1004 | 0.2 | С | | |
| | | | | | | | | | | | | |

| TCS | = | 110 I | solate | ed Oper | ration | Degree | e of Sa | turati | on for | PM Pe | eak VIC | F | |
|-----|---|-------|--------|---------|--------|--------|---------------|--------|--------|---------|---------|---------|-------|
| | | C | o-ordi | inated | Cycle | Length | ר- ר ר | | Isola | ated Cy | /cle Le | ength - | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.50 | 98 | 0 | 95 | 2 | 12 | 0.50 | 98 | 0 | 95 | 2 | 12 |
| 1 | Т | 0.27 | 41 | 4 | 375 | 11 | 24 | 0.27 | 41 | 4 | 375 | 11 | 24 |
| 1 | R | 0.80 | 19 | 7 | 495 | 14 | 42 | 0.80 | 19 | 7 | 495 | 14 | 42 |
| 2 | L | 0.20 | 67 | 0 | 82 | 2 | 18 | 0.20 | 67 | 0 | 82 | 2 | 18 |
| 2 | Т | 0.02 | 19 | 0 | 4 | 0 | 6 | 0.02 | 19 | 0 | 4 | 0 | 6 |
| 2 | R | 0.80 | 27 | 8 | 676 | 17 | 54 | 0.80 | 27 | 8 | 676 | 17 | 54 |
| 3 | L | 0.35 | 82 | 0 | 131 | 3 | 24 | 0.35 | 82 | 0 | 131 | 3 | 24 |
| 3 | Т | 0.80 | 27 | 13 | 1049 | 27 | 54 | 0.80 | 27 | 13 | 1049 | 27 | 54 |
| 3 | R | 0.80 | 6 | 3 | 176 | 5 | 18 | 0.80 | 6 | 3 | 176 | 5 | 18 |
| 4 | L | 0.12 | 22 | 0 | 31 | 1 | 6 | 0.12 | 22 | 0 | 31 | 1 | 6 |
| 4 | Т | 0.02 | 13 | 0 | 5 | 0 | 6 | 0.02 | 13 | 0 | 5 | 0 | 6 |
| 4 | R | 0.80 | 23 | 8 | 590 | 16 | 48 | 0.80 | 23 | 8 | 590 | 16 | 48 |
| INT | | 0.80 | 105 | | | | | 0.80 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay PM Peak File = VICF Isolated Operation

| | | Co-ordinated | | | Cvolo | Longth | | | | | | | |
|-----|---|--------------|-------|------|-------|--------|------|-----------------------|-------|------|------|-------|------|
| | | (| | | 2 | 0 | | isolated Gyble Length | | | | | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 816 | 0.1 | 0.5 | | | | 816 | 0.1 | 0.5 |
| 1 | Т | 50 | 0.6 | 46.7 | 609 | 3.7 | 22.0 | 50 | 0.6 | 46.7 | 609 | 3.7 | 22.0 |
| 1 | R | | | | 546 | 6.9 | 45.2 | | | | 546 | 6.9 | 45.2 |
| 2 | L | | | | 218 | 0.5 | 8.0 | | | | 218 | 0.5 | 8.0 |
| 2 | Т | 50 | 0.6 | 46.7 | 6 | 0.1 | 35.3 | 50 | 0.6 | 46.7 | 6 | 0.1 | 35.3 |
| 2 | R | | | | 779 | 8.4 | 38.7 | | | | 779 | 8.4 | 38.7 |
| 3 | L | | | | 476 | 0.5 | 3.6 | | | | 476 | 0.5 | 3.6 |
| 3 | Т | 50 | 0.6 | 46.7 | 1229 | 12.8 | 37.5 | 50 | 0.6 | 46.7 | 1229 | 12.8 | 37.5 |
| 3 | R | | | | 166 | 3.0 | 65.0 | | | | 166 | 3.0 | 65.0 |
| 4 | L | | | | 43 | 0.4 | 33.3 | | | | 43 | 0.4 | 33.3 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 40.4 | 0 | 0.0 | | 6 | 0.1 | 40.4 |
| 4 | R | | | | 666 | 7.7 | 41.7 | | | | 666 | 7.7 | 41.7 |
| INT | | 150 | 2 | 46.7 | 5560 | 44 | 28.5 | 150 | 2 | 46.7 | 5560 | 0 | 0.0 |
| | | | | | | | | | | | | | |

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| тсѕ | = | 110 F | | | | | | | | File = ion | | | |
|-----|---|-------|-----|------|------|------|------|------|-----|---------------|----|----|--|
| А | М | Peds | - | | • | | | | | | | | |
| 1 | L | | 2 | | 816 | 0.0 | 0.0 | .0 | 0.0 | А | 0 | 6 | |
| 1 | Т | 50 | 0.6 | 46.7 | 609 | 13.3 | 78.5 | 795 | 1.3 | F | 11 | 24 | |
| 1 | R | | | | 546 | 0.8 | 5.0 | 16 | 0.0 | А | 0 | 6 | |
| 2 | L | | | | 218 | 0.5 | 8.0 | 82 | 0.4 | Α | 2 | 18 | |
| 2 | Т | 50 | 0.6 | 46.7 | 6 | 0.1 | 35.3 | 4 | 0.7 | С | 0 | 6 | |
| 2 | R | | | | 779 | 8.4 | 38.7 | 676 | 0.9 | С | 17 | 54 | |
| 3 | L | | | | 476 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | Т | 50 | 0.6 | 46.7 | 1229 | 2.6 | 7.5 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | 166 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 4 | L | | | | 43 | 0.4 | 33.3 | 31 | 0.7 | С | 1 | 6 | |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 40.4 | 5 | 0.8 | С | 0 | 6 | |
| 4 | R | | | | 666 | 7.7 | 41.7 | 590 | 0.9 | С | 16 | 48 | |
| INT | | 150 | 2 | 46.7 | 5560 | 34 | 21.8 | 2199 | 0.4 | В | | | |
| | | | | | | | | | | | | | |

| TCS | = | 110 I | solate | ed Opei | ration | Degree | e of S | aturati | on fo | r Busir | ness Pe | eak VI(| CF |
|-----|---|-------|--------|---------|--------|--------|--------|---------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.10 | 32 | 0 | 41 | 1 | 6 | 0.10 | 32 | 0 | 41 | 1 | 6 |
| 1 | Т | 0.00 | 15 | 0 | 5 | 0 | 6 | 0.00 | 15 | 0 | 5 | 0 | 6 |
| 1 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 2 | L | 0.07 | 47 | 0 | 16 | 0 | 6 | 0.07 | 47 | 0 | 16 | 0 | 6 |
| 2 | Т | 0.44 | 15 | 2 | 342 | 5 | 18 | 0.44 | 15 | 2 | 342 | 5 | 18 |
| 2 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 3 | L | 0.10 | 32 | 0 | 41 | 1 | 6 | 0.10 | 32 | 0 | 41 | 1 | 6 |
| 3 | Т | 0.00 | 15 | 0 | 5 | 0 | 6 | 0.00 | 15 | 0 | 5 | 0 | 6 |
| 3 | R | 0.34 | 5 | 1 | 91 | 2 | 6 | 0.34 | 5 | 1 | 91 | 2 | 6 |
| 4 | L | 0.15 | 22 | 0 | 60 | 1 | 6 | 0.15 | 22 | 0 | 60 | 1 | 6 |
| 4 | Т | 0.51 | 13 | 2 | 359 | 5 | 18 | 0.51 | 13 | 2 | 359 | 5 | 18 |
| 4 | R | 0.40 | 5 | 1 | 92 | 2 | 6 | 0.40 | 5 | 1 | 92 | 2 | 6 |
| INT | | 0.51 | 56 | | | | | 0.51 | 56 | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay Business Peak File = VICF Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 102 | 0.2 | 5.3 | | | | 102 | 0.2 | 5.3 |
| 1 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 |
| 1 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 2 | L | | | | 102 | 0.0 | 0.8 | | | | 102 | 0.0 | 0.8 |
| 2 | Т | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 | 25 | 0.2 | 22.3 | 457 | 2.2 | 17.1 |
| 2 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 3 | L | | | | 102 | 0.2 | 5.3 | | | | 102 | 0.2 | 5.3 |
| 3 | Т | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 | 25 | 0.2 | 22.3 | 7 | 0.0 | 14.7 |
| 3 | R | | | | 108 | 0.7 | 24.1 | | | | 108 | 0.7 | 24.1 |
| 4 | L | | | | 102 | 0.3 | 11.2 | | | | 102 | 0.3 | 11.2 |
| 4 | Т | 0 | 0.0 | | 457 | 2.4 | 18.8 | 0 | 0.0 | | 457 | 2.4 | 18.8 |
| 4 | R | | | | 108 | 0.7 | 24.2 | | | | 108 | 0.7 | 24.2 |
| INT | | 75 | 0 | 22.3 | 1768 | 8 | 16.6 | 75 | 0 | 22.3 | 1768 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay - Stops Business Peak File = VICF ----- Delays & Stops after Co-ordinated Evaluation-----A M Peds Delay Aver Vehs Delay Aver Stops Aver LOS 1 L 102 0.0 0.0 0 0.0 А 0 6 0.3 25 0.2 22.3 0.0 0.4 2 0 6 1 T 7 Α 1 R 108 0.2 5.0 2 0.0 А 0 6 2 102 0 6 L 0.0 0.8 16 0.2 А 2 Т 25 0.2 22.3 457 2.2 17.1 342 0.7 В 5 18 2 R 108 0.7 24.1 91 0.8 В 1 6 3 L 0.0 0 6 102 0.0 0 0.0 А 3 T 0.2 22.3 25 0.0 0.0 0 0.0 А 0 6 7 0.0 3 R 108 0.0 0 6 0 0.0 А 4 L 102 0.3 11.2 60 0.6 А 1 6 4 T 457 18.8 359 0.8 18 0 0.0 2.4 В 5 4 R 108 0.7 24.2 92 0.9 В 1 6 INT 75 0 22.3 1768 963 0.5 7 13.2 А

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TCS = 110 Isolated Operation Degree of Saturation for AM Peak VICF --- Co-ordinated Cycle Length --- Isolated Cycle Length -----GT Delay Stops Queue Metre DS DS GT Delay Stops Queue Metre A M 6 0.21 106 0 20 1 L 0.21 134 0 16 1 1 6 0.68 80 9 1012 78 0.54 57 8 973 24 54 1 T 27 1 R 0.89 37 11 650 22 84 0.89 24 11 684 19 60 2 L 0.51 93 2 269 8 48 0.53 71 2 295 7 42 2 Т 0.03 15 0 5 0 6 0.02 15 0 5 0 6 6 276 2 261 30 R 0.89 10 6 10 36 0.89 8 9 1 3 3 L 84 1 135 0.37 99 162 36 0.34 24 5 3 T 0.89 23 1555 96 0.89 19 1572 48 47 38 38 78 3 R 0.82 5 3 124 5 18 0.66 5 2 97 3 12 4 L 0.05 37 15 6 0.05 0 1 28 0 15 1 6 4 0 4 4 T 0.02 27 0 0 6 0.01 24 0 6 4 R 0.89 24 11 552 20 66 0.89 19 9 569 17 54 INT 0.89 140 0.89 112 _____

| TCS | = | 110 | Pedestr | ian - | - Vehi | cle Dela | ay AM | Peak | File = | VICF | | | |
|-----|---|------|---------|-------|--------|----------|-------|-------|---------|--------|--------|---------|------|
| | | | | | I | solated | Opera | ation | | | | | |
| | | | Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| А | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 347 | 0.0 | 0.1 | | | | 347 | 0.0 | 0.2 |
| 1 | Т | 50 | 0.9 | 64.1 | 1600 | 9.4 | 21.0 | 50 | 0.7 | 50.2 | 1600 | 8.3 | 18.6 |
| 1 | R | | | | 702 | 11.3 | 57.7 | | | | 702 | 10.5 | 54.0 |
| 2 | L | | | | 588 | 2.0 | 12.0 | | | | 588 | 1.9 | 11.6 |
| 2 | Т | 50 | 0.9 | 64.1 | 6 | 0.1 | 56.0 | 50 | 0.7 | 50.2 | 6 | 0.1 | 42.1 |
| 2 | R | | | | 228 | 6.3 | 99.4 | | | | 228 | 5.5 | 86.9 |
| 3 | L | | | | 449 | 1.0 | 8.3 | | | | 449 | 0.6 | 4.6 |
| 3 | Т | 50 | 0.9 | 64.1 | 1787 | 22.9 | 46.1 | 50 | 0.7 | 50.2 | 1787 | 18.9 | 38.0 |
| 3 | R | | | | 109 | 3.0 | 98.1 | | | | 109 | 1.6 | 52.7 |
| 4 | L | | | | 22 | 0.2 | 38.7 | | | | 22 | 0.2 | 31.6 |
| 4 | Т | 0 | 0.0 | | 6 | 0.1 | 45.6 | 0 | 0.0 | | 6 | 0.1 | 34.4 |
| 4 | R | | | | 564 | 11.0 | 70.5 | | | | 564 | 9.3 | 59.7 |
| INT | | 150 | 3 | 64.1 | 6408 | 67 | 37.8 | 150 | 2 | 50.2 | 6408 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |

TCS = 110 Pedestrian - Vehicle Delay - Stops AM Peak File = VICF ----- Delays & Stops after Co-ordinated Evaluation------A M Peds Delay Aver Vehs Delay Aver Stops Aver LOS 1 L 347 0.0 0.0 0 0.0 Α 0 6 1 T 50 0.9 64.1 1600 33.5 75.5 1961 1.2 F 27 78 0.0 1 R 702 0.9 4.6 25 А 1 6 2 L 2.0 12.0 588 269 0.5 Α 8 48 2 T 50 0.9 64.1 0.1 56.0 0.8 0 6 6 5 D 2 R 228 6.3 99.4 261 1.1 F 10 36 0 3 L 449 0.0 0.0 0.0 Α 0 6 3 T 50 0.9 64.1 1787 0 0.0 0 6 4.6 9.2 А 3 R 0.0 0 6 109 0.0 0.0 0 А 15 1 4 L 22 0.2 38.7 0.7 С 6 4 T 0 0.0 6 0.1 45.6 4 0.7 D 0 6 4 R 564 11.0 70.5 552 1.0 F 20 66

59 33.0 3092

С

0.5

150 3 64.1 6408

INT

Church Street Existing – CHURCHX.DAT

SCATES Program Version: 2013 Date: 02-NOV-12 Time: Registered User Name. - Road Delay Solutions Pty Ltd Registered User No. - 0 Data File: CHURCHX CHURCH STREET 2010 EXISTING VOLUMES

| | | | AM PE/ | ٩K | | | | PM PE/ | ٩K | | | E | BUSINE | SS | |
|-------------|-------------------|-------|---------------|----|---------------|-------------|------|-------------------|----|--------------------|------|------|-----------------|----------------|-----|
| AM | Vol | Sat | Phse | | | | Sat | Phse | | | | Sat | Phse | | |
| | | | | | Loss | | | | | Loss | | | | Gain | |
| 1L | ~~ ~ 4 | | | | 0.0 | | | | | 0.0 | | | | 0 | 0.0 |
| 1T | 2974 | 5880 | A | | | 3010 | 5880 | A | | | 2094 | 5880 | A | | |
| 1R 2L | | | | | | | | | | | | | | | |
| 2L 2T | | | | | | | | | | | | | | | |
| 21 2R | | | | | | | | | | | | | | | |
| 3L | | | | 0 | 0.0 | | | | 0 | 0.0 | | | | 0 | 0.0 |
| 3T | 3194 | 5880 | А | - | | 3191 | 5880 | А | - | | 2235 | 5880 | А | Ő | 97 |
| 3R | | | | | | | | | | | | | | | |
| 4L | | | | | | | | | | | | | | | |
| 4T | | | | | | | | | | | | | | | |
| 4R | | | | | | | | | | | | | | | |
| Туре | | | | | | А | | Walk | | H%PM | | | | | |
| File | = CH | URCHX | | | | 1 | | | 2 | 2 | 3 | | | | |
| | | | | | | 2 | | 28 | | | | | | | |
| TCS = | = 19 | 56 | | | | 3 | | | 2 | 2 | 3 | | | | |
| | | | | | | 4 | | | | | | | -DEOT | - | |
| | | | TRIAN | | | | | ARANCI | = | TRAM I | JATA | | EDEST | TRA | |
| Арр | P# | | P#PM | | #B | Wall | | Clear | | | | | ACT | FAC | |
| 1 | 0 | | 0 | | 0 | 0 | | 0 | | 0% | | | 100 | 10 | |
| | - | - | | | | | | | | | | | | | |
| | - | | - | | - | - | | - | | | | | | | |
| 4 | 2 | U | 20 | 2 | 20 | 6 | 2 | 22 | (| J % | | ć | 30 | 10 | 0 |
| 2 3 4 | 3 0 2 | - | 30 0 20 | (| 30 0 20 | 6 0 6 | (| 22 0 22 | (| 0% 0% 0% | | - | 30 100 30 | 10 10 10 | 00 |

| | | | AM PEA | ٩K | | | F | M PEA | ٩K | | | E | BUSINE | ESS | |
|------|------|------|--------|------|------|------|------|-------|------|------|------|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 18 | 1750 | Α | 0 | 0.0 | 64 | 1750 | Α | 0 | 0.0 | 29 | 1750 | Α | 0 | 0.0 |
| 1T | 2974 | 5670 | Α | 18 | 0 | 3010 | 5670 | Α | 65 | 0 | 2094 | 5670 | Α | 30 | 0 |
| 1R | | | | | | | | | | | | | | | |
| 2L | | | | | | | | | | | | | | | |
| 2T | | | | | | | | | | | | | | | |
| 2R | | | | | | | | | | | | | | | |
| 3L | | | | 0 | 0.0 | | | | 0 | 0.0 | | | | 0 | 0.0 |
| ЗT | 3194 | 5880 | Α | 0 | 120 | 3191 | 5880 | AB | 0 | 103 | 2235 | 5880 | AB | 0 | 79 |
| ЗR | 0 | 1800 | S | | | 0 | 1800 | В | | | 0 | 1800 | В | | |
| 4L | 67 | 1750 | В | | | 37 | 1750 | BC | | | 36 | 1750 | BC | | |
| 4T | | 3600 | | | | | 3600 | | | | | 3600 | | | |
| 4R | 152 | 3600 | В | | | 125 | 3600 | С | | | 97 | 3600 | С | | |
| Туре | = T4 | | | | | А | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |

Page | 113

| File = | CHURCH | х | | 1 2 | 22 | 4.0 | 2 | 2 | 3 | 0 ' | 0 | |
|--------|--------|----------|-------|-------------|---------|------------|--------|--------|--------|-----|---|--------|
| TCS = | 448 | | | 2 3 4 | 5 28 | 4.0 4.0 | 2 0 | 2 0 | 3 0 | 0 ' | 0 | 0 0 |
| | PEDE | STRIAN V | OLUME | 4 WALK- | | | - | AM DA | - | PED | - | TRAM |
| Арр | P#AM | P#PM | P#B | Walk | C | lear | | | | FAC | т | FACT |
| 1 | 50 | 50 | 30 | 6 | 10 | 6 | 0% | | | 30 |) | 100 |
| 2 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 10 | 0 | 100 |
| 3 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 10 | 0 | 100 |
| 4 | 50 | 50 | 30 | 6 | 2 | 2 | 0% | | | 30 |) | 100 |
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| | | AM PE | ٩K | | | F | M PE | ٩K | | | 1 | BUSIN | ESS | |
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| AM V | ol Sa | t Phse | | | | Sat | Phse | | | | Sat | Phse | | |
| 1L | 9 175 | D A | Gain O | | | 1750 | А | | Loss 0.0 | | 1750 | А | | Loss 0.0 |
| | 40 556 | | 112 | | 3028 | 5560 | А | 0 | | 2159 | 5560 | Α | 40 | 0 |
| | 0 02 175 | | | | - | 0 1750 | S B | | | - | 0 1750 | S B | | |
| | 92 196 | | | | | 1960 | B | | | | 1960 | B | | |
| | - | D B | | ~ ~ | | 0 | В | | | 0 | - | В | 0 | 0.0 |
| | 30 175 12 567 | | | 0.0 | | 1750 5670 | A | | 0.0 | | 1750 5670 | A A | | 0.0 |
| ЗR | 0 | D S | | | | 0 | S | | | 0 | 0 | S | | |
| | 20 175 | | | | 26 188 | | B B | | | 16 142 | | | | |
| 4T 2 4R | 0 0 | | | | 188 | | B | | | | 1960 | B B | | |
| Type = | | | | | Α | Min | ELT | H%AM | H%PM | | | | R - PD | |
| File = | CHURCH | x | | | 1 | 5 5 | 4.0 | | 2 1 | | 0' 0' | 0 | 0 | |
| TCS = | 11 | | | | | 5 5 | 4.0 | | | 23 | | 0 | - | |
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| Ann | | STRIAN P#PM | | | | <-CLEA < C | | | TRAM I | DATA | | EDEST ACT | TR/ FA | |
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| Tidal N Lane 1 2 3 4 5 6 7 8 Apprch Depart File = | Type T T T No AM 0 CHURCH | Length 9999 9999 9999 Parki PM 0 0 | 0 Sat 1960 1960 1960 BUS 0 0 | Туре М АМ | e Len(lo Pai Pi | rking M E | at ⁻ | Type T T T No | 3 Lengtl 9999 9999 9999 9999 | (1 Sat 1960 1960 1960 1960 BUS |) t Ty)) | oe Le No Pa | ngth | Sat |
| N Lane 1 2 3 4 5 6 7 8 8 Apprch Depart | Type T T T AM O CHURCH: M | 3 Length 9999 9999 9999 Parki PM 0 0 | 0 Sat 1960 1960 1960 BUS 0 0 | Type AM TCS = | e Lenç Io Pai | rking A E | sus | Гуре I T T No AM 0 0 | 3 Lengtl 9999 9999 9999 9999 Park: PM 0 0 | (n Sa ⁺ 196(196(196(196(196(196(((|) t Ty))) S A | oe Le No Pa | ngth arking | Sat |
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| N Lane 1 2 3 4 5 6 7 8 Apprch Depart File = | Type T T T No AM 0 CHURCH M | 3 Length 9999 9999 9999 Parki PM 0 0 X | 0 Sat 1960 1960 1960 BUS 0 0 | Type AM TCS = | e Lenç Io Pai Pi - 1956 | rking A E | sus | Гуре I T T AM O | 3 Lengtl 9999 9999 9999 9999 Park: PM 0 0 | ing BUS (1960 1960 1960 (0 (0 |) t Ty))) S A) | No Pa M 1 | ngth arking PM | Sat BUS |
| N Lane 1 2 3 4 5 6 7 8 Apprch Depart File = Type = Type = | Type T T T No AM O CHURCH M A Down | 3 Length 9999 9999 9999 Parki PM 0 X PPROACI | 0 Sat 1960 1960 1960 BUS 0 0 | Type AM TCS = | e Leng Io Pai Pi = 1956 | rking A E DACH 2 | sus | Type I T T No AM 0 0 | 3 Lengtl 9999 9999 9999 Park: PM 0 0 | (1 Sa ⁺ 196(196(196(196(|) t Ty))) S Al | No Pa M 1 | arkin PM ROACH anes (| Sat BUS Grade |
| N Lane 1 2 3 4 5 6 7 8 Apprch Depart File = Type = Type = | Type T T T No AM O CHURCHI M M Down O | 3 Length 9999 9999 9999 Parki PM 0 X PPROACI Lanes 3 | 0 Sat 1960 1960 BUS 0 0 H 1 Grade 0 | Type AM TCS = Dowr | e Lenç lo Pai Pi = 1956 APPR(1 Lai | rking A E DACH 2 nes Gr | Sus | Type I T T AM O O O O O V O V O V O V O V O V O V O | 3 Lengtl 9999 9999 9999 9999 9999 9999 0 0 0 0 | (n Sa ⁺ 196(196(196(196(196(196(0) 0) 0) 0) 0) 0) 0) 0) 0) 0) 0) 0) 0) |) t Ty))) S A)) | No Pa M 1 APPI wn La | arkin PM ROACH anes 0 2 | Sat BUS Grade 0 |
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| N Lane 1 2 3 4 5 6 7 8 Apprch Depart File = Type = Type = Tidal N Lane | Type T T T No AM O CHURCH M M Down O Type | 3 Length 9999 9999 9999 Parki PM 0 0 X PPROACI Lanes 3 Length 9999 | 0 Sat 1960 1960 1960 BUS 0 0 0 H 1 Grade 0 Sat 1750 | Type AM TCS = Dowr | e Lenç lo Pai Pi = 1956 APPR(1 Lai | rking A E DACH 2 nes Gr | Sus | Гуре I T T AM O O O O Cype I T | 3 Lengtl 9999 9999 9999 9999 Park: PM 0 0 0 | (1 Sa ⁺ 196(196(196(196(CH 3 5 Grac (1 Sa ⁺ 196(|) t Ty)))) de Dov) t Ty)) | No Pa M I APPI Wn La De Lei LR 93 | arkin PM ROACH anes 0 2 ngth | Sat BUS Grade 0 Sat 1750 |

Page | 115

| 3 4 5 | Т | 9999 | 1960 | | | | Т | 9999 | 1960 | | | |
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| | AM | PM | BUS | AM | PM | BUS | AM | PM | BUS | AM | PM | BUS |
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| Apprch Depart | AM | PM | BUS | | | - | AM | PM | BUS | AM | PM | BUS |
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| Depart | AM O O HURCHX | PM 0 0 | BUS 0 0 | | | - | AM O | PM O | BUS 0 | AM O | PM O | BUS 0 |

APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 Tidal Down Lanes Grade Down Lanes Grade Down Lanes Grade Down Lanes Grade N 0 3 0 0 2 0 0 3 0 0 2 0 Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane LT 9999 1750 L 90 1750 LT 9999 1750 L 9999 1750 T 9999 1960 T 9999 1960 T 9999 1960 T 9999 1960 T 9999 1850 T 9999 1960 1 2 3 4 5 6 7 8 No Parking No Parking No Parking No Parking
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 File = CHURCHX
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Req Act Req Act 10 0 TCS = 448Τ4 1

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| B 19.1 19.1 21 C D | RD ISOL CORD ISOL | BUSINESS GT% GT% CL CL CORD ISOL CORD ISOL 80.8 77.7 108 48 19.2 22.3 |
|--|---|---|
| E F G Seq AB dlay 20 Stps 3.8 Mode CHURCHX A TCS = 11 CHURCHX A CCS = 11 CCS = 111 CCS = 111 CCS = 1111 CCS = 1111 CCS = 11111 CCS = 11111111111111111111111111111111 | dlay dlay 0.0 0.0 AB dlay 23 23 Stps 4.0 4.0 0 DS 0.80 0.80 Bay Bay Slip Sli Req Act Req Act 10 0 60 90 17 0 | 0.0 0.0 AB dlay 12 7 Stps 2.0 2.5 0 DS 0.55 0.61 p Type COCO |
| | Bays if all interse | ctions are optimised |
| TCS = 1956 Isolated Operation Do Co-ordinated Cycle Lo A M DS GT Delay Stops Qu 1 L | ength Isol | |
| 1 T 0.74 78 8 1682 1 R 2 L 2 T 2 R 3 L | 27 60 0.68 108 | 7 1322 27 60 |
| 3 T 0.78 78 9 1909 3 R 4 L 4 T 4 R | 29 60 0.72 108 | 7 1500 29 60 |
| INT 0.78 110 | 0.72 140 | |
| TCS = 1956 Pedestrian - Vehicl Iso Co-ordinated Cycle Lo A M Peds Delay Aver Vehs Do | lated Operation ength Isol | ated Cycle Length |
| 1 L 1 T 0 0.0 3070 | 8.3 9.7 0 0.0 | - |
| 1 R 2 L 2 T 30 0.4 49.2 2 R 3 L | 30 0.5 | 64.1 |
| | 9.4 10.4 0 0.0 | 3255 7.4 8.2 |

| INT 50 1 49.2 6325 18 10.1 50 1 64.1 6325 0 0. | 4 T 4 B | 20 | 0.3 | 49.2 | | 20 | 0.4 | 64.1 | | |
|--|------------|----|-----|------|--|----|-----|------|--|--|
| | INT | | | | | | | | | |

Addendum - Arterial Road Network

| | | 1956 | | | | | | | | | | | |
|------------------|------------------|------|--------|------|------|--------------------|------|------|--------|-------|--------|-------|------|
| A 1 | | | | | | Delay | | | | | | | |
| 1 1 | T R | 0 | 0.0 | | 3070 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 2 2 | L T R | 30 | 0.4 | 49.2 | | | | | | | | | |
| 3 3 3 | L T R | 0 | 0.0 | | 3255 | 10.3 | 11.4 | 1139 | 0.4 | А | 29 | 60 | |
| 4 | L T R | 20 | | 49.2 | | | | | | | | | |
| INT | | 50 | 1 | | | 10 | | | | A | | | |
| TCS | = | 1956 | | | | | | | | | | | |
| | М | DS | | | | Length Queue | | | | | | | |
| 1 1 1 | L T R | 0.52 | 76 | 4 | 908 | 19 | 42 | 0.50 | 91 | 4 | 798 | 19 | 42 |
| 2 2 2 3 | L T R L | | | | | | | | | | | | |
| 3 3 4 | T R L | 0.56 | 76 | 5 | 1009 | 20 | 42 | 0.53 | 91 | 4 | 886 | 20 | 42 |
| | T R | 0.56 | 108 | | | | | 0.53 | 123 | | | | |
| | | | | | | | | | | | | | |
| TCS | = | 1956 | Pedest | rian | | cle Del solated | | | Peak I | ile = | CHURCH | IX | |
| | | | | | | Length | | | | | | | |
| A 1 | ML | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 1 2 | T R L | 0 | 0.0 | | 2157 | 4.5 | 7.5 | 0 | 0.0 | | 2157 | 3.9 | 6.6 |
| 2 2 | T R | 30 | 0.4 | 48.2 | | | | 30 | 0.5 | 55.6 | | | |
| 3 3 3 | L T R | 0 | 0.0 | | 2302 | 5.0 | 7.8 | 0 | 0.0 | | 2302 | 4.4 | 6.8 |
| | L T R | 20 | 0.3 | 48.2 | | | | 20 | 0.3 | 55.6 | | | |
| INT | | 50 | 1 | 48.2 | | 9 | | 50 | 1 | 55.6 | 4459 | 0 | 0.0 |
| | | | | | | | | | | | | | |

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| TCS | = | 1956 P | | | | | 2 | • | | | File = | CHURCHX |
|-----|---|--------|-----|------|------|-----|-----|---|-----|---|--------|---------|
| А | М | Peds | - | | • | | | | | | | |
| 1 | L | | - | | | - | | | | | | |
| 1 | Т | 0 | 0.0 | | 2157 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | |
| 2 | Т | 30 | 0.4 | 48.2 | | | | | | | | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 2302 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | | | | | | | | |
| 4 | Т | 20 | 0.3 | 48.2 | | | | | | | | |
| 4 | R | | | | | | | | | | | |
| INT | | 50 | 1 | 48.2 | 4459 | 0 | 0.0 | 0 | 0.0 | Α | | |
| | | | | | | | | | | | | |

TCS = 1956 Isolated Operation Degree of Saturation for AM Peak CHURCHX --- Co-ordinated Cycle Length ---- Isolated Cycle Length -----DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre А Μ 1 L 1 T 0.74 73 8 1718 27 54 0.74 73 8 1718 27 54 R 1 2 L 2 Т 2 R 3 L 0.80 73 10 2004 29 60 0.80 73 10 2004 Т 29 3 60 3 R 4 L 4 T 4 R INT 0.80 105 0.80 105 _____ TCS = 1956 Pedestrian - Vehicle Delay AM Peak File = CHURCHX Isolated Operation --- Co-ordinated Cycle Length ---- Isolated Cycle Length -----Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh Delay Aver А М 1 L Т 0 0.0 3033 8.5 10.1 0 0.0 3033 8.5 10.1 1 1 R 2 L 2 Т 30 0.4 46.7 30 0.4 46.7 2 R 3 L 0.0 3258 9.9 10.9 0 0.0 3258 9.9 10.9 3 T 0 3 R 4 L 4 Т 20 0.3 46.7 20 0.3 46.7 4 R 50 1 46.7 6291 18 10.5 50 1 46.7 6291 0 0.0 INT TCS = 1956 Pedestrian - Vehicle Delay - Stops AM Peak File = CHURCHX ----- Delays & Stops after Co-ordinated Evaluation------A M Peds Delay Aver Vehs Delay Aver Stops Aver LOS 1 L 0 0.0 3033 0.0 0.0 0 0.0 A 0 1 T 6 R 1 2 L 2 Т 30 0.4 46.7 2 R 3 L 1.5 1.7 265 0.1 A 3 Т 0 0.0 3258 8 18 3 R 4 L 4 T 20 0.3 46.7 4 R INT 50 1 46.7 6291 2 0.9 265 0.0 A

November 2012

| TCS | = | 448 I | solate | ed Oper | ration | Degree | e of Sa | turati | on fo | r PM Pe | eak CHU | JRCHX | |
|-----|---|-------|--------|---------|--------|--------|---------|--------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength – | |
| Α | Μ | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.72 | 85 | 0 | 31 | 0 | 6 | 0.67 | 114 | 0 | 24 | 0 | 48 |
| 1 | Т | 0.72 | 85 | 6 | 1436 | 22 | 48 | 0.68 | 114 | 5 | 1143 | 22 | 48 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | | | | | | | | | | | | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | |
| 3 | т | 0.65 | 94 | 2 | 985 | 15 | 30 | 0.63 | 123 | 2 | 789 | 15 | 36 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.36 | 17 | 0 | 30 | 1 | 6 | 0.45 | 18 | 1 | 31 | 1 | 12 |
| 4 | т | | | | | | | | | | | | |
| 4 | R | 0.56 | 8 | 2 | 109 | 4 | 18 | 0.68 | 9 | 2 | 110 | 5 | 18 |
| INT | | 0.72 | 110 | | | | | 0.68 | 140 | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 448 | Pedestr | ian | | | - | | Peak F | ile = | CHURCH | łX | |
|-----|---|------|---------|--------|-------|---------|-------|-------|---------|---------|--------|---------|------|
| | | | | | Is | solated | 0pera | ation | | | | | |
| | | | Co-ordi | .nated | Cycle | Length | | | - Isola | ited Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 30 | 0.0 | 4.9 | | | | 30 | 0.0 | 4.3 |
| 1 | Т | 30 | 0.4 | 48.2 | 2157 | 2.9 | 4.9 | 30 | 0.5 | 55.6 | 2157 | 2.6 | 4.3 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | C | 0.0 | | | | | 0 | 0.0 | | | | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | |
| 3 | Т | C | 0.0 | | 2302 | 1.3 | 2.1 | 0 | 0.0 | | 2302 | 1.2 | 1.8 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 36 | 0.4 | 39.9 | | | | 36 | 0.5 | 47.5 |
| 4 | Т | 30 | 0.4 | 48.2 | | | | 30 | 0.5 | 55.6 | | | |
| 4 | R | | | | 97 | 1.3 | 47.5 | | | | 97 | 1.5 | 55.1 |
| INT | | 60 |) 1 | 48.2 | 4622 | 6 | 4.6 | 60 | 1 | 55.6 | 4622 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |

| | | | Pedest - Dela | | | | | | | | | | RCHX |
|--------|--------|-------|------------------|---|--------|---------|---------|--------|--------|---------|---------|-------|------|
| А | | | Delay | | | | | | | | | | |
| | L | | | 40.0 | | 0.0 | 0.0 | | 0.0 | A | 0 | 6 | |
| | Т | 30 | 0.4 | 48.2 | 2157 | 0.0 | 0.0 | 0 | 0.0 | A | 0 | 6 | |
| | R L | | | | | | | | | | | | |
| | Т | C | 0.0 | | | | | | | | | | |
| 2 | R | | | | | | | | | | | | |
| | L | | | | | | | | | | | | |
| | Т | 0 | 0.0 | | 2302 | 0.1 | 0.2 | 36 | 0.0 | A | 1 | 6 | |
| | R L | | | | 36 | 0.4 | 39.9 | 29 | 0.8 | С | 1 | 6 | |
| | T | 30 | 0.4 | 48.2 | | 0.4 | 59.9 | 29 | 0.0 | U | 1 | 0 | |
| | R | 00 | 011 | 1012 | | 1.3 | 47.5 | 83 | 0.9 | D | 3 | 12 | |
| INT | | 60 |) 1 | 48.2 | 4622 | | 1.4 | | | | | | |
| | | | | | | | | | | | | | |
| TCS | = | 448 | Isolat | ed Ope | ration | Degree | e of Sa | aturat | ion fo | r AM Pe | eak CHI | JRCHX | |
| | | | Co-ord | | | | | | | | | | |
| | М | DS | | Delay | Stops | Queue | Metre | DS | GT | Delay | | | |
| | L | 0.39 | | 0 | 5 | 0 17 | 6 | 0.39 | 85 | 0 | 5 | | 6 |
| | T R | 0.67 | 85 | 4 | 1155 | 17 | 42 | 0.67 | 85 | 4 | 1155 | 17 | 42 |
| | L | | | | | | | | | | | | |
| | Т | | | | | | | | | | | | |
| | R | | | | | | | | | | | | |
| | L | | | | | | | | | _ | | | |
| | Т | 0.69 | 85 | 4 | 1286 | 18 | 42 | 0.69 | 85 | 4 | 1286 | 18 | 42 |
| 3 4 | R L | 0.69 | 12 | 1 | 59 | 2 | 12 | 0.69 | 12 | 1 | 59 | 2 | 12 |
| | Т | 0.00 | | • | | _ | | 0100 | | • | 00 | - | . – |
| 4 | R | | | 2 | 128 | 4 | 18 | 0.46 | 12 | 2 | 128 | 4 | 18 |
| INT | | 0.69 | 105 | | | | | 0.69 | 105 | | | | |
| | | | | | | | | | | | | | |
| TCS | = | 448 | Pedest | rian | | | | | File = | CHURCH | łX | | |
| | | | Co-ord | inatod | | solated | | | | ated C | | anath | |
| А | М | | Delay | | | | | | | | | | |
| 1 | L | 1 ouo | Doray | ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | | 0.0 | | | Doray | / | 18 | | |
| 1 | Т | 50 | 0.6 | 46.7 | | | | | 0.6 | 46.7 | | | |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 2 | Т | C | 0.0 | | | | | 0 | 0.0 | | | | |
| | R L | | | | | | | | | | | | |
| | T | C | 0.0 | | 3258 | 4.1 | 4.5 | 0 | 0.0 | | 3258 | 4.1 | 4.5 |
| | R | - | | | | | | - | | | | | |
| 4 | L | | | | 67 | 0.9 | 45.9 | | | | 67 | 0.9 | 45.9 |
| | Т | 50 | 0.6 | 46.7 | | | | 50 | 0.6 | 46.7 | | | |
| | R | 100 | | 16 7 | 152 | | 43.2 | | 4 | 16 7 | 152 | | |
| INT | | |) 1 | | | 10 | | | 1 | | 6528 | 0 | |
| | | | | | | | | | | | | | |

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| TCS | = | 448 P | | | | cle Del fter Co | 2 | • | | | | НХ |
|-----|---|-------|-----|------|------|--------------------|------|-----|-----|-----|----|----|
| A | м | Peds | - | | • | | | | | LOS | | |
| 1 | L | | , | | 18 | 0.0 | | 4 | 0.2 | A | 0 | 6 |
| 1 | Т | 50 | 0.6 | 46.7 | 3033 | 4.1 | 4.9 | 715 | 0.2 | А | 17 | 42 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | |
| 2 | Т | 0 | 0.0 | | | | | | | | | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 3258 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 67 | 0.9 | 45.9 | 59 | 0.9 | D | 2 | 12 |
| 4 | Т | 50 | 0.6 | 46.7 | | | | | | | | |
| 4 | R | | | | 152 | 1.8 | 43.2 | 128 | 0.8 | D | 4 | 18 |
| INT | | 100 | 1 | 46.7 | 6528 | 7 | 3.8 | 906 | 0.1 | А | | |
| | | | | | | | | | | | | |

| TCS | = | 11 I | solat | ed Opei | ration | Degree | e of Sa | turati | on foi | ° PM P€ | ak CHL | JRCHX | |
|-----|---|------|--------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | ו ו | | Isola | ated Cy | /cle Le | ength · | |
| Α | Μ | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.40 | 83 | 0 | 5 | 0 | 6 | 0.40 | 83 | 0 | 5 | 0 | 6 |
| 1 | Т | 0.75 | 83 | 7 | 1568 | 23 | 54 | 0.75 | 83 | 7 | 1568 | 23 | 54 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.60 | 19 | 2 | 153 | 5 | 30 | 0.60 | 19 | 2 | 153 | 5 | 30 |
| 2 | Т | 0.80 | 19 | 4 | 258 | 7 | 48 | 0.80 | 19 | 4 | 258 | 7 | 48 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.80 | 83 | 1 | 119 | 2 | 54 | 0.80 | 83 | 1 | 119 | 2 | 54 |
| 3 | Т | 0.80 | 83 | 7 | 1763 | 24 | 54 | 0.80 | 83 | 7 | 1763 | 24 | 54 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.09 | 19 | 0 | 20 | 1 | 6 | 0.09 | 19 | 0 | 20 | 1 | 6 |
| 4 | Т | 0.56 | 19 | 2 | 156 | 5 | 30 | 0.56 | 19 | 2 | 156 | 5 | 30 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.80 | 110 | | | | | 0.80 | 110 | | | | |
| | | | | | | | | | | | | | |

TCS = 11 Pedestrian - Vehicle Delay PM Peak File = CHURCHX Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | Isola | ted Cy | cle Le | ngth - | |
|-----|---|------|---------|-------|-------|--------|------|------|-------|--------|--------|--------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 17 | 0.0 | 4.8 | | | | 17 | 0.0 | 4.8 |
| 1 | Т | 0 | 0.0 | | 3089 | 6.6 | 7.7 | 0 | 0.0 | | 3089 | 6.6 | 7.7 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 184 | 2.1 | 41.9 | | | | 184 | 2.1 | 41.9 |
| 2 | Т | 0 | 0.0 | | 272 | 3.9 | 51.7 | 0 | 0.0 | | 272 | 3.9 | 51.7 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | 206 | 0.6 | 10.6 | | | | 206 | 0.6 | 10.6 |
| 3 | Т | 0 | 0.0 | | 3174 | 7.4 | 8.4 | 0 | 0.0 | | 3174 | 7.4 | 8.4 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 26 | 0.3 | 38.0 | | | | 26 | 0.3 | 38.0 |
| 4 | Т | 0 | 0.0 | | 190 | 2.2 | 41.5 | 0 | 0.0 | | 190 | 2.2 | 41.5 |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 7158 | 23 | 11.6 | | | | 7158 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 11 Pedestrian - Vehicle Delay - Stops PM Peak File = CHURCHX ----- Delays & Stops after Co-ordinated Evaluation-----

| Α | Μ | Peds | Delay | Aver Vehs | Delay | Aver | Stops | Aver | LOS | | | |
|-----|---|------|-------|-----------|-------|------|-------|------|-----|----|----|--|
| 1 | L | | | 17 | 0.0 | 1.6 | 2 | 0.1 | Α | 0 | 6 | |
| 1 | Т | 0 | 0.0 | 3089 | 1.4 | 1.6 | 345 | 0.1 | А | 11 | 24 | |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 184 | 2.1 | 41.9 | 153 | 0.8 | С | 5 | 30 | |
| 2 | Т | 0 | 0.0 | 272 | 3.9 | 51.7 | 258 | 0.9 | D | 7 | 48 | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 206 | 0.1 | 1.6 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | Т | 0 | 0.0 | 3174 | 1.4 | 1.6 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 26 | 0.3 | 38.0 | 20 | 0.8 | С | 1 | 6 | |
| 4 | Т | 0 | 0.0 | 190 | 2.2 | 41.5 | 156 | 0.8 | С | 5 | 30 | |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7158 | 11 | 5.7 | 933 | 0.1 | Α | | | |
| | | | | | | | | | | | | |

| тсѕ | = | 11 I | solate | ed Opei | ration | Degree | e of Sa | turati | on fo | - Busir | ness Pe | eak CHL | JRCHX |
|-----|---|------|--------|---------|--------|--------|---------|--------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.24 | 83 | 0 | 2 | 0 | 6 | 0.26 | 33 | 0 | 3 | 0 | 6 |
| 1 | Т | 0.53 | 83 | 3 | 771 | 15 | 36 | 0.58 | 33 | 2 | 1030 | 9 | 24 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.51 | 17 | 2 | 113 | 3 | 24 | 0.56 | 7 | 1 | 115 | 2 | 12 |
| 2 | Т | 0.55 | 17 | 2 | 137 | 4 | 30 | 0.61 | 7 | 1 | 140 | 2 | 12 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.54 | 83 | 0 | 43 | 1 | 102 | 0.60 | 33 | 0 | 57 | 0 | 24 |
| 3 | Т | 0.55 | 83 | 3 | 799 | 15 | 36 | 0.61 | 33 | 2 | 1067 | 9 | 24 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.06 | 17 | 0 | 12 | 0 | 6 | 0.07 | 7 | 0 | 13 | 0 | 6 |
| 4 | Т | 0.48 | 17 | 2 | 119 | 4 | 24 | 0.53 | 7 | 1 | 121 | 2 | 12 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.55 | 108 | | | | | 0.61 | 48 | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 11 P | edest | rian - | | | - | | Peak F | ile = | CHURCH | łX | |
|-----|---|-----------|-------|--------|------|------------------|------|-------|--------|-------|------------|----------|------|
| | | | | | | solated | | | | | . . | | |
| | | | | | | Length | | | | | | | |
| Α | М | Peds | Delay | Aver | | Delay | | | Delay | Aver | Veh | - | |
| 1 | L | | | | 9 | 0.0 | 3.5 | | | | 9 | 0.0 | 2.8 |
| 1 | Т | 0 | 0.0 | | 2224 | 2.9 | 4.8 | 0 | 0.0 | | 2224 | 2.3 | 3.8 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 137 | 1.6 | 41 8 | | | | 137 | 0.7 | 19.3 |
| 2 | Т | 0 | 0.0 | | 165 | | | | 0.0 | | 165 | | 19.4 |
| 2 | R | Ŭ | 0.0 | | 100 | 1.5 | 72.1 | Ŭ | 0.0 | | 100 | 0.5 | 1014 |
| | | | | | 100 | 0 0 | 1 0 | | | | 100 | 0 1 | 2 0 |
| 3 | L | | | | 120 | | | | | | 120 | | |
| 3 | Т | 0 | 0.0 | | 2244 | 3.1 | 4.9 | 0 | 0.0 | | 2244 | 2.4 | 3.9 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 16 | | | | | | 16 | | 17.9 |
| 4 | Т | 0 | 0.0 | | 145 | 1.7 | 41.6 | 0 | 0.0 | | 145 | 0.8 | 19.2 |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 5060 | 12 | 8.2 | | | | 5060 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| TCS | = | 11 P | | | | | | | | | | | СНХ |
| | | | | | | fter Co | | | | | | | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | | |
| 1 | L | | | | 9 | 0.0 | 1.0 | 1 | 0.1 | А | 0 | 6 | |
| 1 | Т | 0 | 0.0 | | 2224 | | 1.0 | 176 | | A | 5 | 12 | |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 137 | 1.6 | 41 8 | 113 | 0.8 | С | 3 | 24 | |
| 2 | Т | 0 | 0.0 | | 165 | | | | | D | | | |
| 2 | | 0 | 0.0 | | 105 | 1.5 | 42.1 | 107 | 0.0 | D | 4 | 50 | |
| | R | | | | 100 | 0.0 | ~ ~ | • | ~ ~ | | 0 | 0 | |
| 3 | L | | | | 120 | | 0.9 | | | A | | 6 | |
| 3 | Т | 0 | 0.0 | | 2244 | 0.6 | 0.9 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 16 | 0.2 | 38.9 | 12 | 0.8 | С | 0 | 6 | |
| 4 | Т | 0 | 0.0 | | 145 | 1.7 | 41.6 | 119 | 0.8 | С | 4 | 24 | |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 5060 | 7 | 4.7 | 558 | 0.1 | А | | | |
| | | | | | | | | | | | | | |
| TCS | = | 11 I C | | | | Degree Length | | | | | | | |
| Α | М | DS | GT | | | Queue I | | | | | | Queue | |
| 1 | L | 0.24 | 81 | 0 | 2 | 0 | 6 | 0.24 | 81 | 0 | 2 | 0 | 6 |
| 1 | Т | 0.75 | 81 | 6 | 1576 | 21 | 48 | 0.75 | 81 | 6 | 1576 | 21 | 48 |
| 1 | R | 0.75 | 01 | 0 | 10/0 | <u> </u> | | 0.75 | 01 | 0 | 1070 | <u> </u> | -10 |
| | | 0 70 | 10 | ~ | 400 | - | ~~ | 0 70 | 10 | ~ | 100 | - | 00 |
| 2 | L | 0.76 | 16 | 3 | 192 | 5 | 36 | 0.76 | 16 | 3 | 192 | 5 | 36 |
| 2 | Т | 0.65 | 16 | 2 | 164 | 5 | 30 | 0.65 | 16 | 2 | 164 | 5 | 30 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.76 | 81 | 0 | 69 | 1 | 48 | 0.76 | 81 | 0 | 69 | 1 | 48 |
| 3 | Т | 0.76 | 81 | 6 | 1583 | 21 | 48 | 0.76 | 81 | 6 | 1583 | 21 | 48 |
| 3 | D | | | | | | | | | | | | |

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0.07 16 0 15 0.73 16 3 196

0.07 16

0.76 105

3 R

4 L

4 T 4 R INT

0 6 0.07 16 0 15 0 6 6 36 0.73 16 3 196 6 36

105

0.76

Page | 131

.

| TCS | = | 11 | Pedestr | ian - Vehio Is | cle Dela solated | | | File = | CHURCH | Х | | |
|-----|---|------|---------|-------------------|---------------------|------|------|---------|--------|--------|---------|------|
| | | | Co-ordi | nated Cycle | | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | 9 | 0.0 | 3.4 | | | | 9 | 0.0 | 3.4 |
| 1 | Т | 0 | 0.0 | 3203 | 5.9 | 6.6 | 0 | 0.0 | | 3203 | 5.9 | 6.6 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 204 | 2.8 | 49.4 | | | | 204 | 2.8 | 49.4 |
| 2 | Т | 0 | 0.0 | 194 | 2.3 | 41.8 | 0 | 0.0 | | 194 | 2.3 | 41.8 |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 133 | 0.3 | 8.1 | | | | 133 | 0.3 | 8.1 |
| 3 | Т | 0 | 0.0 | 3174 | 5.9 | 6.7 | 0 | 0.0 | | 3174 | 5.9 | 6.7 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 20 | 0.2 | 38.1 | | | | 20 | 0.2 | 38.1 |
| 4 | Т | 0 | 0.0 | 219 | 2.8 | 45.5 | 0 | 0.0 | | 219 | 2.8 | 45.5 |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7156 | 20 | 10.1 | | | | 7156 | 0 | 0.0 |
| | | | | | | | | | | | | |

| TCS | = | 11 F | | ian - Vehio s & Stops a [.] | | - | - | | | | | |
|-----|---|-------|-------|---|-----|------|------|-----|---|----|----|--|
| Δ | М | Peds | 5 | Aver Vehs | | | | | | | | |
| 1 | ï | 1 000 | Deruy | 9 | 0.0 | 4.7 | 4 | 0.4 | A | 0 | 6 | |
| 1 | Т | 0 | 0.0 | 3203 | 4.2 | | 1247 | 0.4 | A | 21 | 48 | |
| 1 | R | Ŭ | 0.0 | 0200 | 716 | 4.7 | 1641 | 0.4 | ~ | 21 | 40 | |
| 2 | 1 | | | 204 | 2.8 | 49.4 | 192 | 0.9 | D | 5 | 36 | |
| 2 | Т | 0 | 0 0 | | | | | 0.9 | - | 5 | | |
| _ | • | 0 | 0.0 | 194 | 2.3 | 41.8 | 164 | 0.8 | С | Э | 30 | |
| 2 | R | | | | | | | | | | _ | |
| 3 | L | | | 133 | 0.0 | 1.3 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | Т | 0 | 0.0 | 3174 | 1.1 | 1.3 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 20 | 0.2 | 38.1 | 15 | 0.8 | С | 0 | 6 | |
| 4 | т | 0 | 0.0 | 219 | 2.8 | 45.5 | 196 | 0.9 | D | 6 | 36 | |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7156 | 13 | 6.8 | 1818 | 0.3 | А | | | |
| | | | | | | | | | | | | |

Church Street Future without Development – CHURCHB.DAT

SCATES Program Version: 2013 Date: 02-NOV-12 Time: Registered User Name. - Road Delay Solutions Pty Ltd Registered User No. - 0 Data File: CHURCHB CHURCH STREET 2031 BITZIOS BASE VOLUMES

| | | | AM PEA | ٩K | | | 1 | PM PEA | ٩K | PM PEAK ers Vol Sat Phse MocV Pers | | | | | |
|------------|-------|-------|--------|----------|------|--------|--------|--------|------|---------------------------------------|------|-------|--------|------|-----|
| AM | Vol | Sat | Phse | | | Vol | Sat | Phse | | | Vol | Sat | Phse | | |
| | | | | | Loss | | | | | Loss | | | | Gain | |
| 1L 1T | 2007 | 5880 | ^ | - | 0.0 | 3825 | E000 | А | - | 0.0 | | 5880 | А | 0 | 0.0 |
| 1R | 3007 | 5660 | A | | | 3020 | 0000 | A | | | 2419 | 5000 | A | | |
| 2L | | | | | | | | | | | | | | | |
| 2T | | | | | | | | | | | | | | | |
| 2R | | | | | | | | | | | | | | | |
| 3L | | | | 0 | 0.0 | | | | 0 | 0.0 | | | | 0 | 0.0 |
| ЗT | 3490 | 5880 | Α | 0 | 261 | 3695 | 5880 | Α | 0 | 165 | 2515 | 5880 | Α | 0 | 149 |
| ЗR | | | | | | | | | | | | | | | |
| 4L | | | | | | | | | | | | | | | |
| 4T | | | | | | | | | | | | | | | |
| 4R Type | – M | | | | | А | | Walk | H%AM | н⊱DМ | H%B | | | | |
| • • | | URCHB | | | | 1 | | Wain | 2 | 2 | | | | | |
| 1 110 | 011 | Onone | | | | 2 | | 28 | - | - | 0 | | | | |
| TCS = | = 19 | 56 | | | | 3 | | | 2 | 2 | 3 | | | | |
| | | | | | | 4 | | | | | | | | | |
| | | PEDES | TRIAN | VOLU | ΛE | WAL | (-CLE/ | ARANCE | | TRAM I | DATA | PE | EDEST | TR/ | ۸M |
| Арр | | AM | P#PM | | #B | Walk | | Clear | | | | | ACT | FAG | |
| 1 | 0 | | 0 | | D | 0 | | 0 | | 0% | | | 100 | 1(| |
| 2 | - | 0 | 30 | | 30 | 6 | - | 22 | |)% >> | | - | 30 | 1(| |
| 3 | 0 | | 0 | |) | 0 6 | | 0 | |)%]% | | | 100 | 10 | |
| 4 | 2 | 0 | 20 | <u>،</u> | 20 | | | 22 | |)% | | : | 30 | 1(| |

| | | | AM PEA | ٩K | | | F | PM PE | ٩K | | | E | BUSINE | SS | |
|------|------|------|--------|------|------|------|------|-------|------|------|------|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 19 | 1750 | Α | 0 | 0.0 | 101 | 1750 | A | 0 | 0.0 | 42 | 1750 | Α | 0 | 0.0 |
| 1T | 3068 | 5670 | Α | 0 | 1 | 3715 | 5670 | Α | 0 | 9 | 2374 | 5670 | Α | 0 | 4 |
| 1R | | | | | | | | | | | | | | | |
| 2L | | | | | | | | | | | | | | | |
| 2T | | | | | | | | | | | | | | | |
| 2R | | | | | | | | | | | | | | | |
| 3L | | | | 0 | 0.0 | | | | 0 | 0.0 | | | | 0 | 0.0 |
| ЗT | 3492 | 5880 | Α | 180 | 0 | 3727 | 5880 | AB | 418 | 0 | 2526 | 5880 | AB | 211 | 0 |
| ЗR | 0 | 1800 | S | | | 0 | 1800 | В | | | 0 | 1800 | В | | |
| 4L | 112 | 1750 | В | | | 39 | 1750 | BC | | | 53 | 1750 | BC | | |
| 4T | | 3600 | | | | | 3600 | | | | | 3600 | | | |
| 4R | 259 | 3600 | В | | | 132 | 3600 | С | | | 137 | 3600 | С | | |
| Туре | = T4 | | | | | А | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |

Page | 134

| File = | CHURCH | В | | 1 2 | 22 | 4.0 | 2 | 2 | 3 | 0 ' | 0 | |
|--------|--------|----------|-------|------------|---------|------------|--------|--------|--------|-----|---|------|
| TCS = | 448 | | | 3 | 5 28 | 4.0 4.0 | 2 0 | 2 0 | 3 0 | 0 ' | 0 | 0 |
| | PEDE | STRIAN V | OLUME | 4 WALK- | | | - | AM DA | - | PED | - | TRAM |
| Арр | P#AM | P#PM | P#B | Walk | С | lear | | | | FAC | Т | FACT |
| 1 | 50 | 50 | 30 | 6 | 1 | 6 | 0% | | | 30 | | 100 |
| 2 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 10 | 0 | 100 |
| 3 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 10 | 0 | 100 |
| 4 | 50 | 50 | 30 | 6 | 2 | 2 | 0% | | | 30 | | 100 |
| | | | | | | | | | | | | |

| | | AK | | | | | | | | | BUSIN | | |
|--|---|--|---------------------|--------------------------------|-----------------------|--------|---|------------------------------------|--|---|---------------------------------|---|-------------------------------|
| AM Vol Sa | at Phse | Gain L | | VOI | Sat | Phse | | Pers Loss | | Sat | Phse | MocV Gain | |
| 1L 4 175 | | 0 | 0.0 | | 1750 | Α | 0 | 0.0 | 6 | | | 0 | 0.0 |
| 1T 3115 556 1R 0 | | | 60 3 | | 5560 0 | A S | | 735 | | 5560 0 | | | 281 |
| 2L 197 175 | | | | - | 1750 | B | | | - | 1750 | - | | |
| 2T 225 196 | 60 B | | | | 1960 | В | | | 176 | 1960 | В | | |
| 2R 0 3L 134 175 | | | 0.0 | | 0 1750 | B | | 0.0 | 0 | | - | 0 | 0.0 |
| 3T 3121 567 | | - | | | 5670 | A | | 0.0 | | 5670 | | - | 0.0 |
| 3R 0 | 0 S | | | | 0 | S | | | 0 | - | - | | |
| 4L 18 175 4T 207 196 | | | | | 1750 1960 | B B | | | 14 | 1750 1960 | | | |
| 41 207 190 4R 0 | | | | 0 | | B | | | | 1900 | | | |
| Type = COCO | | | | А | | | | H%PM | | | L-PD | R - PD | |
| File = CHURCH | ΙB | | | 1 | 5 5 | 4.0 | | 2 1 | | 0' 0' | 0 0 | 0 0 | |
| TCS = 11 | | | | | | 4.0 | | | 2 | | | - | |
| | | | | 4 | 5 | 4.0 | 1 | 1 | 2 | - | 0 | - | |
| | ESTRIAN P#PM | | | | <-CLEA | | | TRAM D | DATA | | | TRA FAC | |
| App P#AM 1 O | Р#РМ 0 | 0 | 5 | wair 0 | 0 | | | 0% | | | ACT 100 | гац 1(| |
| 2 0 | 0 | 0 | | 0 | 0 |) | | 0% | | | 100 | 10 | |
| 3 0 4 0 | 0 0 | 0 0 | | 0 0 | 0 | | | 0% 0% | | | 100 100 | 10 | |
| | | - | | - | - | | | | | | | 1(| |
| N Lane Type 1 T 2 T 3 T | Length 9999 | 0 Sat 1960 | | | | | Гуре | 3 |) Sat |) t Ty | | | |
| AM Apprch O Depart O File = CHURCH Type = M | Parki PM 0 0 | 1960 ng BUS 0 0 | AM -CS = | P١ | л в | US | T No AM O O | | 1960 ing BUS (|)) S Al)) | | arkinç PM | |
| 5 6 7 8 MM Apprch 0 Depart 0 File = CHURCH Type = M | o Parki PM O IB | 1960 ng BUS 0 0 | AM CS = | PN 1956 | л В 5 | | T AM O O | 9999 Park: PM 0 0 | 1960 ing BUS (|)) ()) | M | PM | BUS |
| 5 6 7 8 MM Apprch 0 Depart 0 File = CHURCH Type = M | o Parki PM 0 1B | 1960 ng BUS 0 0 1 | AM -CS = | ۹۹ 1956 | и В 5 | | T AM O O | 9999 Park: PM 0 0 | 1960 ing BUS (((|)) ()) | M APP | PM ROACH | BUS |
| 5 6 7 8 M Apprch 0 Depart 0 File = CHURCH Type = M Tidal Down | o Parki PM O IB | 1960 ng BUS 0 0 1 | AM -CS = | ۹۹ 1956 | и В 5 | | T AM O O | 99999 Park: PM 0 0 | 1960 ing BUS (((|)) S Al)) de Dov | M APP | PM ROACH | BUS |
| 5 6 7 8 M Apprch 0 Depart 0 File = CHURCH Type = M Tidal Down N 0 Lane Type | o Parki PM 0 1B APPROAC Lanes 3 Length | 1960 ng BUS 0 0 1 | AM TCS = Down | ۹۸ 1956 APPRC Lar | и В 5 | ade [| T AM O O O Sown O Type I | 99999 Park: PM 0 0 | 1960 ing BUS ((CH 3 s Grac (n Sat |)) S Al)) de Dov) t Ty | APPI wn Li pe Lei | PM ROACH anes (2 ngth | BUS 4 Grade 0 Sat |
| 5 6 7 8 M Apprch 0 Depart 0 File = CHURCH Type = M Tidal Down N 0 Lane Type | Parki PM 0 HB APPROAC Lanes 3 Length 9999 | 1960 ng BUS 0 0 1 H 1 Grade 0 Sat 1750 | AM TCS = Down | ۹۸ 1956 APPRC Lar |) DACH 2 Des Gr | ade [| T AM O O O O Vype I T | 99999 Park: PM 0 0 | 1960 ing BUS ((CH 3 s Grac (1 Sa ⁺ 1960 |)) S Al)) de Dov) t Ty)) | APPI wn La pe Le LR 99 | PM ROACH anes (2 ngth 999 | BUS 4 Grade 0 Sat |

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November 2012

| 3 4 5 | Т | 9999 | 1960 | | | | т | 9999 | 1960 | | | |
|-------------|--------|-------|------|-------|-------|-----|----|-------|------|----|--------|-----|
| 6 | | | | | | | | | | | | |
| 7 | | | | | | | | | | | | |
| 8 | | | | | | | | | | | | |
| | No | Parki | ng | No | Parki | ng | No | Parki | ng | No | Parkir | ng |
| | AM | PM | BUS | AM | PM | BUS | AM | PM | BUS | AM | PM | BUS |
| Apprch | 0 | 0 | 0 | | | | 0 | 0 | 0 | 0 | 0 | 0 |
| Depart | 0 | 0 | 0 | | | | 0 | 0 | 0 | 0 | 0 | 0 |
| File = C | HURCHI | В | | | | | | | | | | |
| Type = T | 4 | | - | TCS = | 448 | | | | | | | |
| | | | | | | | | | | | | |

APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 Tidal Down Lanes Grade Down Lanes Grade Down Lanes Grade Down Lanes Grade 0 3 0 0 2 0 0 3 0 0 2 0 Ν Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane LT 9999 1750 L 90 1750 LT 9999 1750 L 9999 1750 T 9999 1960 T 9999 1960 T 9999 1960 T 9999 1960 T 9999 1850 T 9999 1960 1 2 3 4 5 6 7 8 No Parking No Parking No Parking No Parking
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 File = CHURCHB Type = COCO TCS = 11 AM PEAK PM PEAK BUSINESS GT% GT% CL CL GT% GT% CL CL GT% GT% CL CL CL GT% GT% CL CL CL CCRD ISOL CORD ISOL CORD ISOL CORD ISOL CORD ISOL CORD ISOL Ph CORD ISOL
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 12

 Stps
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 Mode
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Bay Bay Slip Slip Req Act Req Act File = CHURCHB Type TCS = 1956 Μ -----. PM PEAK BUSINESS AM PEAK
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 ABC
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 Stps
 3.9
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 3.6
 3.4
 Stps
 1.9
 1.8

 Mode
 1
 DS
 0.81
 0.81
 1
 DS
 0.59
 0.58

 File = CHURCHB
 A
 Bay
 Bay
 Slip
 Slip
 Type

Req Act Req Act 10 0 TCS = 448Τ4 1

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| AM PE Ph GT% GT% CORD ISOL A 81.0 81.0 B 19.0 19.0 C D | CL CL GT CORD ISOL COR 105 105 78. | | CL GT% GT% ISOL CORD ISOL | |
|--|--|---|--|--|
| | 3.8 3.8 | AB dlay 26 Stps 4.0 O DS 0.80 Bay Bay Sli Req Act Rec 10 58 18 | 0.0 23 AB 4.2 0.81 0 p Slip Act 0 90 5 0 | Stps 2.1 2.7 DS 0.56 0.62 Type COCO |
| | | Bays if all in | tersections are | |
| | nated Cycle Le | gree of Saturati ngth eue Metre DS | Isolated Cycle | Length |
| 1 T 0.88 96 1 R 2 L 2 T 2 R | 13 2608 | 35 72 0.86 | 108 12 23 | 84 35 72 |
| 3 L 3 T 0.85 96 3 R 4 L 4 T 4 R | 12 2362 | 34 72 0.83 | 108 11 210 | 60 34 72 |
| INT 0.88 128 | | 0.86 | 140 | |
| TCS = 1956 Pedestr | | e Delay PM Peak F ated Operation | ile = CHURCHB | |
| A M Peds Delay | | ength lay Aver Peds | | |
| 1 L 1 T 0 0.0 1 R 2 L | 3901 1 | 2.9 11.9 0 | 0.0 39 | 01 11.8 10.9 |
| 2 T 30 0.5 2 R | 58.1 | 30 | 0.5 64.1 | |
| 3 L 3 T 0 0.0 3 R 4 L | 3769 1 | 1.7 11.1 0 | 0.0 37 | 69 10.7 10.2 |

| 4 T 20 4 B | 0.3 | 58.1 | | | | 20 | 0.4 | 64.1 | | | |
|---------------|-----|------|------|----|------|----|-----|------|------|---|-----|
| | 1 | 58.1 | 7670 | 25 | 11.5 | 50 | 1 | 64.1 | 7670 | 0 | 0.0 |

Addendum - Arterial Road Network

| | | 1956 I | | | | | | | | | | | |
|------------------|-----------------------|--------|---------|---------|--------|-------------------|-------|---------|---------|---------|---------|--------|------|
| A 1 | | Peds | | | | Delay | | | | | | | |
| 1 1 | T R | 0 | 0.0 | | 3901 | 0.0 | 0.0 | 0 | 0.0 | A | 0 | 6 | |
| 2 | L T R L | 30 | 0.5 | 58.1 | | | | | | | | | |
| | T R L | 0 | 0.0 | | 3769 | 11.9 | 11.3 | 1325 | 0.4 | A | 34 | 72 | |
| | Т | 20 | 0.3 | 58.1 | | | | | | | | | |
| INT | | 50 | 1 | 58.1 | 7670 | 12 | 5.6 | 1325 | 0.2 | A | | | |
| тсѕ | = | 1956 | Isolate | ed Oper | ration | Dearee | of Sa | aturat: | ion for | - Busir | iess Pe | ak CHU | RCHB |
| A | | | Co-ord: | inated | Cycle | Length Queue | | | - Isola | ated Cy | cle Le | ngth - | |
| 1 | L T | 0.62 | 69 | 6 | 1233 | 22 | 48 | 0.60 | 77 | 6 | 1143 | 22 | 48 |
| | R L T R L | | | | | | | | | | | | |
| 3 3 4 4 | T R L T | 0.64 | 69 | 7 | 1320 | 23 | 48 | 0.62 | 77 | 6 | 1223 | 23 | 48 |
| 4 INT | | 0.64 | 101 | | | | | 0.62 | 109 | | | | |
| TOO | _ | 1056 | Dadaati | aian | Vobi | | | incoo | Deale | -ilo - | | D | |
| 105 | - | 1956 I | | | I | solated Length | Opera | ation | | | | | |
| A 1 | М | | | | | Delay | | | | | | | |
| 1 | L T R | 0 | 0.0 | | 2492 | 6.1 | 8.8 | 0 | 0.0 | | 2492 | 5.6 | 8.2 |
| 2 2 2 | L T R | 30 | 0.4 | 44.7 | | | | 30 | 0.4 | 48.7 | | | |
| 3 | L T | 0 | 0.0 | | 2590 | 6.5 | 9.1 | 0 | 0.0 | | 2590 | 6.0 | 8.4 |
| 4 4 | R L T | 20 | 0.2 | 44.7 | | | | 20 | 0.3 | 48.7 | | | |
| 4 INT | R | 50 | 1 | 44.7 | | 13 | | | | | 5082 | 0 | 0.0 |
| | | | | | | | | | | | | | |

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| | | 1956 P | | | | | 2 | • | | | File = | CHURCHB |
|-----|---|--------|-----|------|------|-----|-----|----|-----|---|--------|---------|
| | | Peds | - | | • | | | | | | | |
| 1 | L | | - | | | - | | | | | | |
| 1 | Т | 0 | 0.0 | | 2492 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | |
| 2 | Т | 30 | 0.4 | 44.7 | | | | | | | | |
| _ | R | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 2590 | 0.1 | 0.1 | 12 | 0.0 | А | 0 | 6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | | | | | | | | |
| 4 | Т | 20 | 0.2 | 44.7 | | | | | | | | |
| 4 | R | | | | | | | | | | | |
| INT | | 50 | 1 | 44.7 | 5082 | 0 | 0.1 | 12 | 0.0 | A | | |
| | | | | | | | | | | | | |

| | = | | | | | Degree | | | | | | | |
|-------------------------------|----------------------------|------|---------|---------|---------|------------------------------|--------|---------|--------|--------|-------|-------|-------|
| A M | | DS | GT | Delay | Stops | Length Queue I | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 1 2 2 2 | L T R L T R | 0.77 | 73 | 9 | 1860 | 28 | 60 | 0.77 | 73 | 9 | 1860 | 28 | 60 |
| 3 3 4 4 | L T R L T R | 0.87 | 73 | 12 | 2476 | 32 | 66 | 0.87 | 73 | 12 | 2476 | 32 | 66 |
| INT | | | 105 | | | | | 0.87 | | | | | |
| | | | | | | | | | | | | | |
| TCS = | = | 1956 | Pedesti | rian · | | cle Dela solated | | | ile = | CHURCH | ΙB | | |
| | M | | | | | Length Delay | | | | | | | |
| 1 T 1 F | T R | 0 | 0.0 | | 3149 | 9.2 | 10.5 | 0 | 0.0 | | 3149 | 9.2 | 10.5 |
| 2 2 F | L T R | 30 | 0.4 | 46.7 | | | | 30 | 0.4 | 46.7 | | | |
| 3 T 3 F | L T R | 0 | 0.0 | | 3560 | 12.2 | 12.4 | 0 | 0.0 | | 3560 | 12.2 | 12.4 |
| 4 | L T R | 20 | 0.3 | 46.7 | | | | 20 | 0.3 | 46.7 | | | |
| INT | | 50 | | | | 21 | | | | | | | |
| A N | | | - Delay | ys & St | tops at | cle Dela fter Co Delay | -ordir | nated E | Valuat | ion | | | |
| 1 T 1 F | T R L | 0 | 0.0 | | 3149 | 0.0 | 0.0 | 0 | 0.0 | A | 0 | 6 | |
| 2 2 F | – T R L | 30 | 0.4 | 46.7 | | | | | | | | | |
| 3 T 3 F | T R | 0 | 0.0 | | 3560 | 2.2 | 2.2 | 364 | 0.1 | A | 11 | 24 | |
| 4 | L T R | 20 | 0.3 | 46.7 | | | | | | | | | |
| INT | | 50 | 1 | 46.7 | 6709 | 2 | 1.2 | 364 | 0.1 | А | | | |
| TCS | = | 448 I: | | | | 0 | | | | | | | |
|-----|---|--------|--------|--------|-------|--------|-------|------|-------|---------|---------|-------|-------|
| | | Co | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.86 | 103 | 0 | 62 | 1 | 36 | 0.84 | 115 | 0 | 56 | 1 | 60 |
| 1 | Т | 0.86 | 103 | 9 | 2182 | 27 | 60 | 0.84 | 115 | 8 | 1995 | 27 | 60 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | | | | | | | | | | | | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | |
| 3 | Т | 0.75 | 112 | 3 | 1252 | 17 | 36 | 0.74 | 124 | 3 | 1145 | 17 | 36 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.44 | 17 | 1 | 32 | 1 | 12 | 0.48 | 17 | 1 | 33 | 1 | 12 |
| 4 | Т | | | | | | | | | | | | |
| 4 | R | 0.68 | 8 | 2 | 116 | 4 | 18 | 0.75 | 8 | 3 | 131 | 5 | 24 |
| INT | | 0.86 | 128 | | | | | 0.84 | 140 | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 448 | Pedesti | rian - | | cle Del solated | | | ile = | CHURCH | IB | | | |
|-----|---|-------|---------|--------|-------|--------------------|------|------|---------|-------------|--------|--------|------|--|
| | | | Co-ord: | inated | | | | | Isola | ted Cv | cle Le | nath - | | |
| А | М | | Delay | | | | | | | | | | | |
| 1 | L | 1 Cub | Deruy | //// | | 0.3 | | | Deruy | //// | 103 | | 10.7 | |
| | | | | F0 4 | 0700 | 8.6 | 12.1 | 50 | 0 0 | 64 4 | 0700 | 7.0 | 10.7 | |
| 1 | Т | 50 | 0.8 | 58.1 | 3789 | 8.6 | 8.1 | 50 | 0.9 | 64.1 | 3789 | 7.8 | 1.4 | |
| 1 | R | | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | | |
| 2 | Т | 0 | 0.0 | | | | | 0 | 0.0 | | | | | |
| 2 | R | - | | | | | | - | | | | | | |
| | | | | | | | | | | | | | | |
| | L | | | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 3802 | 3.2 | 3.0 | 0 | 0.0 | | 3802 | 2.9 | 2.7 | |
| 3 | R | | | | | | | | | | | | | |
| 4 | L | | | | 39 | 0.6 | 50.8 | | | | 39 | 0.6 | 57.1 | |
| 4 | Т | 50 | 0.8 | 58.1 | | | | 50 | 0 9 | 64.1 | | | | |
| | Ŕ | 00 | 010 | 0011 | 132 | 2.1 | 50 E | | 010 | 0111 | 132 | 2.8 | 76.9 | |
| | | 100 | | | | | | | • | | | | | |
| INT | | 100 | 2 | 58.1 | | 15 | | 100 | 2 | 64.1 | 7865 | 0 | 0.0 | |
| | | | Pedesti | | | | | | | | | | | |
| | | | - Delay | | | | | | | 10n | | | | |
| Α | М | Peds | Delay | Aver | Vehs | | | | | LOS | | | | |
| 1 | L | | | | 103 | 0.0 | 1.6 | 12 | 0.1 | Α | 0 | 6 | | |
| 1 | Т | 50 | 0.8 | 58.1 | 3789 | 1.7 | | | | А | 16 | 36 | | |
| 1 | R | | | | | | | | | | | | | |
| | L | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |
| | Т | 0 | 0.0 | | | | | | | | | | | |
| 2 | R | | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 3802 | 0.3 | 0.3 | 138 | 0.0 | А | 5 | 12 | | |
| 3 | R | | | | | | | | | | | | | |
| 4 | L | | | | 39 | 0.6 | 50.8 | 32 | 0.8 | D | 1 | 12 | | |
| 4 | Т | 50 | 0.8 | 58.1 | 03 | 0.0 | 50.0 | 02 | 0.0 | D | | 12 | | |
| | | 50 | 0.0 | 50.1 | 400 | • • | | | | - | | 10 | | |
| | R | | | | 132 | | | | | E | 4 | 18 | | |
| INT | | 100 | 2 | 58.1 | 7865 | 5 | 2.2 | 740 | 0.1 | Α | | | | |
| | | | | | | | | | | | | | | |
| | | | Isolate | | | | | | | | | | | |
| | | | Co-ord: | inated | Cycle | Length | | | - Isola | ted Cy | cle Le | ngth - | | |
| А | М | DS | | | | Queue | | | | | Stops | | | |
| 1 | L | 0.59 | | | 17 | 0 | 30 | | 83 | - | 16 | 0 | 42 | |
| 1 | Т | 0.59 | | | 992 | 17 | 42 | | 83 | 4 | 943 | 18 | | |
| | | 0.59 | /0 | 4 | 992 | 17 | 42 | 0.58 | 00 | 4 | 940 | 10 | 42 | |
| 1 | R | | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | | |
| 2 | Т | | | | | | | | | | | | | |
| 2 | R | | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | | |
| | | 0 | | ~ | 600 | 4.0 | ~ ~ | 0 50 | ~~ | ~ | 660 | 4.0 | 0.0 | |
| 3 | Т | 0.53 | 85 | 2 | 686 | 12 | 24 | 0.53 | 92 | 2 | 662 | 12 | 30 | |
| 3 | R | | | | | | | | | | | | | |
| 4 | L | 0.40 | 17 | 1 | 42 | 1 | 12 | 0.42 | 18 | 1 | 43 | 1 | 12 | |
| 4 | Т | | | | | | | | | | | | | |
| 4 | R | 0.58 | 8 | 2 | 119 | 4 | 18 | 0.58 | 9 | 2 | 119 | 4 | 18 | |
| INT | | 0.59 | | _ | - | | _ | 0.58 | 109 | _ | | | | |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |

| TCS | = | 448 | Pedestr | ian | - Vehio | cle Dela | ay Bus | siness | Peak F | ile = | CHURCH | ΗB | |
|-----|---|------|---------|-------|---------|----------|--------|--------|---------|---------|--------|---------|------|
| | | | | | Is | solated | Opera | ation | | | | | |
| | | | Co-ordi | nated | Cycle | Length | | | - Isola | ited Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 43 | 0.1 | 5.7 | | | | 43 | 0.1 | 5.6 |
| 1 | Т | 30 | 0.4 | 44.7 | 2445 | 3.9 | 5.7 | 30 | 0.4 | 48.7 | 2445 | 3.8 | 5.6 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | C | 0.0 | | | | | 0 | 0.0 | | | | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | |
| 3 | Т | C | 0.0 | | 2602 | 1.7 | 2.4 | 0 | 0.0 | | 2602 | 1.7 | 2.4 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 53 | 0.5 | 37.2 | | | | 53 | 0.6 | 40.7 |
| 4 | Т | 30 | 0.4 | 44.7 | | | | 30 | 0.4 | 48.7 | | | |
| 4 | R | | | | 137 | 1.7 | 44.6 | | | | 137 | 1.8 | 48.1 |
| INT | | 60 |) 1 | 44.7 | 5280 | 8 | 5.4 | 60 | 1 | 48.7 | 5280 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |

| | | | | | | cle Del fter Co | | | | | | | RCHB |
|----------|--------|------------|--------|---------|--------|--------------------|---------|--------------|---------|---------|------------|---------|------------|
| Α | | | | | Vehs | Delay 0.0 | Aver | Stops | | LOS | 0 | 6 | |
| | Т | 30 | 0.4 | 44.7 | 2445 | | 1.1 | | | A | 5 | 12 | |
| | R L | | | | | | | | | | | | |
| | T | 0 | 0.0 | | | | | | | | | | |
| | R | | | | | | | | | | | | |
| | L T | 0 | 0.0 | | 2602 | 0.2 | 0.2 | 62 | 0.0 | А | 2 | 6 | |
| | R | | | | 50 | 0 5 | 07 0 | 40 | 0 0 | 0 | - | 10 | |
| | L T | 30 | 0.4 | 44.7 | 53 | 0.5 | 37.2 | 42 | 0.8 | С | 1 | 12 | |
| 4 | R | | | | | 1.7 | | | | | 3 | 18 | |
| INT | | 60 | 1 | 44.7 | 5280 | 3 | 2.2 | 422 | 0.1 | A | | | |
| | | | | | | | | | | | | | |
| тсѕ | = | 448 | Isolat | ed Oper | ration | Degree | e of Sa | aturat | ion fo | ∽ AM P€ | eak CHL | JRCHB | |
| | | | Co-ord | inated | Cycle | Length | ı | | - Isola | ated Cy | /cle Le | ength · | |
| | M L | DS 0.43 | | | | Queue | | | | | Stops 6 | | Metre 6 |
| | Т | 0.43 | | 6 | 1575 | 0 23 | 48 | 0.43 | 79 | 6 | 1575 | - | |
| 1 | R | | | | | | | | | | | | |
| | L | | | | | | | | | | | | |
| | T R | | | | | | | | | | | | |
| | L | | | | | | | | | | | | |
| | Т | 0.81 | 79 | 8 | 2026 | 26 | 54 | 0.81 | 79 | 8 | 2026 | 26 | 54 |
| | R L | 0.81 | 18 | 2 | 111 | 3 | 24 | 0.81 | 18 | 2 | 111 | 3 | 24 |
| | Т | | | - | | | | | | | | | |
| 4 INT | R | | | | 213 | 6 | 30 | 0.54 0.81 | | 3 | 213 | 6 | 30 |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| TCS | = | 448 | Pedest | rian | | cle Del | | | File = | CHURCH | ΙB | | |
| | | | Co-ord | inated | | solatec Length | | | - Isola | ated Cy | | anath . | |
| А | М | | | | | Delay | | | | | | | |
| | L | | | | | 0.0 | | | | | 19 | | |
| | T R | 50 | 0.6 | 46.7 | 3129 | 6.3 | 7.3 | 50 | 0.6 | 46.7 | 3129 | 6.3 | 7.3 |
| 2 | L | | | | | | | | | | | | |
| | Т | 0 | 0.0 | | | | | 0 | 0.0 | | | | |
| | R L | | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 3562 | 8.1 | 8.2 | 0 | 0.0 | | 3562 | 8.1 | 8.2 |
| | R | | | | 110 | | F0 F | | | | 110 | 4 - | F0 F |
| | L T | 50 | 0.6 | 46.7 | 112 | 1.7 | 53.5 | 50 | 0.6 | 46.7 | 112 | 1.7 | 53.5 |
| 4 | R | | | | 259 | | | | | | 259 | | |
| INT | | 100 | | | 7081 | 19 | | | 1 | | 7081 | 0 | |
| | | | | | | | | | | | | | |

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| TCS | = | 448 P | | | | cle Del fter Co | - | • | | | | НВ |
|-----|---|-------|-----|------|------|--------------------|------|------|-----|---|----|--------|
| А | М | Peds | 2 | | | | | | | | | |
| 1 | L | | - | | 19 | 0.0 | 6.7 | 5 | 0.3 | Α | 0 | 6 |
| 1 | Т | 50 | 0.6 | 46.7 | 3129 | 5.9 | 6.7 | 785 | 0.3 | Α | 23 | 48 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | |
| 2 | Т | 0 | 0.0 | | | | | | | | | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 3562 | 1.8 | 1.8 | 576 | 0.2 | Α | 17 | 36 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 112 | 1.7 | 53.5 | 111 | 1.0 | D | 3 | 24 |
| 4 | Т | 50 | 0.6 | 46.7 | | | | | | | | |
| 4 | R | | | | 259 | 2.9 | 39.8 | 213 | 0.8 | С | 6 | 30 |
| INT | | 100 | 1 | 46.7 | 7081 | 12 | 6.2 | 1690 | 0.2 | Α | | |
| | | | | | | | | | | | | |

| TCS | = | 11 I | solat | ed Opei | ration | Degree | e of Sa | turati | on fo | ° PM P€ | ak CHL | JRCHB | |
|-----|---|------|-------|---------|--------|--------|---------|--------|-------|---------|---------|---------|-------|
| | | C | o-ord | inated | Cycle | Length | ו ו | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.34 | 97 | 0 | 4 | 0 | 6 | 0.35 | 78 | 0 | 4 | 0 | 6 |
| 1 | Т | 0.74 | 97 | 7 | 1527 | 27 | 60 | 0.75 | 78 | 7 | 1596 | 23 | 54 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.59 | 23 | 2 | 154 | 5 | 36 | 0.60 | 19 | 2 | 154 | 4 | 30 |
| 2 | Т | 0.80 | 23 | 5 | 263 | 9 | 54 | 0.81 | 19 | 4 | 273 | 8 | 48 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.80 | 97 | 1 | 124 | 2 | 102 | 0.81 | 78 | 1 | 131 | 2 | 54 |
| 3 | Т | 0.80 | 97 | 8 | 1770 | 28 | 66 | 0.81 | 78 | 8 | 1851 | 24 | 54 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.07 | 23 | 0 | 16 | 1 | 6 | 0.07 | 19 | 0 | 16 | 1 | 6 |
| 4 | Т | 0.51 | 23 | 2 | 146 | 5 | 36 | 0.52 | 19 | 2 | 147 | 4 | 30 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.80 | 128 | | | | | 0.81 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 11 Pedestrian - Vehicle Delay PM Peak File = CHURCHB Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 14 | 0.0 | 5.1 | | | | 14 | 0.0 | 4.6 |
| 1 | Т | 0 | 0.0 | | 3079 | 7.3 | 8.6 | 0 | 0.0 | | 3079 | 6.6 | 7.7 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 186 | 2.5 | 48.1 | | | | 186 | 2.1 | 39.7 |
| 2 | Т | 0 | 0.0 | | 282 | 4.6 | 58.3 | 0 | 0.0 | | 282 | 4.0 | 51.4 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | 216 | 0.7 | 11.8 | | | | 216 | 0.7 | 11.3 |
| 3 | Т | 0 | 0.0 | | 3198 | 8.5 | 9.6 | 0 | 0.0 | | 3198 | 7.6 | 8.6 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 22 | 0.3 | 43.5 | | | | 22 | 0.2 | 35.9 |
| 4 | Т | 0 | 0.0 | | 180 | 2.4 | 47.4 | 0 | 0.0 | | 180 | 2.0 | 39.1 |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 7177 | 26 | 13.2 | | | | 7177 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 11 Pedestrian - Vehicle Delay - Stops PM Peak File = CHURCHB ----- Delays & Stops after Co-ordinated Evaluation-----

| Α | М | Peds | Delay | Aver Vehs | Delay | Aver | Stops | Aver | LOS | | | |
|-----|---|------|-------|-----------|-------|------|-------|------|-----|---|----|--|
| 1 | L | | | 14 | 0.0 | 0.3 | 0 | 0.0 | Α | 0 | 6 | |
| 1 | Т | 0 | 0.0 | 3079 | 0.2 | 0.3 | 67 | 0.0 | Α | 2 | 6 | |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 186 | 2.5 | 48.1 | 154 | 0.8 | D | 5 | 36 | |
| 2 | Т | 0 | 0.0 | 282 | 4.6 | 58.3 | 263 | 0.9 | Е | 9 | 54 | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 216 | 0.1 | 1.8 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | Т | 0 | 0.0 | 3198 | 1.6 | 1.8 | 0 | 0.0 | А | 0 | 6 | |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 22 | 0.3 | 43.5 | 16 | 0.7 | D | 1 | 6 | |
| 4 | Т | 0 | 0.0 | 180 | 2.4 | 47.4 | 146 | 0.8 | D | 5 | 36 | |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7177 | 12 | 5.8 | 646 | 0.1 | А | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |

| тсѕ | = | 11 I | solate | ed Opei | ration | Degree | e of Sa | turati | on fo | r Busir | ness Pe | eak CHL | JRCHB |
|-----|---|------|--------|---------|--------|--------|---------|--------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | ו ו | | Isola | ated Cy | /cle Le | ength · | |
| Α | Μ | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.17 | 76 | 0 | 2 | 0 | 6 | 0.19 | 31 | 0 | 2 | 0 | 6 |
| 1 | Т | 0.53 | 76 | 3 | 812 | 15 | 36 | 0.59 | 31 | 2 | 1071 | 9 | 24 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.47 | 17 | 1 | 111 | 3 | 24 | 0.53 | 7 | 1 | 113 | 1 | 12 |
| 2 | Т | 0.56 | 17 | 2 | 149 | 4 | 30 | 0.62 | 7 | 1 | 152 | 2 | 12 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.56 | 76 | 0 | 48 | 1 | 96 | 0.62 | 31 | 0 | 63 | 1 | 24 |
| 3 | Т | 0.56 | 76 | 3 | 859 | 15 | 36 | 0.62 | 31 | 3 | 1132 | 9 | 24 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.05 | 17 | 0 | 11 | 0 | 6 | 0.05 | 7 | 0 | 11 | 0 | 6 |
| 4 | Т | 0.43 | 17 | 1 | 111 | 3 | 24 | 0.47 | 7 | 1 | 113 | 1 | 12 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.56 | 101 | | | | | 0.62 | 46 | | | | |
| | | | | | | | | | | | | | |

| тсѕ | = | 11 P | edestr | ian · | | cle Del solated | | | Peak F | ile = | CHURCH | ΙB | |
|------|---|-------|----------|---------|---------|--------------------|----------|---------|----------|--------|--------|------------|-------|
| | | C | o-ordi | inated | | Length | | | - Isola | ted Cv | cle Le | enath - | |
| А | М | | | | | Delay | | | | | | | |
| 1 | L | | , | | | 0.0 | | | , | | 6 | | |
| 1 | Т | 0 | 0.0 | | 2211 | | 5.0 | 0 | 0.0 | | 2211 | | |
| | | 0 | 0.0 | | 2211 | 5.1 | 5.0 | 0 | 0.0 | | 2211 | 2.4 | 4.0 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 136 | | | | | | 136 | | |
| 2 | Т | 0 | 0.0 | | 180 | 1.9 | 38.8 | 0 | 0.0 | | 180 | 0.9 | 18.4 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | 125 | 0.2 | 5.2 | | | | 125 | 0.1 | 4.1 |
| 3 | Т | 0 | 0.0 | | 2255 | | 5.2 | | 0.0 | | 2255 | | |
| | | 0 | 0.0 | | 2200 | 0.0 | 5.2 | 0 | 0.0 | | 2200 | 2.0 | 4.1 |
| 3 | R | | | | | • • | <u> </u> | | | | | • • | 10.0 |
| 4 | L | | | | 14 | | 35.5 | | | | 14 | | |
| 4 | Т | 0 | 0.0 | | 137 | 1.4 | 37.9 | 0 | 0.0 | | 137 | 0.7 | 18.0 |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 5064 | 12 | 8.2 | | | | 5064 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| TCS | = | 11 P | edestr | rian 🛛 | - Vehi | cle Del | ay - 8 | Stops E | Busines | s Peak | File | = CHUR | CHB |
| | | | Delav | /s & S1 | tops at | fter Co | -ordir | nated E | Evaluat | ion | | | |
| Α | М | Peds | | | | | | | | | | | |
| 1 | L | . eue | Doray | / | | 0.0 | | | | A | 0 | 6 | |
| | | 0 | 0 0 | | | | | | | | | | |
| 1 | Т | 0 | 0.0 | | 2211 | 0.1 | 0.1 | 29 | 0.0 | Α | 1 | 6 | |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 136 | 1.4 | 38.2 | 111 | 0.8 | С | 3 | 24 | |
| 2 | Т | 0 | 0.0 | | 180 | 1.9 | 38.8 | 149 | 0.8 | С | 4 | 30 | |
| 2 | R | - | | | | | | | | - | - | | |
| 3 | L | | | | 105 | 0 0 | 1.0 | 0 | 0.0 | А | 0 | 6 | |
| | | • | ~ ~ | | 125 | | | | | | | 6 | |
| 3 | Т | 0 | 0.0 | | 2255 | 0.6 | 1.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 14 | 0.1 | 35.5 | 11 | 0.8 | С | 0 | 6 | |
| 4 | Т | 0 | 0.0 | | 137 | 1.4 | 37.9 | 111 | 0.8 | С | 3 | 24 | |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 5064 | 6 | 1 0 | 410 | 0 1 | А | | | |
| TINI | | | | | 5004 | 0 | 4.0 | 410 | 0.1 | A | | | |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| TCS | = | 11 I | solate | ed Oper | ration | Dearee | of Sa | aturati | ion for | AM Pe | ak CHL | JRCHB | |
| | | | | | | Length | | | | | | | |
| ^ | | | | | | | | | | | | | |
| A | M | DS | GT | ретау | Stops | Queue | wetre | DS | GT | ретау | Stops | Queue | wetre |
| 1 | L | | | | | | | | | | | | |
| 1 | Т | 0.74 | 81 | 6 | 1534 | 21 | 48 | 0.74 | 81 | 6 | 1534 | 21 | 48 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.75 | 16 | 3 | 184 | 5 | 36 | 0.75 | 16 | 3 | 184 | 5 | 36 |
| | | | | | | | | | | | | | |
| 2 | Т | 0.76 | 16 | 3 | 212 | 6 | 42 | 0.76 | 16 | 3 | 212 | 6 | 42 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.76 | 81 | 0 | 71 | 1 | 48 | 0.76 | 81 | 0 | 71 | 1 | 48 |
| 3 | Т | 0.76 | 81 | 6 | 1587 | 21 | 48 | 0.76 | 81 | 6 | 1587 | 21 | 48 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.07 | 16 | 0 | 14 | 0 | 6 | 0.07 | 16 | 0 | 14 | 0 | 6 |
| | | | | | | | | | | | | | |
| 4 | Т | 0.70 | 16 | 3 | 182 | 5 | 36 | 0.70 | 16 | 3 | 182 | 5 | 36 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.76 | 105 | | | | | 0.76 | 105 | | | | |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |

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| TCS | = | 11 | Pedestr | ian - Vehio Is | cle Dela solated | | | File = | CHURCH | В | | |
|-----|---|------|---------|-------------------|---------------------|------|------|---------|--------|--------|---------|------|
| | | | Co-ordi | nated Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | 4 | 0.0 | 0.0 | | | | 4 | 0.0 | 0.0 |
| 1 | Т | 0 | 0.0 | 3177 | 5.7 | 6.4 | 0 | 0.0 | | 3177 | 5.7 | 6.4 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 199 | 2.7 | 48.1 | | | | 199 | 2.7 | 48.1 |
| 2 | Т | 0 | 0.0 | 227 | 3.1 | 48.9 | 0 | 0.0 | | 227 | 3.1 | 48.9 |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 137 | 0.3 | 8.1 | | | | 137 | 0.3 | 8.1 |
| 3 | Т | 0 | 0.0 | 3183 | 5.9 | 6.6 | 0 | 0.0 | | 3183 | 5.9 | 6.6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 18 | 0.2 | 38.2 | | | | 18 | 0.2 | 38.2 |
| 4 | Т | 0 | 0.0 | 209 | 2.5 | 43.5 | 0 | 0.0 | | 209 | 2.5 | 43.5 |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7154 | 20 | 10.2 | | | | 7154 | 0 | 0.0 |
| | | | | | | | | | | | | |

| тсѕ | = | 11 F | | ian - Vehio s & Stops a [.] | | 2 | • | | | | | |
|-----|-----|------|-------|---|-----|------|------|-----|---|----|----|--|
| ^ | 5.4 | | 5 | | | | | | | | | |
| | IVI | Peds | ретау | Aver Vehs | - | | | | | | | |
| 1 | L | | | 4 | 0.0 | 3.0 | 1 | 0.2 | Α | 0 | 6 | |
| 1 | Т | 0 | 0.0 | 3177 | 2.6 | 3.0 | 539 | 0.2 | Α | 16 | 36 | |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 199 | 2.7 | 48.1 | 184 | 0.9 | D | 5 | 36 | |
| 2 | Т | 0 | 0.0 | 227 | 3.1 | 48.9 | 212 | 0.9 | D | 6 | 42 | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 137 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | Т | 0 | 0.0 | 3183 | 0.0 | 0.0 | 0 | 0.0 | Α | 0 | 6 | |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 18 | 0.2 | 38.2 | 14 | 0.8 | С | 0 | 6 | |
| 4 | Т | 0 | 0.0 | 209 | 2.5 | 43.5 | 182 | 0.9 | D | 5 | 36 | |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7154 | 11 | 5.6 | 1131 | 0.2 | Α | | | |
| | | | | | | | | | | | | |

Church Street Future with Development – CHURCHF.DAT

SCATES Program Version: 2013 Date: 02-NOV-12 Time: Registered User Name. - Road Delay Solutions Pty Ltd Registered User No. - 0 Data File: CHURCHF CHURCH STREET 2031 BITZIOS VOLUMES

| | | | AM PEA | ٩K | | | | PM PEA | ٩K | | | E | BUSINE | SS | |
|----------|------|-------|--------|------|------|--------|-------|--------|-----------|------|----------|------|--------|------|-----|
| AM | Vol | Sat | Phse | | | Vol | Sat | Phse | | | | Sat | Phse | | |
| | | | | | Loss | | | | | Loss | | | | Gain | |
| 1L | 0000 | | | | 0.0 | 0700 | | • | | 0.0 | | 5000 | | 0 | 0.0 |
| 1T 1R | 3086 | 5880 | A | | | 3708 | 5880 | A | | | 2378 | 5880 | A | | |
| 2L | | | | | | | | | | | | | | | |
| 2T | | | | | | | | | | | | | | | |
| 2R | | | | | | | | | | | | | | | |
| 3L | | | | 0 | 0.0 | | | | 0 | 0.0 | | | | 0 | 0.0 |
| ЗТ | 3507 | 5880 | Α | 0 | 254 | 3673 | 5880 | А | 0 | 165 | 2513 | 5880 | Α | 0 | 147 |
| ЗR | | | | | | | | | | | | | | | |
| 4L | | | | | | | | | | | | | | | |
| 4T | | | | | | | | | | | | | | | |
| 4R | - M | | | | | ^ | | Wolk | LIQ- A M | H%PM | LI%-D | | | | |
| Type | | URCHF | | | | A 1 | | Walk | п∻АМ 2 | | п≈в 3 | | | | |
| LTTE | - UП | ОКСПГ | | | | 2 | | 28 | 2 | 2 | 3 | | | | |
| TCS = | = 19 | 56 | | | | 3 | | 20 | 2 | 2 | 3 | | | | |
| | | | | | | 4 | | | - | _ | - | | | | |
| | | PEDES | TRIAN | VOLU | ΛE | WAL | <-CLE | ARANCE | | TRAM | DATA | PE | EDEST | TRA | M |
| Арр | P#. | AM | P#PM | Pi | #B | Wall | < (| Clear | | | | FA | ACT | FAC | т |
| 1 | 0 | | 0 | (| C | 0 | (| 0 | (| 0% | | 1 | 00 | 10 | 00 |
| 2 | 3 | - | 30 | | 30 | 6 | | 22 | | 0% | | | 30 | 10 | |
| 3 | 0 | | 0 | |) | 0 | | 0 | | 0% | | | 00 | 10 | |
| 4 | 2 | 0 | 20 | 2 | 20 | 6 | | 22 | (| 0% | | 3 | 30 | 10 | 00 |
| | | | | | | | | | | | | | | | · - |

| | | | AM PEA | ٨K | | | F | PM PE | ٩K | | | E | BUSINE | ESS | |
|------|------|------|--------|------|------|------|------|-------|------|------|------|------|--------|--------|------|
| AM | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers | Vol | Sat | Phse | MocV | Pers |
| | | | | Gain | Loss | | | | Gain | Loss | | | | Gain | Loss |
| 1L | 19 | 1750 | Α | 0 | 0.0 | 74 | 1750 | Α | 0 | 0.0 | 33 | 1750 | Α | 0 | 0.0 |
| 1T | 3067 | 5670 | Α | 0 | 1 | 3634 | 5670 | Α | 0 | 0 | 2346 | 5670 | Α | 1 | 0 |
| 1R | | | | | | | | | | | | | | | |
| 2L | | | | | | | | | | | | | | | |
| 2T | | | | | | | | | | | | | | | |
| 2R | | | | | | | | | | | | | | | |
| ЗL | | | | 0 | 0.0 | | | | 0 | 0.0 | | | | 0 | 0.0 |
| ЗT | 3492 | 5880 | Α | 184 | 0 | 3704 | 5880 | AB | 420 | 0 | 2518 | 5880 | AB | 213 | 0 |
| ЗR | 0 | 1800 | S | | | 0 | 1800 | В | | | 0 | 1800 | В | | |
| 4L | 119 | 1750 | В | | | 39 | 1750 | BC | | | 55 | 1750 | BC | | |
| 4T | | 3600 | | | | | 3600 | | | | | 3600 | | | |
| 4R | 269 | 3600 | В | | | 133 | 3600 | С | | | 141 | 3600 | С | | |
| Туре | = T4 | | | | | А | Min | ELT | H%AM | H%PM | H%B | L/S | L-PD | R - PD | |

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| File = | CHURCH | F | | 1 2 | 22 | 4.0 | 2 | 2 | 3 | 0 ' | 0 | |
|--------|--------|----------|-------|-------------|---------|------------|--------|--------|--------|-----|---|--------|
| TCS = | 448 | | | 2 3 4 | 5 28 | 4.0 4.0 | 2 0 | 2 0 | 3 0 | 0 ' | 0 | 0 0 |
| | PEDE | STRIAN V | OLUME | 4 WALK- | | | - | AM DA | - | PED | - | TRAM |
| Арр | P#AM | P#PM | P#B | Walk | С | lear | | | | FAC | т | FACT |
| 1 | 50 | 50 | 30 | 6 | 1 | 6 | 0% | | | 30 |) | 100 |
| 2 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 10 | 0 | 100 |
| 3 | 0 | 0 | 0 | 0 | 0 | | 0% | | | 10 | 0 | 100 |
| 4 | 50 | 50 | 30 | 6 | 2 | 2 | 0% | | | 30 | | 100 |
| | | | | | | | | | | | | |

| | | AM PEA | | | | | | | | | | BUSIN | | |
|------------|---|---|---|------------|-------------------------------|--------------|------------------------|---------------------|--|---|----------------------------|--------------------|----------------|--------------|
| AM V | 'ol Sat | Phse | MocV Gain | | | Sat | Phse | | Pers Loss | | Sat | Phse | | Pers Loss |
| 1L | 9 1750 | А | | | | 1750 | А | | 0.0 | | 1750 | А | | 0.0 |
| | 40 5560 | Α | | | 3028 | 5560 | | 0 | 640 | 2159 | 5560 | A | | 238 |
| | 0 0 | | | | | 0 | S | | | | 0 | - | | |
| | 02 1750 24 1960 | | | | | 1750 1960 | B B | | | | 1750 1960 | | | |
| | 0 0 | | | | | 0 | B | | | | 0 | | | |
| | 30 1750 | | | 0.0 | 202 | | | | 0.0 | | | A | | 0.0 |
| | 12 5670 0 0 | | | | | 5670 | A | | | | 5670 | | | |
| | 20 1750 | - | | | - | 0 1750 | S B | | | 16 | 0 1750 | - | | |
| | 17 1960 | | | | 188 | | B | | | | 1960 | B | | |
| | 0 0 | | | | 0 | - | В | | | 0 | - | _ | | |
| ••• | 0000 | | | | A | Min | | | H%PM | | | | | |
| File = | CHURCHE | | | | 1 | 5 5 | 4.0 4.0 | | 2 1 | - | 0' 0' | 0 | - | |
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| | | | | | 4 | | | 1 | | 2 | 0 ' | 0 | - | |
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| 2 | 0 | 0 | 0 | | - | C | | | 0% 0% | | | 100 | | 00 |
| 3 | 0 | 0 | 0 | | | C | | | 0% | | | 100 | | 00 |
| 4 | 0 | 0 | 0 | | 0 | C | | | 0% | | | 100 | | 00 |
| File = | Type L T T T AM O CHURCHF | ength 9999 9999 9999 Parkin PM 0 0 | Grade 0 Sat 1960 1960 1960 | Type AM | Lar e Lenç No Par Pî | rking M E | ade at ⁻ | Гуре Т Т Т | Lanes 3 Lengtl 9999 9999 9999 9999 | s Grac (1 Sa ⁺ 1960 1960 1960 1960 BUS | de) t Ty)) | L pe Le No P | anes (ngth | Grade Sat |
| Туре = | | | | | - 1956 | | | | | | | | | |
| | | | | | | | | | | | | | | |
| | | PROACI | | | | | | | | | | | | |
| Tidal N | Down 0 | | Grade 0 | Dowr | n Lar | nes Gr | ade I | | Lane: 3 | | de Dov) | wn L | anes (2 | Grade O |
| Lane | Type L | - | | ανΤ | e Lend | ath S | at ' | | Jengti | | | pe Le | _ | |
| 1 | | 9999 | | 21-1 | | | | | 9999 | | | | | |
| 2 | | | | | | | | - | | | | 0 | | |
| 2 | Т | 9999 | | | | | | T | 9999 | 1960 |) | R 9 | | 1850 |

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| 3 4 5 | т | 9999 | 1960 | | | | т | 9999 | 1960 | | | |
|-------------|--------|--------|------|-------|-------|-----|----|-------|------|----|--------|-----|
| 6 | | | | | | | | | | | | |
| 7 | | | | | | | | | | | | |
| 8 | | | | | | | | | | | | |
| | No | Parkir | ng | No | Parki | ng | No | Parki | ng | No | Parkir | ng |
| | AM | PM | BUS | AM | PM | BUS | AM | PM | BUS | AM | PM | BUS |
| Apprch | 0 | 0 | 0 | | | | 0 | 0 | 0 | 0 | 0 | 0 |
| Depart | 0 | 0 | 0 | | | | 0 | 0 | 0 | 0 | 0 | 0 |
| File = C | HURCHF | - | | | | | | | | | | |
| Type = T | 4 | | | rcs = | 448 | | | | | | | |
| | | | | | | | | | | | | |

APPROACH 1 APPROACH 2 APPROACH 3 APPROACH 4 Tidal Down Lanes Grade Down Lanes Grade Down Lanes Grade Down Lanes Grade 0 3 0 0 2 0 0 3 0 0 2 0 N Type Length Sat Type Length Sat Type Length Sat Type Length Sat Lane LT 9999 1750 L 90 1750 LT 9999 1750 L 9999 1750 T 9999 1960 T 9999 1960 T 9999 1960 T 9999 1960 T 9999 1850 T 9999 1960 1 2 3 4 5 6 7 8 No Parking No Parking No Parking No Parking
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 Stps
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 Mode
 0
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 File
 CHURCHE
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 Bay Bay Slip Slip Req Act Req Act File = CHURCHF Type TCS = 1956 М -----. PM PEAK AM PEAK BUSINESS
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 Stps
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 Mode
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 1
 DS
 0.84
 0.82
 1
 DS
 0.59
 0.59

 File
 CHURCHF
 A
 Bay
 Bay
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 Slip
 Type

 Req Act Req Act 10 0 TCS = 448Τ4 1

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| AM PEAK PM PEAK BL Ph GT% GT% CL CL GT% GT% CL CL GT% GT% <th>JSINESS CL CL CORD ISOL 99 46</th> | JSINESS CL CL CORD ISOL 99 46 |
|--|---|
| Stps 3.8 3.8 Stps 4.0 4.1 S | dlay dlay 0.0 0.0 dlay 11 8 Stps 2.1 2.7 DS 0.56 0.62 Type COCO |
| Bays if all intersections are o | • |
| TCS = 1956 Isolated Operation Degree of Saturation for PM Peak CH Co-ordinated Cycle Length Isolated Cycle L A M DS GT Delay Stops Queue Metre DS GT Delay Stops 1 L | _ength |
| 1 L 1 T 0.86 96 12 2385 34 72 0.83 108 11 2181 1 R 2 L 2 T 2 R 3 L | 1 34 72 |
| 3 T 0.85 96 11 2322 33 72 0.83 108 10 2123 3 R 4 L 4 T 4 R | 3 33 72 |
| INT 0.86 128 0.83 140 | |
| TCS = 1956 Pedestrian - Vehicle Delay PM Peak File = CHURCHF Isolated Operation | |
| Co-ordinated Cycle Length Isolated Cycle L A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh | |
| 1 L 1 T 0 0.0 3782 11.8 11.2 0 0.0 3782 1 R 2 L | 2 10.8 10.2 |
| 2 T 30 0.5 58.1 30 0.5 64.1 2 R | |
| 3 L 3 T 0 0.0 3746 11.5 11.0 0 0.0 3746 3 R 4 L | 6 10.5 10.1 |

| 4 T 20 4 B | 0.3 | 58.1 | | | | 20 | 0.4 | 64.1 | | | |
|---------------|-----|------|------|----|------|----|-----|------|------|---|-----|
| | 1 | 58.1 | 7528 | 23 | 11.1 | 50 | 1 | 64.1 | 7528 | 0 | 0.0 |

| | | | - Dela | ys & S [.] | tops a [.] | cle Del fter Co | -ordir | nated E | Evaluat | ion | | | |
|-------------|------------------|------|--------|---------------------|---------------------|--------------------|--------|---------|---------|---------|--------|---------|-------|
| A | | Peds | Delay | Aver | Vehs | Delay | Aver | Stops | Aver | LOS | | | |
| 1 1 1 | L T R | 0 | 0.0 | | 3782 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 2 2 | L T R | 30 | 0.5 | 58.1 | | | | | | | | | |
| 3 3 3 | L T R | 0 | 0.0 | | 3746 | 10.8 | 10.4 | 1203 | 0.3 | A | 33 | 72 | |
| 4 4 4 | L T R | 20 | 0.3 | 58.1 | | | | | | | | | |
| INT | | | | | | 11 | | | | | | | |
| | | | | | | | | | | | | | |
| тсѕ | = | 1956 | Co-ord | inated | Cycle | Degree Length | | | - Isola | ated Cy | cle Le | ength - | |
| A 1 | M | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| ' 1 1 | TR | 0.62 | 67 | 6 | 1221 | 22 | 48 | 0.62 | 67 | 6 | 1221 | 22 | 48 |
| 2 | L T R L | | | | | | | | | | | | |
| 3 3 4 | T R L T | 0.65 | 67 | 7 | 1345 | 23 | 48 | 0.65 | 67 | 7 | 1345 | 23 | 48 |
| 4 INT | R | 0.65 | 99 | | | | | 0.65 | 99 | | | | |
| | | | | | | | | | | | | | |
| тсѕ | = | 1956 | Pedest | rian | | cle Del solated | | | Peak F | ile = | CHURCH | IF | |
| | | | | | Cycle | Length | | | | | | | |
| A 1 | M | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 1 | T R | 0 | 0.0 | | 2449 | 6.0 | 8.9 | 0 | 0.0 | | 2449 | 6.0 | 8.9 |
| 2 2 2 | L T R | 30 | 0.4 | 43.7 | | | | 30 | 0.4 | 43.7 | | | |
| 3 3 3 | L T R | 0 | 0.0 | | 2588 | 6.6 | 9.2 | 0 | 0.0 | | 2588 | 6.6 | 9.2 |
| 4 4 | L T | 20 | 0.2 | 43.7 | | | | 20 | 0.2 | 43.7 | | | |
| 4 INT | R | 50 | 1 | 43.7 | 5037 | 13 | | 50 | 1 | 43.7 | 5037 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| TCS | = | 1956 P | | | | | 2 | • | | | File = | |
|-----|---|--------|-----|------|------|-----|-----|---|-----|---|--------|---|
| А | М | Peds | - | | • | | | | | | | |
| 1 | L | | - | | | - | | • | | | | |
| 1 | Т | 0 | 0.0 | | 2449 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | |
| 2 | Т | 30 | 0.4 | 43.7 | | | | | | | | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 2588 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | | | | | | | | |
| 4 | Т | 20 | 0.2 | 43.7 | | | | | | | | |
| 4 | R | | | | | | | | | | | |
| INT | | 50 | 1 | 43.7 | 5037 | 0 | 0.0 | 0 | 0.0 | A | | |
| | | | | | | | | | | | | |

| ^ | | 1956 I C | o-ordi | nated | Cycle | Length Queue | | | Isola | ated Cy | cle Le | ength - | Motr |
|------------------|-----------------------|--------------------|----------------|--------|----------------|------------------|----------------|-----------------|----------------|------------|--------|---------|----------|
| A 1 | M L | DS | GI | ретау | Scops | Queue | Merre | 05 | GI | ретау | Scops | Queue | metre |
| 1 1 2 2 | T R L T | 0.77 | 73 | 9 | 1858 | 28 | 60 | 0.77 | 73 | 9 | 1858 | 28 | 6 |
| 2 3 3 3 | R L T R L | 0.88 | 73 | 12 | 2507 | 32 | 66 | 0.88 | 73 | 12 | 2507 | 32 | 6 |
| 4 4 NT | R | 0.88 | 105 | | | | | 0.88 | 105 | | | | |
| CS. | | 1956 P | | | | | | | | | | | |
| 00 | | | | | Is | solated | Opera | tion | | | | | |
| | | | | | | Length | | | | | | | |
| | M L | Peas | ретау | Aver | vens | Delay | Aver | Peas | ретай | Aver | ven | ретай | Ave |
| 1 1 2 | T R L | 0 | 0.0 | | 3148 | 9.2 | 10.5 | 0 | 0.0 | | 3148 | 9.2 | 10. |
| 2 2 | T R | 30 | 0.4 | 46.7 | | | | 30 | 0.4 | 46.7 | | | |
| 3 | L T R | 0 | 0.0 | | 3577 | 12.4 | 12.5 | 0 | 0.0 | | 3577 | 12.4 | 12. |
| 4 | L T | 20 | 0.3 | 46.7 | | | | 20 | 0.3 | 46.7 | | | |
| 4 NT | | 50 | | | | 22 | | | | 46.7 | | | |
| A 1 | M L | 1956 P Peds | Delay Delay | s & St | ops at Vehs | fter Co Delay | -ordir Aver | ated E Stops | valuat Aver | ion LOS | | | |
| 1 1 2 | T R L | 0 | 0.0 | | 3148 | 0.0 | 0.0 | 0 | 0.0 | A | 0 | 6 | |
| 2 2 3 | T R L | 30 | 0.4 | 46.7 | | | | | | | | | |
| 3 3 3 4 | T R L | 0 | 0.0 | | 3577 | 2.1 | 2.1 | 368 | 0.1 | A | 11 | 24 | |
| 4 4 4 | Т | 20 | 0.3 | 46.7 | | | | | | | | | |
| | R | 50 | | | | | | 368 | | А | | | |

November 2012

| TCS | = | 448 I | | • | | 0 | | | | | | | |
|-----|---|-------|--------|--------|-------|--------|-------|------|-------|---------|---------|-------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.81 | 103 | 0 | 40 | 1 | 30 | 0.80 | 115 | 0 | 36 | 1 | 60 |
| 1 | Т | 0.84 | 103 | 8 | 2008 | 26 | 60 | 0.82 | 115 | 7 | 1836 | 26 | 60 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | | | | | | | | | | | | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | |
| 3 | Т | 0.74 | 112 | 3 | 1230 | 17 | 36 | 0.73 | 124 | 3 | 1125 | 17 | 36 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.44 | 17 | 1 | 32 | 1 | 12 | 0.48 | 17 | 1 | 33 | 1 | 12 |
| 4 | Т | | | | | | | | | | | | |
| 4 | R | 0.69 | 8 | 2 | 118 | 4 | 18 | 0.75 | 8 | 3 | 133 | 5 | 24 |
| INT | | 0.84 | 128 | | | | | 0.82 | 140 | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 448 | Pedest | rian · | | cle Del solated | | | =ile = | CHURCH | IF | | |
|-----------------------|-----------------------|------|------------------|-----------------|-----------------------|---|------------------------|-----------------------|------------------------|--------|---------|--------|-------|
| | | | Co-ord | inatod | | Length | | | . Isola | tod Cv | | nath - | |
| А | М | Pode | | Avor | Vohe | Delay | Avor | Dode | Dolay | Avor | Voh | Dolay | Avor |
| | | reus | ретау | Avei | Velis 70 | | Aver | reus | Бетау | Avei | | | |
| 1 | L | | | | /5 | 0.2 | 9.8 | | | | 75 | | |
| 1 | Т | 50 | 0.8 | 58.1 | 3707 | 7.9 | 7.6 | 50 | 0.9 | 64.1 | 3707 | 7.2 | 7.0 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | 0 | 0.0 | | | | | 0 | 0.0 | | | | |
| 2 | R | Ŭ | 010 | | | | | 0 | 010 | | | | |
| | | | | | | | | | | | | | |
| | L | | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 3778 | 3.1 | 3.0 | 0 | 0.0 | | 3778 | 2.8 | 2.7 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 39 | 0.6 | 50.8 | | | | 39 | 0.6 | 57.1 |
| | Т | 50 | <u> </u> | 58.1 | | 010 | 0010 | 50 | 0 0 | 64.1 | | 0.0 | 0/11 |
| | | 50 | 0.0 | 50.1 | 400 | ~ ~ | | | 0.9 | 04.1 | 400 | ~ ~ | |
| | R | | | | 133 | | 59.3 | | | | 133 | 2.9 | 78.2 |
| INT | | 100 | 2 | 58.1 | 7732 | 14 | 6.5 | 100 | 2 | 64.1 | 7732 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| A 1 1 1 | M L T R | | - Delay Delay | ys & S† Aver | tops at Vehs 75 | cle Del fter Co Delay 0.0 1.5 | o-ordin Aver 1.5 | nated E Stops 8 | Evaluat Aver 0.1 | | 0 | | |
| | L T R L T | 0 | | | 3778 | 0.4 | 0.4 | 137 | 0.0 | А | 5 | 12 | |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 39 | 0.6 | 50.8 | 32 | 0.8 | D | 1 | 12 | |
| 4 | Т | 50 | 0.8 | 58.1 | | 010 | 0010 | 01 | 010 | 2 | | | |
| | | 50 | 0.0 | 50.1 | 400 | ~ ~ | | | ~ ~ | - | | 10 | |
| | R | | | | 133 | | 59.3 | | | E | 4 | 18 | |
| INT | | 100 | 2 | 58.1 | 7732 | 5 | 2.2 | 705 | 0.1 | Α | | | |
| | | | | | | | | | | | | | |
| TCS | = | 448 | Isolat | ed Opeı | ration | Degree | of Sa | aturati | ion for | Busir | ness Pe | ak CHU | IRCHF |
| | | | Co-ord | inated | Cvcle | Length | | | - Isola | ted Cv | cle Le | nath - | |
| А | М | DS | | | | Queue | | | | | | | |
| 1 | | | | | 14 | | | 0.58 | 74 | | 14 | | |
| | L | 0.58 | | | | 0 | | | | | | 0 | 36 |
| 1 2 2 2 3 | T R L T R | 0.59 | 74 | 4 | 989 | 17 | 42 | 0.59 | 74 | 4 | 989 | 17 | 42 |
| | L | 0 | | ~ | <u> </u> | 10 | ~ ~ | 0 50 | 00 | ~ | co7 | 10 | 0.4 |
| 3 | Т | 0.53 | 83 | 2 | 697 | 12 | 24 | 0.53 | 83 | 2 | 697 | 12 | 24 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.41 | 17 | 1 | 44 | 1 | 12 | 0.41 | 17 | 1 | 44 | 1 | 12 |
| 4 | Т | | | • | | - | | | | - | | | • = |
| 4 | R | 0 50 | 0 | 2 | 100 | 4 | 10 | 0 50 | 0 | 2 | 100 | 4 | 18 |
| | 'n | 0.59 | | 2 | 122 | 4 | 10 | 0.59 | 8 | 2 | 122 | 4 | 10 |
| INT | | 0.59 | 99 | | | | | 0.59 | 99 | | | | |
| | | | | | | | | | | | | | |
| | | | | | | | | | | | | | |

| TCS | = | 448 | Pedestr | ian | - Vehi | cle Dela | ay Bus | siness | Peak F | ile = | CHURCH | ΙF | |
|-----|---|------|---------|-------|--------|----------|--------|--------|---------|--------|--------|---------|------|
| | | | | | Is | solated | Opera | ation | | | | | |
| | | | Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 34 | 0.1 | 5.7 | | | | 34 | 0.1 | 5.7 |
| 1 | Т | 30 | 0.4 | 43.7 | 2416 | 3.9 | 5.8 | 30 | 0.4 | 43.7 | 2416 | 3.9 | 5.8 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | | |
| 2 | Т | 0 | 0.0 | | | | | 0 | 0.0 | | | | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | | |
| 3 | Т | 0 | 0.0 | | 2594 | 1.8 | 2.5 | 0 | 0.0 | | 2594 | 1.8 | 2.5 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 55 | 0.6 | 36.2 | | | | 55 | 0.6 | 36.2 |
| 4 | Т | 30 | 0.4 | 43.7 | | | | 30 | 0.4 | 43.7 | | | |
| 4 | R | | | | 141 | 1.7 | 43.6 | | | | 141 | 1.7 | 43.6 |
| INT | | 60 | 1 | 43.7 | 5240 | 8 | 5.5 | 60 | 1 | 43.7 | 5240 | 0 | 0.0 |
| | | | | | | | | | | | | | |

| At M Peds Delay Aver Vehs Delay Aver Vehs Delay Aver Stops Aver LOS 1 34 0.0 1.1 3 0.1 A 0 6 1 T 30 0.4 43.7 2416 0.8 1.1 195 0.1 A 5 12 1 T 30 0.4 43.7 2416 0.8 1.1 195 0.1 A 5 12 2 T 0 0.0 2594 0.2 0.2 63 0.0 A 2 6 3 T 0 0.0 2594 0.2 0.2 63 0.0 A 2 6 3 T 0 0.0 2594 0.2 0.2 63 0.0 A 2 6 3 L 0 0 143.7 540 3 2.2 427 0.1 A 1NT 0.61 Delay Stops Queue Metre DS GT Delay Stops Q | | | | Pedest | | | | | | | | | | RCHF |
|--|-------|---|------|--------|--------|------------|---------|------------|--------|---------|---------|---------|---------|------|
| <pre>1 T 30 0.4 43.7 2416 0.8 1.1 195 0.1 A 5 12 2 L 2 T 0 0.0 2 R 3 L 3 T 0 0.0 2594 0.2 0.2 63 0.0 A 2 6 3 R 4 L 55 0.6 36.2 44 0.8 C 1 12 4 T 30 0.4 43.7 4 R 55 0.6 36.2 44 0.8 C 1 12 4 T 30 0.4 43.7 4 R 141 1.7 43.6 122 0.9 D 3 18 INT 60 1 43.7 5240 3 2.2 427 0.1 A TCS = 448 Isolated Operation Degree of Saturation for AM Peak CHURCHF Co-ordinated Cycle Length Isolated Cycle Length Isolated</pre> | | | | | | | | | | | | | | |
| $ \begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | | | | | | | | | | | | |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | 30 | 0.4 | 43.7 | 2416 | 0.8 | 1.1 | 195 | 0.1 | A | 5 | 12 | |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | | | | | | | | | | | | |
| $ \begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | 0 | 0.0 | | | | | | | | | | |
| $ \begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | 0 | 0.0 | | | | | | | | | | |
| 3 T 0 0.0 2594 0.2 0.2 63 0.0 A 2 6 3 R 55 0.6 36.2 44 0.8 C 1 12 4 T 30 0.4 43.7 55 0.6 36.2 44 0.8 C 1 12 4 T 30 0.4 43.7 5240 3 2.2 427 0.1 A TOS = 448 Isolated Operation Degree of Saturation for AM Peak CHURCHF | | | | | | | | | | | | | | |
| $ \begin{array}{cccccccccccccccccccccccccccccccccccc$ | | Г | 0 | 0.0 | | 2594 | 0.2 | 0.2 | 63 | 0.0 | Α | 2 | 6 | |
| 4 T 30 0.4 43.7 4 R 141 1.7 43.6 122 0.9 D 3 18 INT 60 1 43.7 5240 3 2.2 427 0.1 A TCS = 448 Isolated Operation Degree of Saturation for AM Peak CHURCHF Co-ordinated Cycle Length Isolated Cycle Length A M DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre 1 L 0.43 78 0 6 0 6 0.43 78 0 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 1 R 2 L 2 T 2 R 3 L 3 T 0.82 78 9 2078 26 54 0.82 78 9 2078 26 54 3 R 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 T 4 R 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Operation Co-ordinated Cycle Length Isolated Cycle Length TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Operation Co-ordinated Cycle Length Isolated Cycle Length A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh Delay Aver 1 L 2 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 2 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 2 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 119 1.8 53.7 4 T 50 0.6 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | | | | | | | | | | | | |
| 4 R 141 1.7 43.6 122 0.9 D 3 18 INT 60 1 43.7 5240 3 2.2 427 0.1 A TCS = 448 Isolated Operation Degree of Saturation for AM Peak CHURCHF | | | | ~ . | 40 - | | 0.6 | 36.2 | 44 | 0.8 | С | 1 | 12 | |
| INT 60 1 43.7 5240 3 2.2 427 0.1 A TCS = 448 Isolated Operation Degree of Saturation for AM Peak CHURCHF Co-ordinated Cycle Length Isolated Cycle Length Isolated Cycle Length A M DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre 1 L 0.43 78 0 6 0 6 0.43 78 0 6 0 6 1 I 0.43 78 0 6 0 6 0.43 78 7 1614 23 54 2 I 2 7 2 7 2 7 2 7 2 7 2 7 2 1614 23 54 2.5 3 7 1614 23 54 3 T 0.82 78 9 2078 26 54 0.82 19 2 118 24 4 7 4 7 4 7 4 7 4 7 | | | 30 | 0.4 | 43.7 | | 1 7 | 12 6 | 100 | 0.0 | Р | 2 | 10 | |
| TCS = 448 Isolated Operation Degree of Saturation for AM Peak CHURCHF Solated Cycle Length Isolated Cycle Length Isolated Cycle Length A M DS GT Delay Stops Queue Metre D G 0 6 0.43 78 0 6 0 6 1 L 0.43 78 0 6 0 6 0.43 78 0 6 0 6 O 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 2 L | | | 60 | 1 | 43 7 | | | | | | | 3 | 10 | |
| Co-ordinated Cycle Length Isolated Cycle Length Isolated Cycle Length A M DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre 1 L 0.43 78 0 6 0 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 2 L - <td< td=""><td></td><td></td><td></td><td></td><td>40.7</td><td>5240</td><td></td><td>2.2</td><td>427</td><td></td><td></td><td></td><td></td><td></td></td<> | | | | | 40.7 | 5240 | | 2.2 | 427 | | | | | |
| Co-ordinated Cycle Length Isolated Cycle Length Isolated Cycle Length A M DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre 1 L 0.43 78 0 6 0 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 2 L - <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<> | | | | | | | | | | | | | | |
| Co-ordinated Cycle Length Isolated Cycle Length Isolated Cycle Length A M DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre 1 L 0.43 78 0 6 0 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 2 L - <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<> | | | | | | | | | | | | | | |
| A M DS GT Delay Stops Queue Metre DS GT Delay Stops Queue Metre 1 L 0.43 78 0 6 0 6 0.43 78 0 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 1 R . | TCS = | = | | | | | | | | | | | | |
| 1 L 0.43 78 0 6 0.43 78 0 6 0 6 1 T 0.75 78 7 1614 23 54 0.75 78 7 1614 23 54 2 L 2 T 7 1614 23 54 0.75 78 7 1614 23 54 2 L 2 T 7 1614 23 54 0.82 78 9 2078 26 54 3 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 T 0.82 19 2 118 3 24 0.82 105 0.0 0 0.0 0 0.0 0 0.0 0 0.0 0 0.0 0 0.0 0 | | | | | | | | | | | | | | |
| 1 R 2 T 2 T 3 L 3 L 3 L 3 L 4 L 0.82 78 9 2078 26 54 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 R 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 0.82 105 0.82 105 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Cycle Length Isolated Operation Co-ordinated Cycle Length 1 19 0.0 5.0 19 0.0 5.0 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 19 | | | | | Оетау | SLOPS 6 | Queue | Metre 6 | 0 43 | 78 | Delay | | | |
| 1 R 2 T 2 T 3 L 3 L 3 L 3 L 4 L 0.82 78 9 2078 26 54 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 R 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 0.82 105 0.82 105 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Cycle Length Isolated Operation Co-ordinated Cycle Length 1 19 0.0 5.0 19 0.0 5.0 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 19 | | | | | 7 | 1614 | 23 | 54 | 0.75 | 78 | 7 | - | - | |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | 0170 | , 0 | | 1011 | 20 | 01 | 0170 | , 0 | | 1011 | 20 | 01 |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | | | | | | | | | | | | |
| 3 L 3 T 0.82 78 9 2078 26 54 3 R 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 T | | Г | | | | | | | | | | | | |
| 3 T 0.82 78 9 2078 26 54 0.82 78 9 2078 26 54 3 R 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 T 4 T 6 30 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 0.82 105 6 30 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Operation 10.0 5.0 19 0.0 5.0 1 L 19 0.0 5.0 19 0.0 5.0 19 0.0 5.0 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 19 0.0 | | | | | | | | | | | | | | |
| 3 R 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 R 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 0.82 105 0 30 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Operation | | | | | | ~~~~ | | | | | | ~~~~ | | |
| 4 L 0.82 19 2 118 3 24 0.82 19 2 118 3 24 4 T 4 R 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 0.82 105 6 30 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Operation | | | 0.82 | 78 | 9 | 2078 | 26 | 54 | 0.82 | 78 | 9 | 2078 | 26 | 54 |
| $ \begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | 0 82 | 10 | 2 | 118 | 3 | 24 | 0 82 | 10 | 2 | 118 | 3 | 24 |
| 4 R 0.55 19 3 221 6 30 0.55 19 3 221 6 30 INT 0.82 105 0.82 105 0.82 105 3 221 6 30 TCS = 448 Pedestrian - Vehicle Delay AM Peak File = CHURCHF Isolated Operation Co-ordinated Cycle Length A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver 1 L 19 0.0 5.0 19 0.0 5.0 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 R 119 1.8 53.7 19 1.8 53.7 2 R 119 1.8 53.7 119 1.8 53.7 3 T 0 0.6 46.7 50 0.6 46.7 46.7 | | | 0.02 | 13 | 2 | 110 | 0 | 27 | 0.02 | 13 | 2 | 110 | 0 | 27 |
| $TCS = 448 \text{ Pedestrian } \cdot \text{Vehicle Delay AM Peak File = CHURCHF}_{Isolated Operation} \\ Co-ordinated Cycle Length Isolated Cycle Length A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh Delay Aver 1 L 19 0.0 5.0 19 0.0 5.0 19 0.0 5.0 11 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 R 2 L 2 7 0 0.0 0.0 2 R 3 L 2 2 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 4 L 119 1.8 53.7 119 1.8 53.7 4 T 50 0.6 46.7 50 0.6 46.7 30.0 119 1.8 53.7 $ | | | 0.55 | 19 | 3 | 221 | 6 | 30 | 0.55 | 19 | 3 | 221 | 6 | 30 |
| $\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$ | INT | | 0.82 | 105 | | | | | | 105 | | | | |
| Isolated Operation A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Delay Aver | | | | | | | | | | | | | | |
| Isolated Operation A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Delay Aver | | | | | | | | | | | | | | |
| Isolated Operation A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Delay Aver | TCS = | = | 448 | Pedest | rian | - Vehi | cle Del | av AM | Peak I | File = | CHURCH | IF | | |
| A M Peds Delay Aver Vehs Delay Aver Peds Delay Aver Veh Delay Aver 1 L 19 0.0 5.0 19 0.0 5.0 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 R 2 L 0 0.0 5.0 18 6.6 7.6 2 L 0 0.0 0.0 0.0 0.0 17 100 0.0 5.0 2 L 0 0.0 0.0 0.0 0.0 16 17 100 1.0 118 110 1.0 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 1.8 53.7 119 | 100 | | 440 | reacor | Tan | | | | | TIC | ononoi | | | |
| A M Peds Delay Aver Ven Delay Aver Ven Delay Aver Ven Delay Aver 1 L 19 0.0 5.0 19 0.0 5.0 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 R | | | | Co-ord | inated | | | | | - Isola | ated Cy | /cle Le | ength | |
| 1 T 50 0.6 46.7 3128 6.6 7.6 50 0.6 46.7 3128 6.6 7.6 1 R 2 L 0 0.0 50 0.6 46.7 3128 6.6 7.6 2 L 0 0.0 <td< td=""><td>A N</td><td>Λ</td><td></td><td></td><td></td><td>Vehs</td><td>Delay</td><td>Aver</td><td>Peds</td><td></td><td></td><td></td><td></td><td></td></td<> | A N | Λ | | | | Vehs | Delay | Aver | Peds | | | | | |
| 1 R 2 L 2 T 0 0.0 2 R 3 L 3 T 0 0.0 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R | | | | | | | | | | | | | | |
| 2 L 2 T 0 0.0 2 R 3 L 3 T 0 0.0 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R | | | 50 | 0.6 | 46.7 | 3128 | 6.6 | 7.6 | 50 | 0.6 | 46.7 | 3128 | 6.6 | 7.6 |
| 2 T 0 0.0 0.0 0.0 2 R 0 0.0 0.0 0.0 3 L 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 119 1.8 53.7 119 1.8 53.7 4 L 119 1.8 53.7 50 0.6 46.7 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | | | | | | | | | | | | |
| 2 R 3 L 3 L 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 119 1.8 53.7 119 1.8 53.7 4 T 50 0.6 46.7 50 0.6 46.7 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | 0 | 0 0 | | | | | 0 | 0.0 | | | | |
| 3 L 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 119 1.8 53.7 119 1.8 53.7 4 T 50 0.6 46.7 50 0.6 46.7 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | U | 0.0 | | | | | 0 | 0.0 | | | | |
| 3 T 0 0.0 3562 8.5 8.6 0 0.0 3562 8.5 8.6 3 R 119 1.8 53.7 119 1.8 53.7 4 T 50 0.6 46.7 50 0.6 46.7 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | | | | | | | | | | | | |
| 3 R 4 L 119 1.8 53.7 4 T 50 0.6 46.7 50 0.6 46.7 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | 0 | 0.0 | | 3562 | 8.5 | 8.6 | 0 | 0.0 | | 3562 | 8.5 | 8.6 |
| 4 T 50 0.6 46.7 50 0.6 46.7 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | | | | | | | | | | | | |
| 4 R 269 2.9 39.3 269 2.9 39.3 INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | | | | | 1.8 | 53.7 | | | | | 1.8 | 53.7 |
| INT 100 1 46.7 7097 20 10.1 100 1 46.7 7097 0 0.0 | | | 50 | 0.6 | 46.7 | | | | 50 | 0.6 | 46.7 | | <i></i> | |
| | | ł | 100 | - | 46 7 | | | | 100 | - | 16 7 | | | |
| | TINI | | 100 | | | | | | | | | | | |
| | | - | | | | | | | | | | | | |

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| TCS | = | 448 P | | | | cle Del fter Co | - | • | | | | HF |
|-----|---|--------|-----|------|------|--------------------|------|------|-----|---|----|--------|
| А | М | Peds I | - | | • | | | | | | | |
| 1 | L | | - | | 19 | 0.0 | 6.8 | 5 | 0.3 | Α | 0 | 6 |
| 1 | Т | 50 | 0.6 | 46.7 | 3128 | 5.9 | 6.8 | 794 | 0.3 | Α | 23 | 54 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | | | | | | | | | |
| 2 | Т | 0 | 0.0 | | | | | | | | | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | | | | | | | | | |
| - | Т | 0 | 0.0 | | 3562 | 1.8 | 1.8 | 588 | 0.2 | Α | 17 | 36 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | | 119 | 1.8 | 53.7 | 118 | 1.0 | D | 3 | 24 |
| - | Т | 50 | 0.6 | 46.7 | | | | | | | | |
| 4 | R | | | | 269 | 2.9 | 39.3 | 221 | 0.8 | С | 6 | 30 |
| INT | | 100 | 1 | 46.7 | 7097 | 12 | 6.3 | 1726 | 0.2 | Α | | |
| | | | | | | | | | | | | |

| TCS | = | 11 I | solat | ed Opei | ration | Degree | e of Sa | turati | on foi | ° PM P€ | eak CHL | JRCHF | |
|-----|---|------|-------|---------|--------|--------|---------|--------|--------|---------|---------|---------|-------|
| | | C | o-ord | inated | Cycle | Length | ו ו | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.39 | 97 | 0 | 5 | 0 | 6 | 0.40 | 78 | 0 | 6 | 0 | 6 |
| 1 | Т | 0.74 | 97 | 7 | 1536 | 27 | 60 | 0.75 | 78 | 7 | 1606 | 23 | 54 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.59 | 23 | 2 | 152 | 5 | 36 | 0.59 | 19 | 2 | 152 | 4 | 30 |
| 2 | Т | 0.79 | 23 | 4 | 257 | 9 | 54 | 0.80 | 19 | 4 | 266 | 7 | 48 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.79 | 97 | 1 | 116 | 2 | 102 | 0.80 | 78 | 1 | 122 | 2 | 54 |
| 3 | Т | 0.79 | 97 | 8 | 1726 | 27 | 66 | 0.80 | 78 | 7 | 1805 | 23 | 54 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.08 | 23 | 0 | 19 | 1 | 6 | 0.08 | 19 | 0 | 20 | 1 | 6 |
| 4 | Т | 0.54 | 23 | 3 | 155 | 6 | 36 | 0.55 | 19 | 2 | 156 | 5 | 30 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.79 | 128 | | | | | 0.80 | 105 | | | | |
| | | | | | | | | | | | | | |

TCS = 11 Pedestrian - Vehicle Delay PM Peak File = CHURCHF Isolated Operation

| | | (| Co-ordi | nated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength - | |
|-----|---|------|---------|-------|-------|--------|------|------|---------|--------|--------|---------|------|
| Α | М | Peds | Delay | Aver | Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | | 17 | 0.0 | 5.4 | | | | 17 | 0.0 | 4.8 |
| 1 | Т | 0 | 0.0 | | 3089 | 7.3 | 8.6 | 0 | 0.0 | | 3089 | 6.6 | 7.7 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 184 | 2.5 | 48.1 | | | | 184 | 2.0 | 39.7 |
| 2 | Т | 0 | 0.0 | | 278 | 4.4 | 57.4 | 0 | 0.0 | | 278 | 3.9 | 50.3 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | 206 | 0.6 | 11.3 | | | | 206 | 0.6 | 10.8 |
| 3 | Т | 0 | 0.0 | | 3174 | 8.3 | 9.4 | 0 | 0.0 | | 3174 | 7.4 | 8.4 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 26 | 0.3 | 43.7 | | | | 26 | 0.3 | 36.1 |
| 4 | Т | 0 | 0.0 | | 190 | 2.5 | 47.7 | 0 | 0.0 | | 190 | 2.1 | 39.4 |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 7164 | 26 | 13.1 | | | | 7164 | 0 | 0.0 |
| | | | | | | | | | | | | | |

TCS = 11 Pedestrian - Vehicle Delay - Stops PM Peak File = CHURCHF ----- Delays & Stops after Co-ordinated Evaluation-----

| Α | М | Peds | Delay | Aver Vehs | Delay | Aver | Stops | Aver | LOS | | | |
|-----|---|------|-------|-----------|-------|------|-------|------|-----|---|----|--|
| 1 | L | | | 17 | 0.0 | 0.2 | 0 | 0.0 | А | 0 | 6 | |
| 1 | Т | 0 | 0.0 | 3089 | 0.2 | 0.2 | 30 | 0.0 | А | 1 | 6 | |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 184 | 2.5 | 48.1 | 152 | 0.8 | D | 5 | 36 | |
| 2 | Т | 0 | 0.0 | 278 | 4.4 | 57.4 | 257 | 0.9 | Е | 9 | 54 | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 206 | 0.1 | 1.8 | 0 | 0.0 | А | 0 | 6 | |
| 3 | Т | 0 | 0.0 | 3174 | 1.6 | 1.8 | 0 | 0.0 | А | 0 | 6 | |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 26 | 0.3 | 43.7 | 19 | 0.7 | D | 1 | 6 | |
| 4 | Т | 0 | 0.0 | 190 | 2.5 | 47.7 | 155 | 0.8 | D | 6 | 36 | |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7164 | 12 | 5.8 | 614 | 0.1 | А | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |

| TCS | = | 11 I | solate | ed Opei | ration | Degree | e of Sa | turati | on fo | r Busir | ness Pe | eak CHL | JRCHF |
|-----|---|------|--------|---------|--------|--------|---------|--------|-------|---------|---------|---------|-------|
| | | C | o-ord: | inated | Cycle | Length | 1 | | Isola | ated Cy | /cle Le | ength · | |
| Α | М | DS | GT | Delay | Stops | Queue | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.24 | 75 | 0 | 2 | 0 | 6 | 0.27 | 31 | 0 | 3 | 0 | 6 |
| 1 | Т | 0.54 | 75 | 3 | 823 | 15 | 36 | 0.60 | 31 | 2 | 1081 | 9 | 24 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | 0.48 | 16 | 1 | 112 | 3 | 24 | 0.53 | 7 | 1 | 114 | 1 | 12 |
| 2 | Т | 0.56 | 16 | 2 | 147 | 4 | 30 | 0.62 | 7 | 1 | 150 | 2 | 12 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.56 | 75 | 0 | 46 | 1 | 96 | 0.62 | 31 | 0 | 60 | 0 | 24 |
| 3 | Т | 0.56 | 75 | 3 | 853 | 15 | 36 | 0.62 | 31 | 3 | 1119 | 9 | 24 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | 0.06 | 16 | 0 | 12 | 0 | 6 | 0.06 | 7 | 0 | 12 | 0 | 6 |
| 4 | Т | 0.45 | 16 | 2 | 118 | 3 | 24 | 0.50 | 7 | 1 | 120 | 2 | 12 |
| 4 | R | | | | | | | | | | | | |
| INT | | 0.56 | 99 | | | | | 0.62 | 46 | | | | |
| | | | | | | | | | | | | | |

| тсѕ | = | 11 P | edestr | rian | | | - | | Peak F | ile = | CHURCH | łF | |
|-----|---|------|--------|--------|-------|---------------------|-------|------|---------|---|------------|------------|-------|
| | | - | | | | solated | | | | | . . | | |
| | | | | | | Length | | | | | | | |
| Α | М | Peds | Delay | Aver | | Delay | | Peds | Delay | Aver | Veh | - | |
| 1 | L | | | | 9 | 0.0 | 3.6 | | | | 9 | 0.0 | 2.9 |
| 1 | Т | 0 | 0.0 | | 2224 | 3.1 | 5.0 | 0 | 0.0 | | 2224 | 2.5 | 4.0 |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 137 | 1.4 | 37 5 | | | | 137 | 0.7 | 18 1 |
| 2 | Т | 0 | 0.0 | | 178 | | | | 0.0 | | 178 | | |
| 2 | R | Ū | 0.0 | | 170 | 1.5 | 00.1 | U | 0.0 | | 170 | 0.5 | 1014 |
| | | | | | 100 | 0 0 | E 1 | | | | 100 | 0 1 | 4 4 |
| 3 | L | | ~ ~ | | 120 | | | • | | | 120 | | |
| 3 | Т | 0 | 0.0 | | 2244 | 3.2 | 5.1 | 0 | 0.0 | | 2244 | 2.6 | 4.1 |
| 3 | R | | | | | | | | | | | | |
| 4 | L | | | | 16 | | | | | | 16 | | 16.9 |
| 4 | Т | 0 | 0.0 | | 145 | 1.5 | 37.4 | 0 | 0.0 | | 145 | 0.7 | 18.1 |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 5073 | 11 | 8.1 | | | | 5073 | 0 | 0.0 |
| | | | | | | | | | | | | | |
| TCS | = | 11 P | | | | cle Dela fter Co | | | | | | | RCHF |
| | | | | | | | | | | | | | |
| | | Peds | ретау | Aver | | | | | | LOS | • | • | |
| 1 | L | | | | | 0.0 | 0.1 | 0 | | А | 0 | 6 | |
| 1 | Т | 0 | 0.0 | | 2224 | 0.1 | 0.1 | 30 | 0.0 | A | 1 | 6 | |
| 1 | R | | | | | | | | | | | | |
| 2 | L | | | | 137 | 1.4 | 37.5 | 112 | 0.8 | С | 3 | 24 | |
| 2 | Т | 0 | 0.0 | | 178 | 1.9 | 38.1 | 147 | 0.8 | С | 4 | 30 | |
| 2 | R | | | | | | | | | | | | |
| 3 | L | | | | 120 | 0.0 | 1.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | Т | 0 | 0.0 | | 2244 | | 1 0 | 0 | | A | | 6 | |
| 3 | R | Ū | 0.0 | | 6677 | 0.0 | 1.0 | U | 0.0 | ~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~ | Ū | 0 | |
| 4 | L | | | | 16 | 0 0 | 24 0 | 10 | 0 0 | 0 | 0 | e | |
| | | • | ~ ~ | | 16 | | | 12 | | C | | | |
| | Т | 0 | 0.0 | | 145 | 1.5 | 37.4 | 118 | 0.8 | С | 3 | 24 | |
| 4 | R | | | | | | | | | | | | |
| INT | | | | | 5073 | 6 | 4.0 | 419 | 0.1 | А | | | |
| | | | | | | | | | | | | | |
| TCS | = | 11 I | | | | | | | | | | | |
| | | C | o-ordi | inated | Cycle | Length | | | - Isola | ted Cy | cle Le | ength · | |
| А | М | DS | GT | Delay | Stops | Queue I | Metre | DS | GT | Delay | Stops | Queue | Metre |
| 1 | L | 0.24 | 81 | Ó | 2 | 0 | 6 | 0.24 | 81 | Ó | 2 | 0 | 6 |
| 1 | Т | 0.75 | 81 | 6 | 1576 | 21 | 48 | 0.75 | 81 | 6 | 1576 | 21 | 48 |
| 1 | R | 0.75 | 01 | 0 | 1370 | 21 | 40 | 0.75 | 01 | 0 | 1370 | <u>د</u> ا | +0 |
| | | 0 70 | 10 | ~ | 400 | - | ~~ | 0 70 | 10 | ~ | 100 | - | 00 |
| 2 | L | 0.76 | 16 | 3 | 192 | 5 | 36 | 0.76 | 16 | 3 | 192 | 5 | 36 |
| 2 | Т | 0.76 | 16 | 3 | 208 | 6 | 36 | 0.76 | 16 | 3 | 208 | 6 | 36 |
| 2 | R | | | | | | | | | | | | |
| 3 | L | 0.76 | 81 | 0 | 69 | 1 | 48 | 0.76 | 81 | 0 | 69 | 1 | 48 |
| 3 | Т | 0.76 | 81 | 6 | 1583 | 21 | 48 | 0.76 | 81 | 6 | 1583 | 21 | 48 |
| 3 | R | | | | | | | | | | | | |
| - | 1 | 0.07 | 16 | 0 | 15 | 0 | 6 | 0 07 | 16 | 0 | 15 | 0 | 6 |

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November 2012

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| TCS | = | 11 | Pedestr | ian - Vehio Is | cle Dela solated | - | | File = | CHURCH | F | | |
|-----|---|------|---------|-------------------|---------------------|------|------|---------|--------|--------|---------|------|
| | | | Co-ordi | nated Cycle | | | | - Isola | ted Cy | cle Le | ength - | |
| Α | М | Peds | Delay | Aver Vehs | Delay | Aver | Peds | Delay | Aver | Veh | Delay | Aver |
| 1 | L | | | 9 | 0.0 | 3.4 | | | | 9 | 0.0 | 3.4 |
| 1 | Т | 0 | 0.0 | 3203 | 5.9 | 6.6 | 0 | 0.0 | | 3203 | 5.9 | 6.6 |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 204 | 2.8 | 49.4 | | | | 204 | 2.8 | 49.4 |
| 2 | Т | 0 | 0.0 | 226 | 3.0 | 47.7 | 0 | 0.0 | | 226 | 3.0 | 47.7 |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 133 | 0.3 | 8.1 | | | | 133 | 0.3 | 8.1 |
| 3 | Т | 0 | 0.0 | 3174 | 5.9 | 6.7 | 0 | 0.0 | | 3174 | 5.9 | 6.7 |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 20 | 0.2 | 38.1 | | | | 20 | 0.2 | 38.1 |
| 4 | Т | 0 | 0.0 | 219 | 2.8 | 45.5 | 0 | 0.0 | | 219 | 2.8 | 45.5 |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7188 | 21 | 10.4 | | | | 7188 | 0 | 0.0 |
| | | | | | | | | | | | | |

| TCS | = | 11 | | ian - Vehio s & Stops a [.] | | 2 | • | | | | | |
|-----|---|------|-------|---|-----|------|------|-----|-----|----|----|--|
| А | М | | 5 | Aver Vehs | | | | | LOS | | | |
| 1 | | reus | Deray | 9 | 0.0 | | 1 | 0.2 | | 0 | 6 | |
| - | L | _ | | - | | 2.7 | | | A | - | | |
| 1 | Т | 0 | 0.0 | 3203 | 2.4 | 2.7 | 508 | 0.2 | A | 15 | 36 | |
| 1 | R | | | | | | | | | | | |
| 2 | L | | | 204 | 2.8 | 49.4 | 192 | 0.9 | D | 5 | 36 | |
| 2 | Т | 0 | 0.0 | 226 | 3.0 | 47.7 | 208 | 0.9 | D | 6 | 36 | |
| 2 | R | | | | | | | | | | | |
| 3 | L | | | 133 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | Т | 0 | 0.0 | 3174 | 0.0 | 0.0 | 0 | 0.0 | А | 0 | 6 | |
| 3 | R | | | | | | | | | | | |
| 4 | L | | | 20 | 0.2 | 38.1 | 15 | 0.8 | С | 0 | 6 | |
| 4 | Т | 0 | 0.0 | 219 | 2.8 | 45.5 | 196 | 0.9 | D | 6 | 36 | |
| 4 | R | | | | | | | | | | | |
| INT | | | | 7188 | 11 | 5.6 | 1120 | 0.2 | Α | | | |
| | | | | | | | | | | | | |